

Multidimensional measurements using multivariate techniques

The future of particle physics precision measurements?



Dag Gillberg, Carleton & Lund University

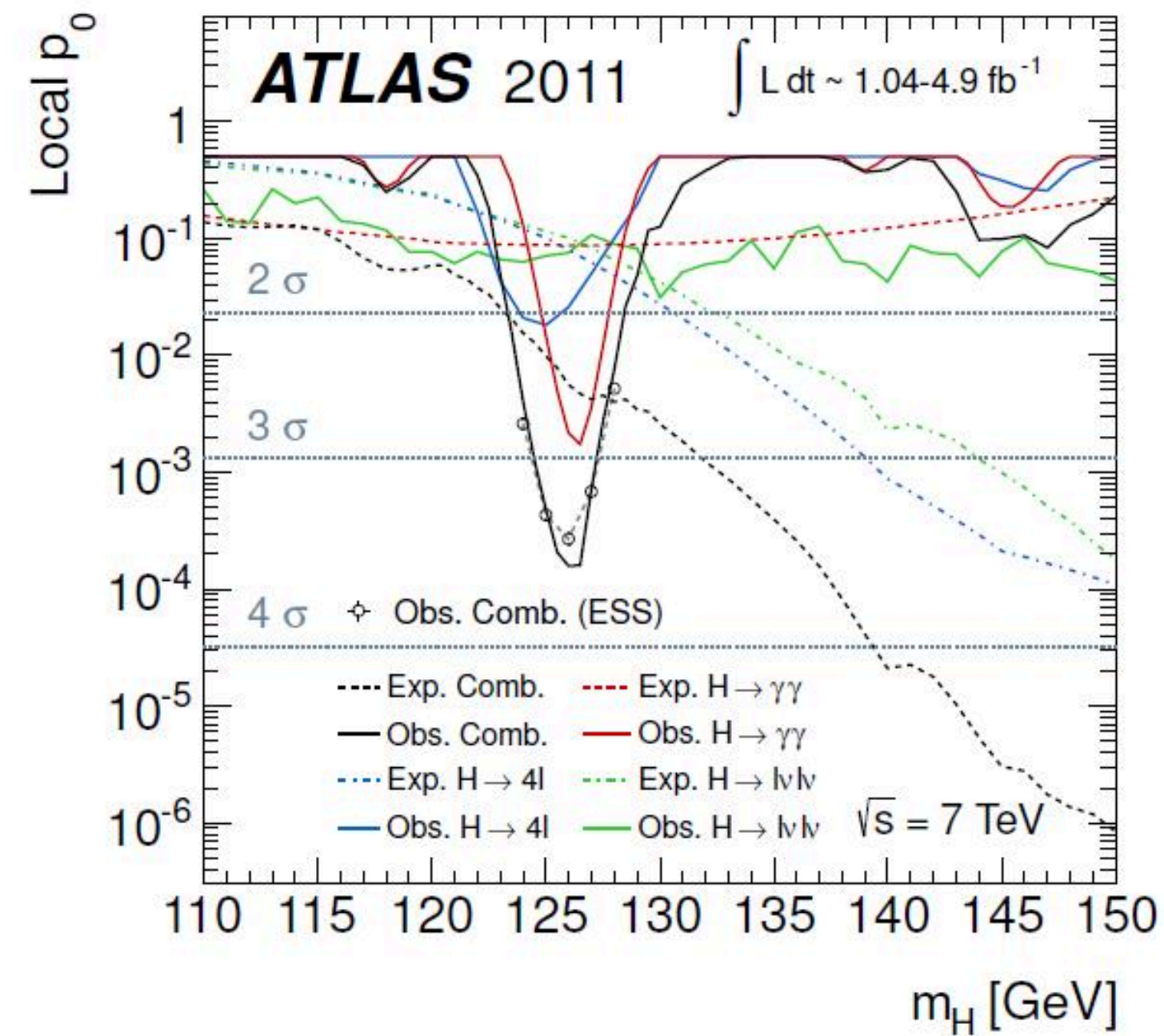


Outline

- Measurements in particle physics
 - Standard approach at the LHC
 - Public data, hypothesis testing
 - Limitations with current approach
- New possibilities following development in machine learning
 - Underlying mechanism
 - New opportunities
 - Challenges and open questions

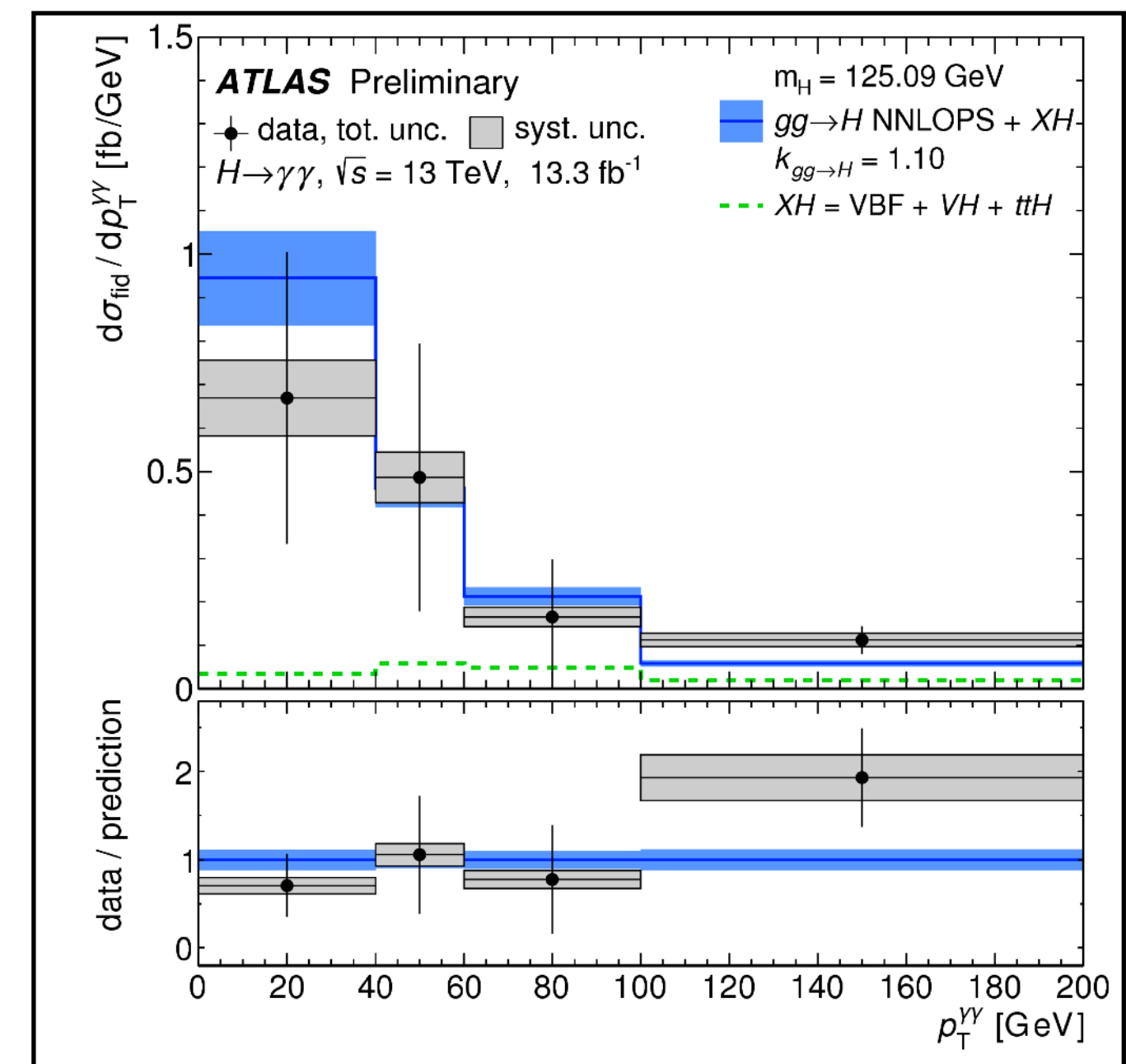
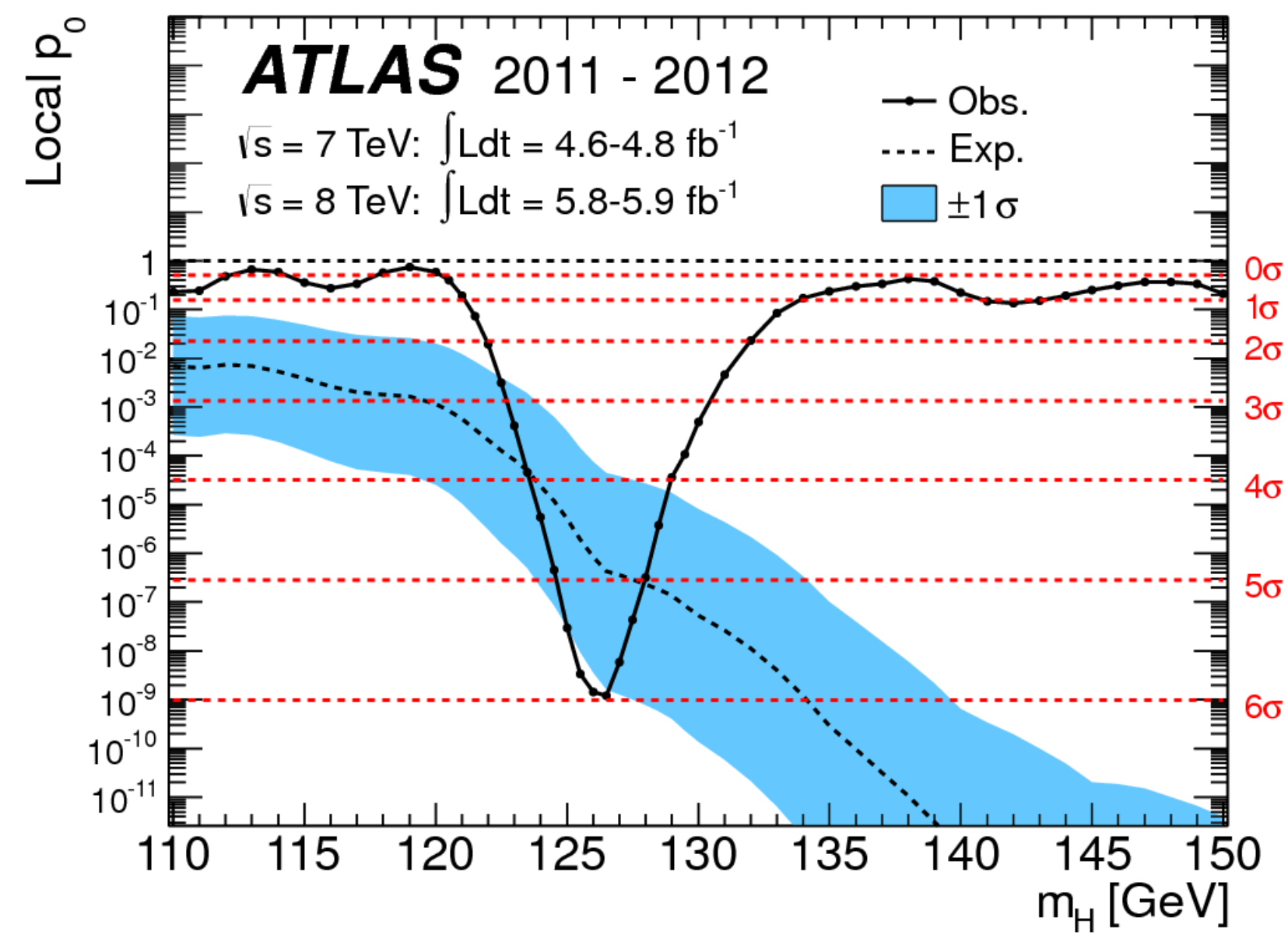
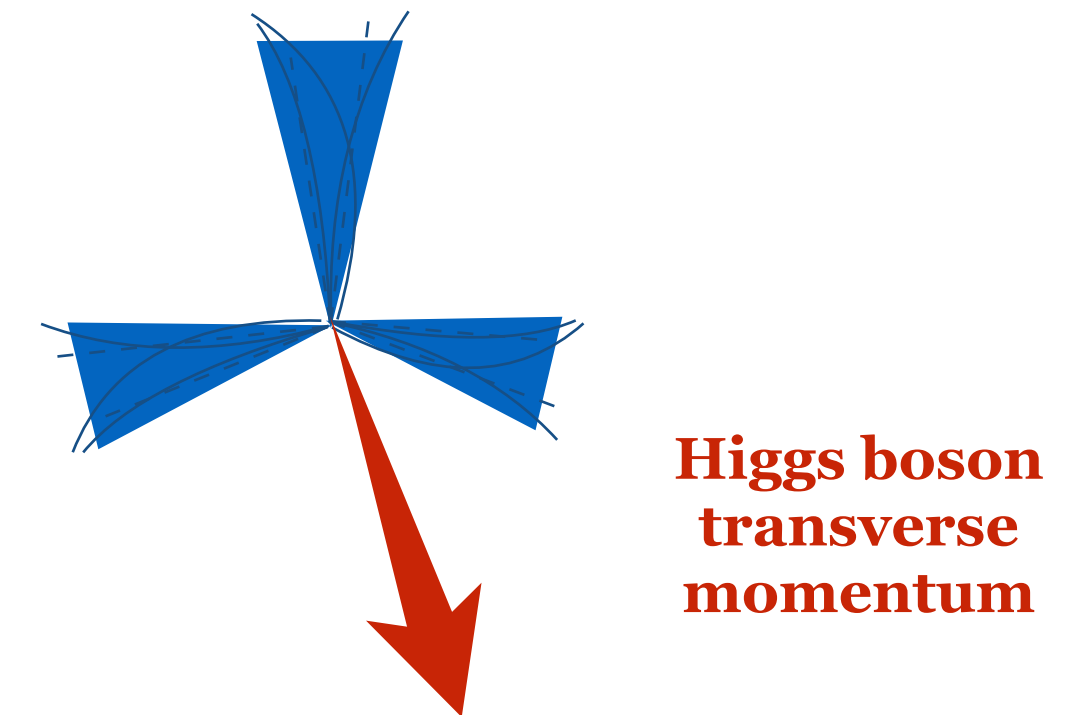
Particle physics measurements

- Two main classes of experimental analyses
 - Searches
 - Measurements



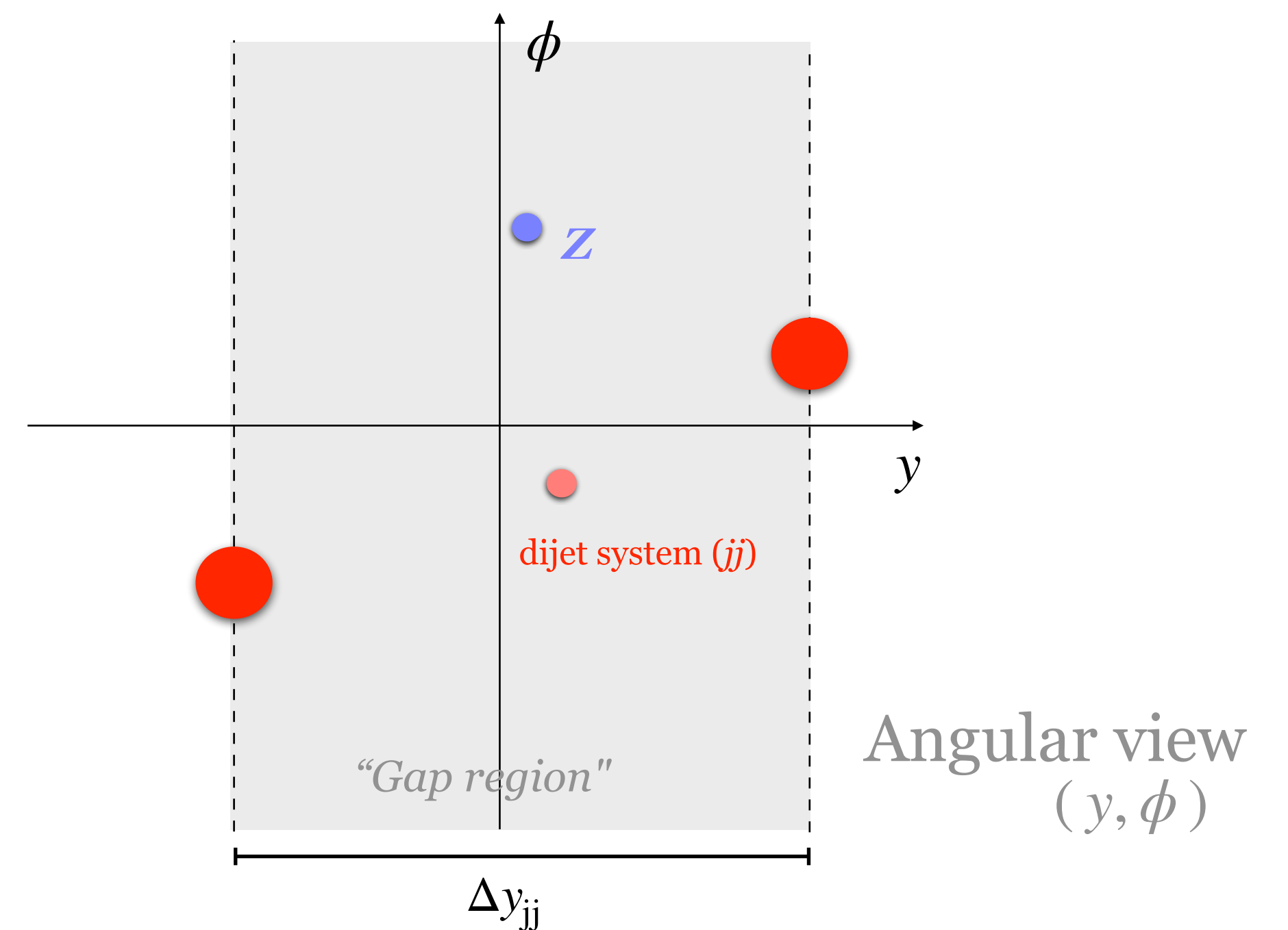
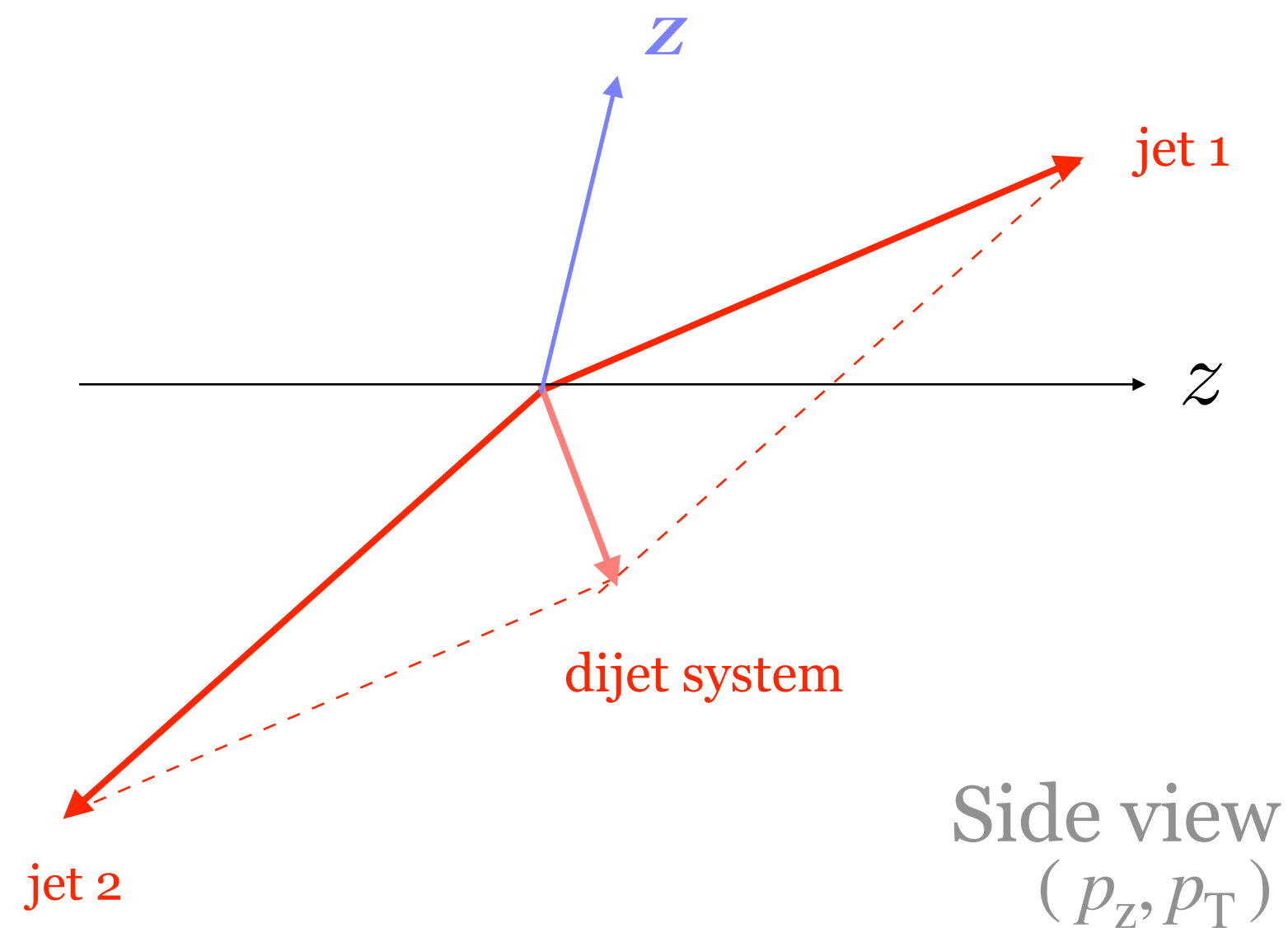
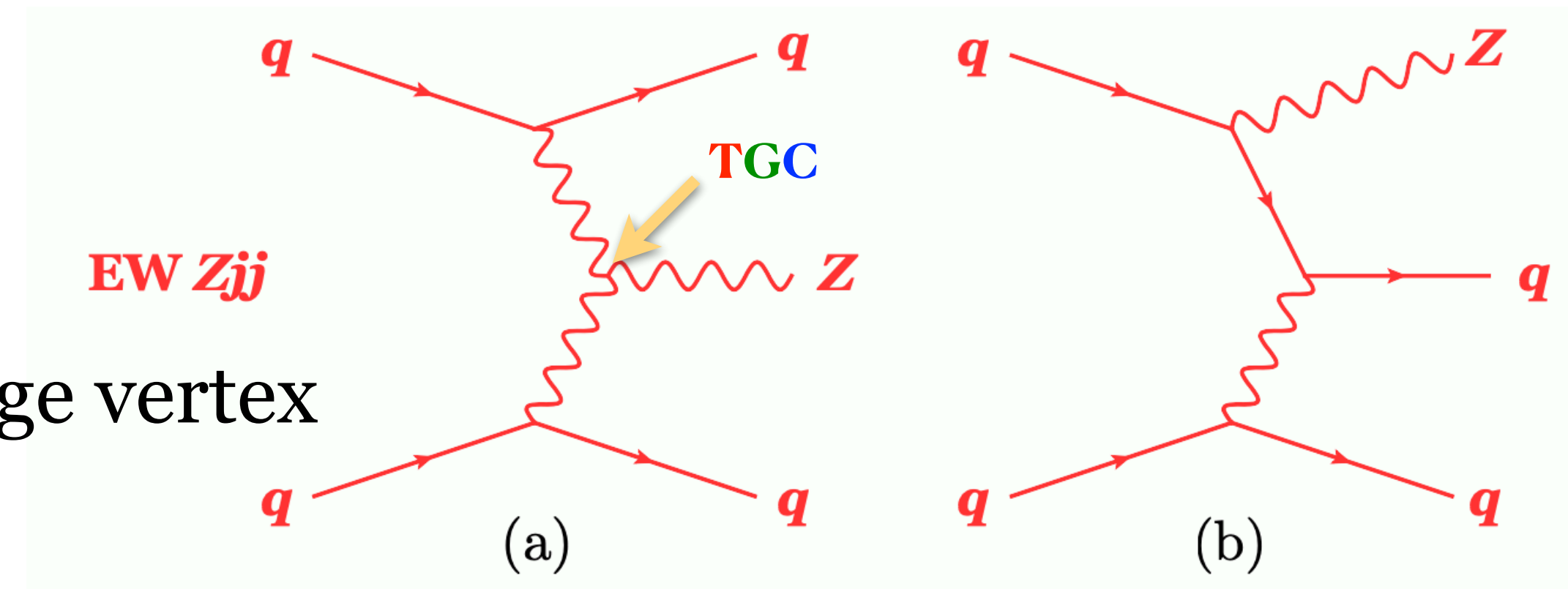
Particle physics measurements

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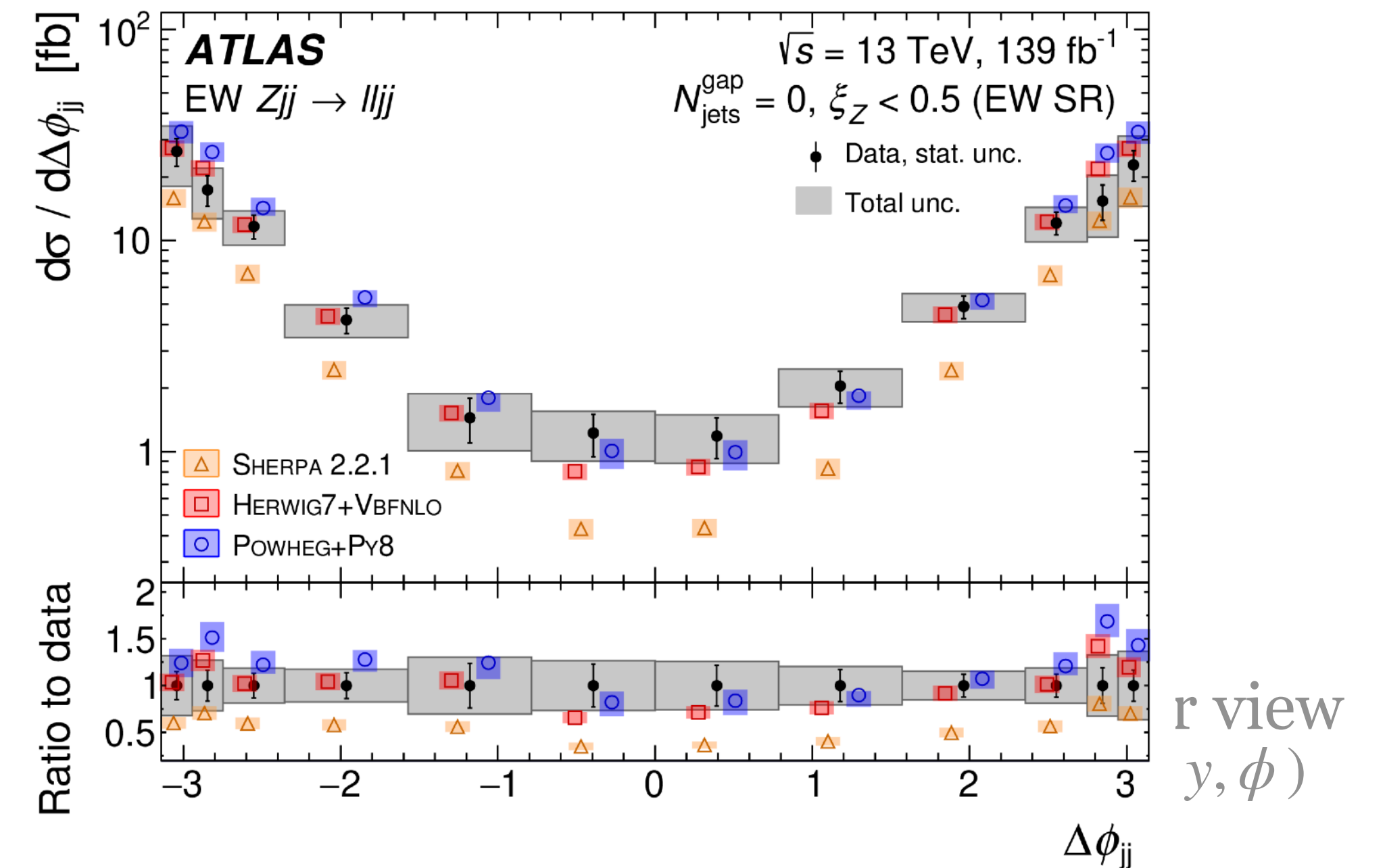
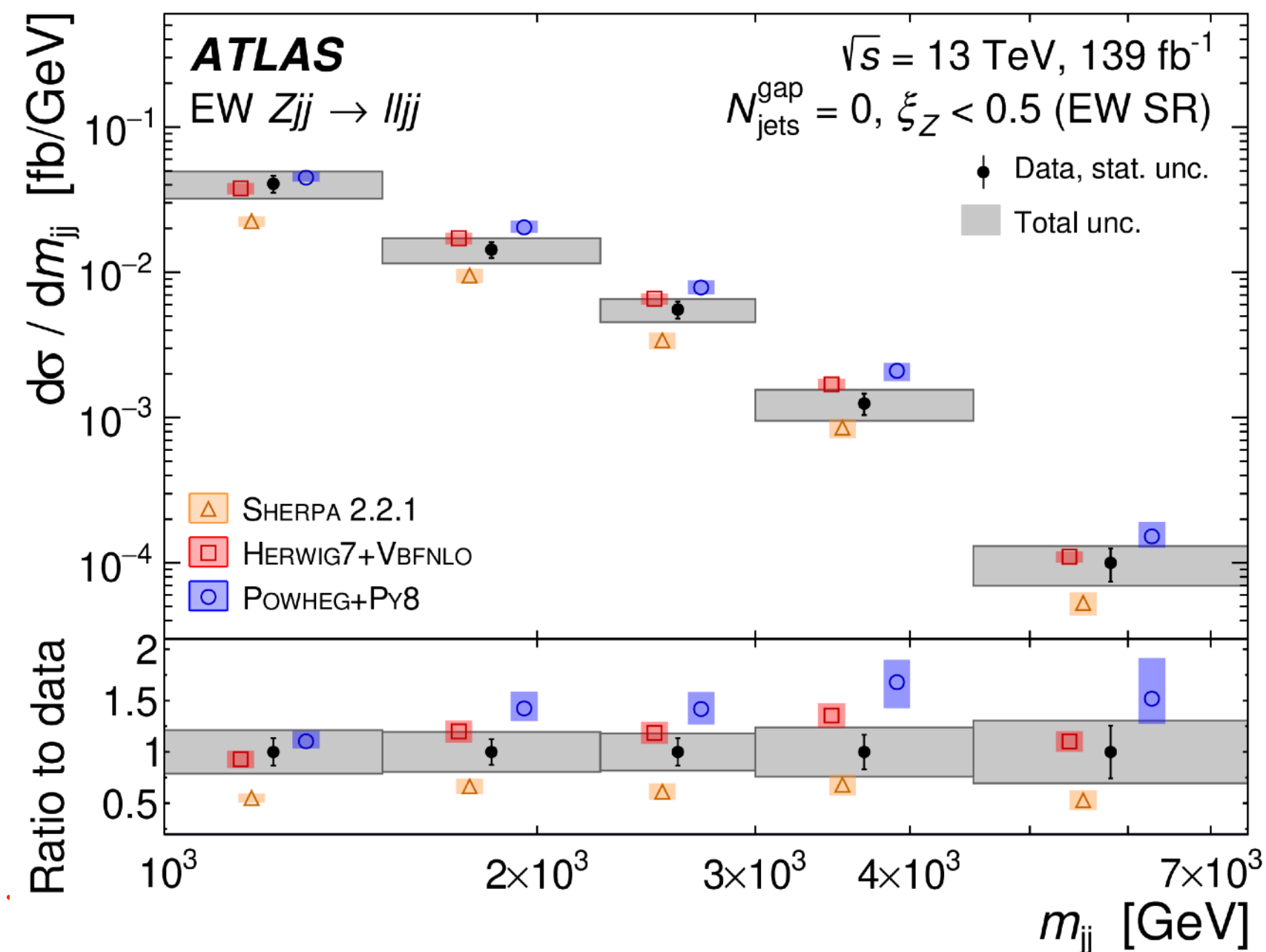
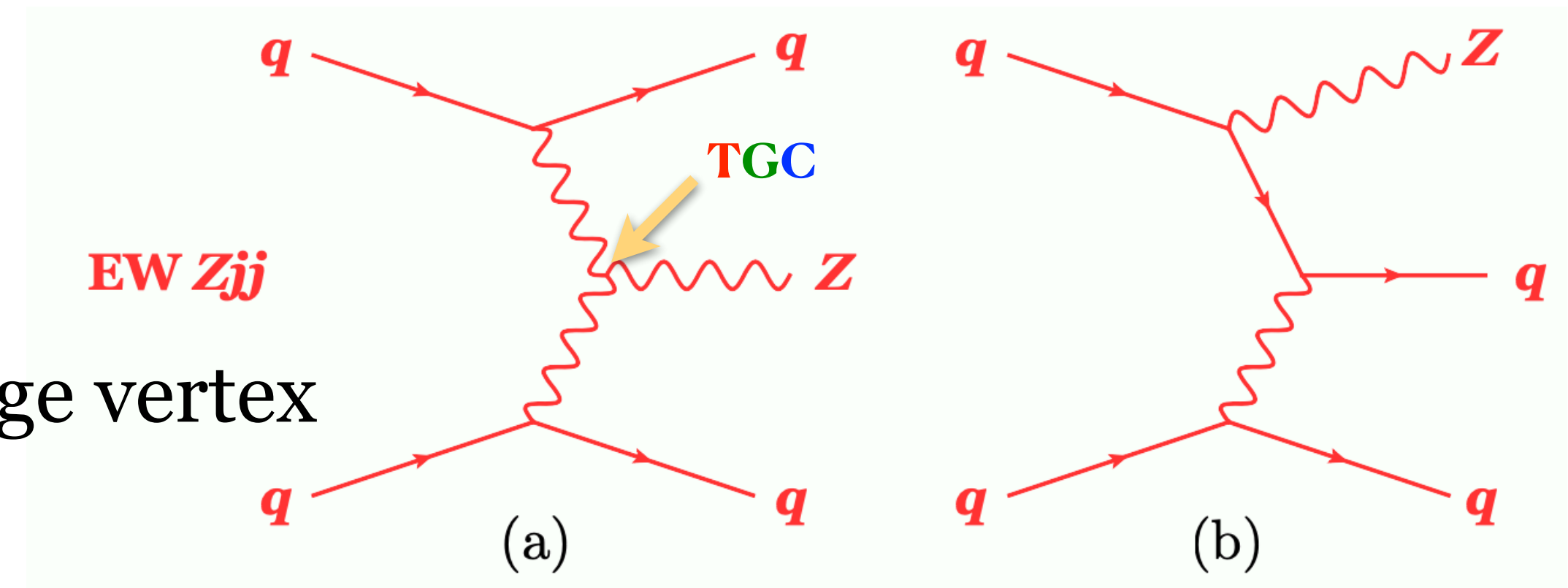
Example of a measurement

- Analysis close to heart
- Measurement of electroweak Zjj production
 - Probes gauge boson self-interaction via triple gauge vertex
 - Sensitive to CP asymmetry
- Final state: Z boson and two forward jets

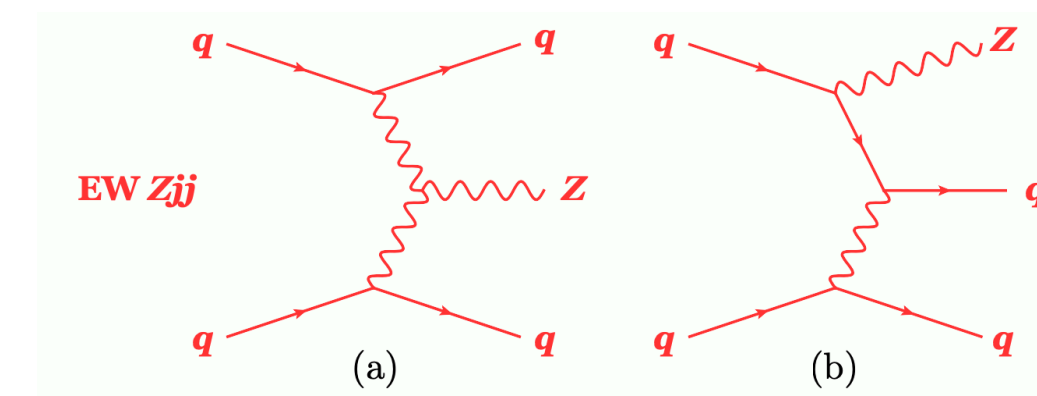


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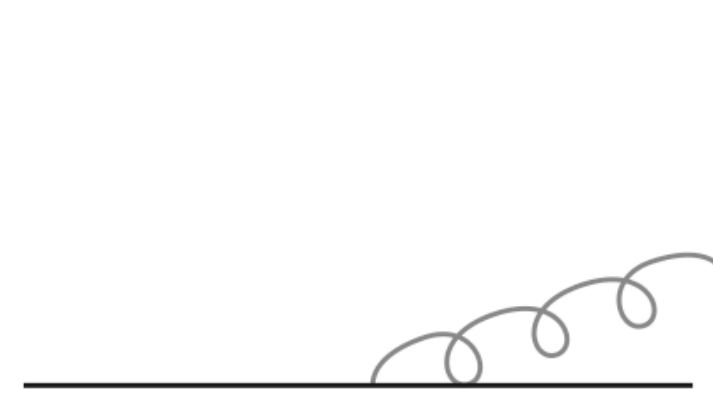
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Precision measurements

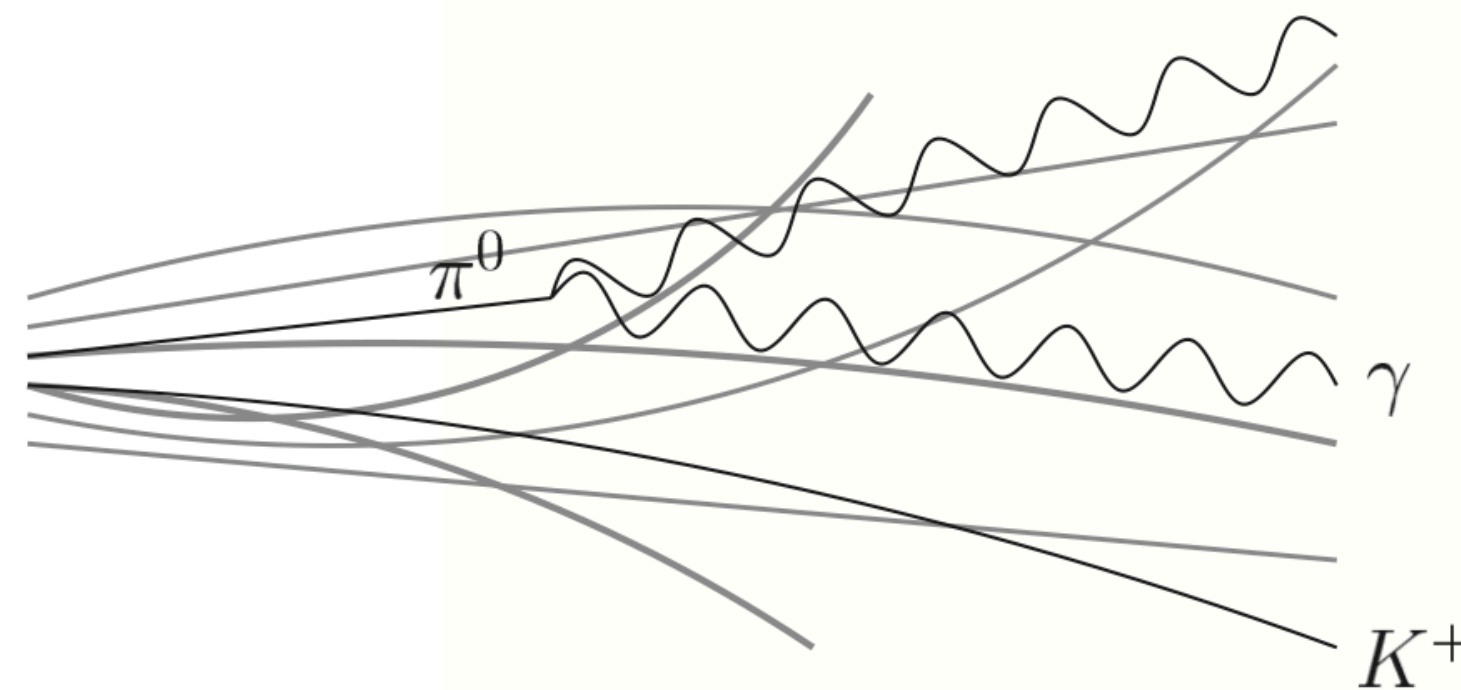


- For a measurement to be useful, it needs a **precise definition**
- We define measurement at the particle level
 - Real particles with life time $c \tau_0 > 10 \text{ mm}$ ($\pi^\pm, p, n, K, e^-, e^+ \dots$)



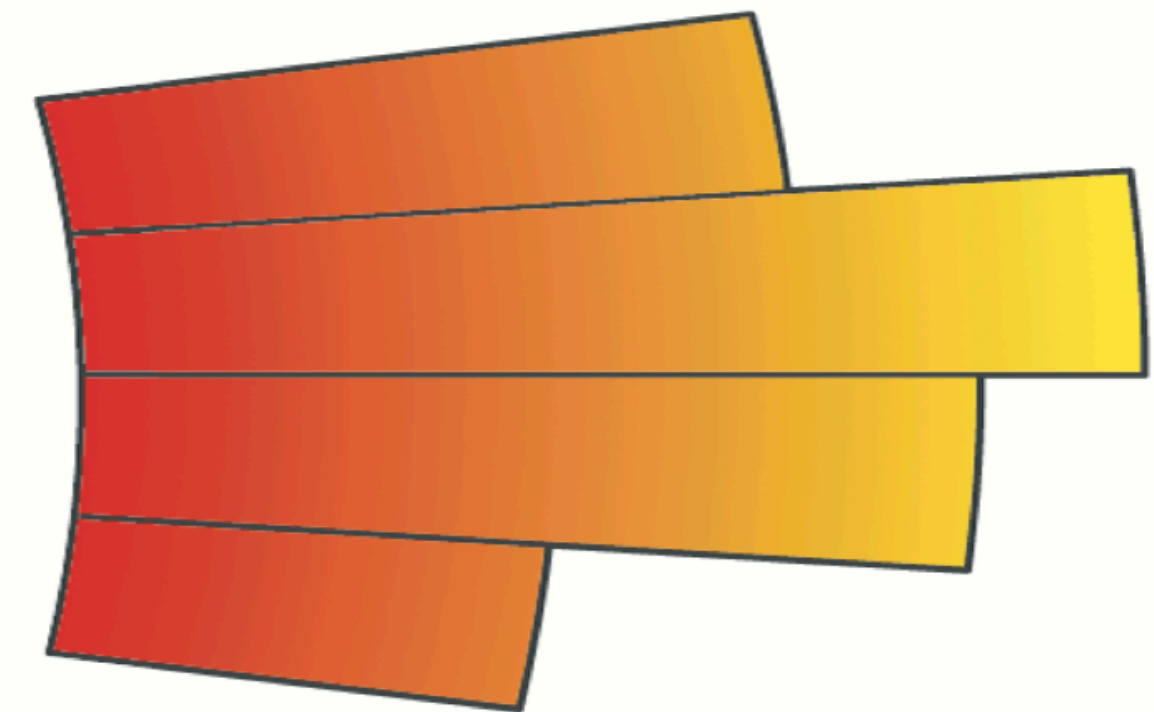
parton level jet

*Quarks/gluons don't exist
as free particles
Cannot be observed*



particle level jet

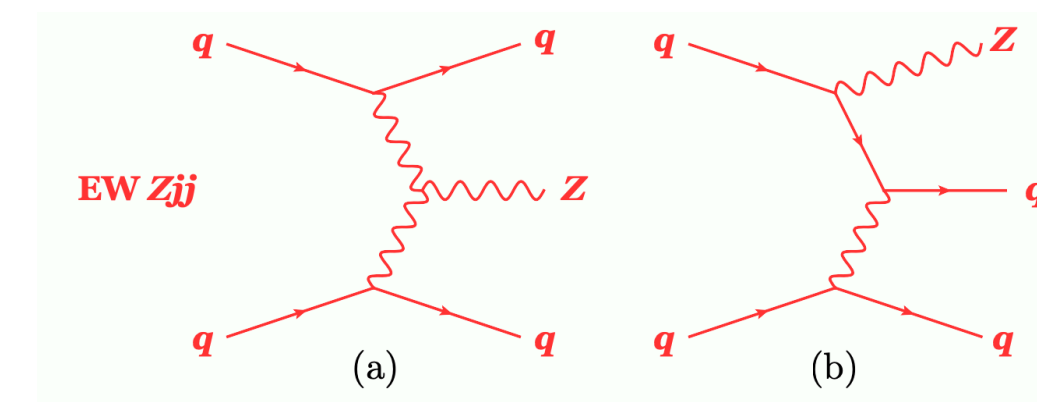
*Final state!
Observable in **nature**
"What a perfect
detector would see"*



calorimeter level jet

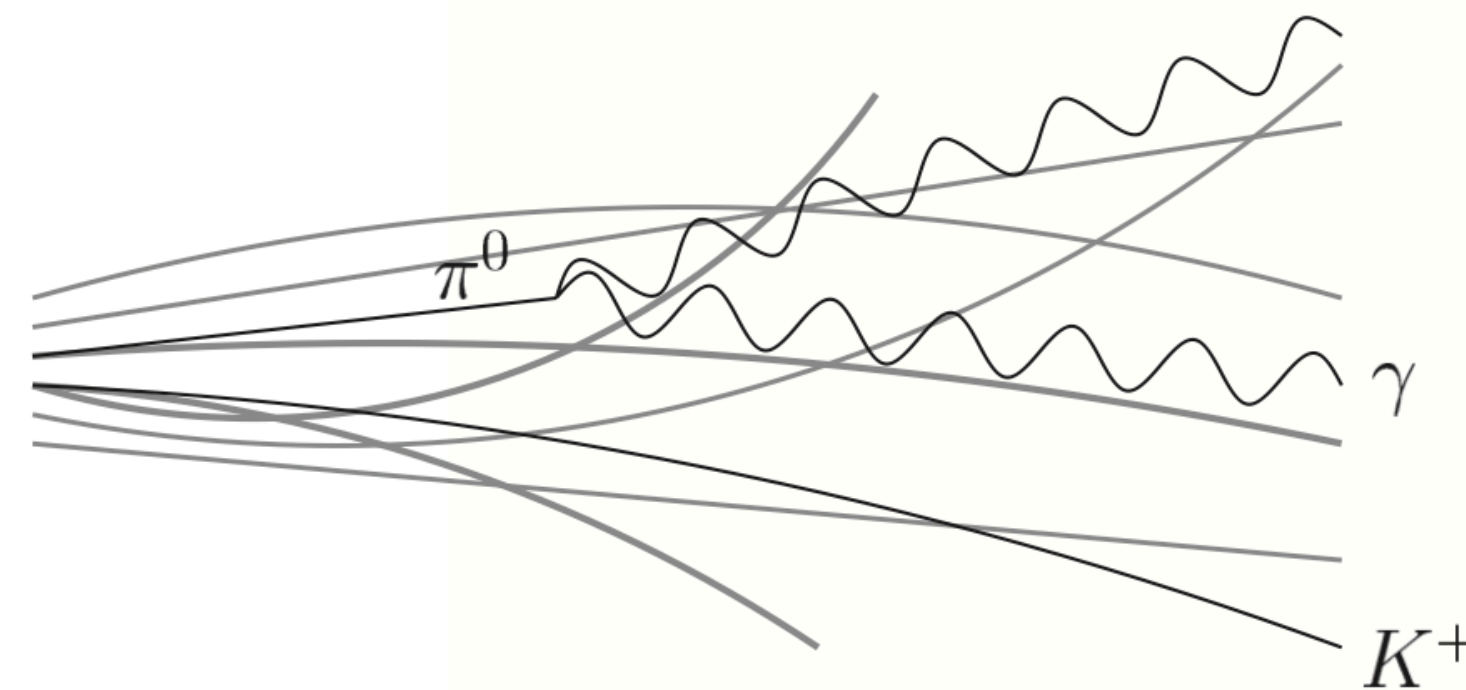
*Reconstructed level
What we measure
in the detector*

Precision measurements



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parton level jet

particle level jet

calorimeter level jet

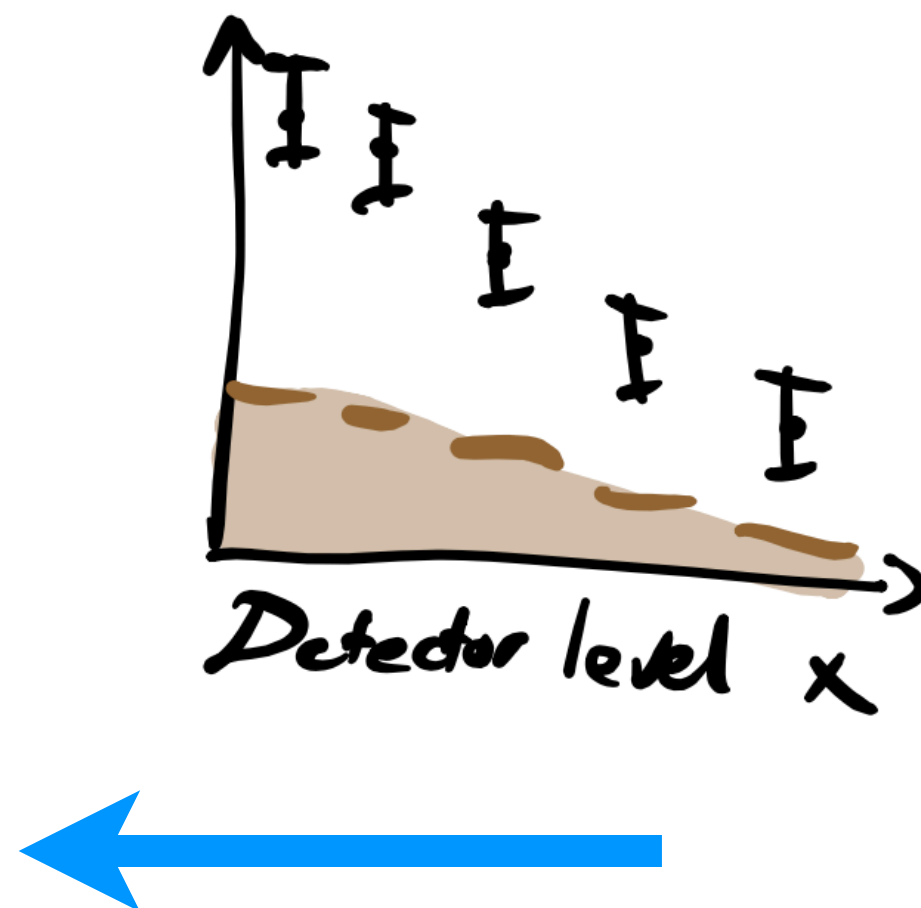
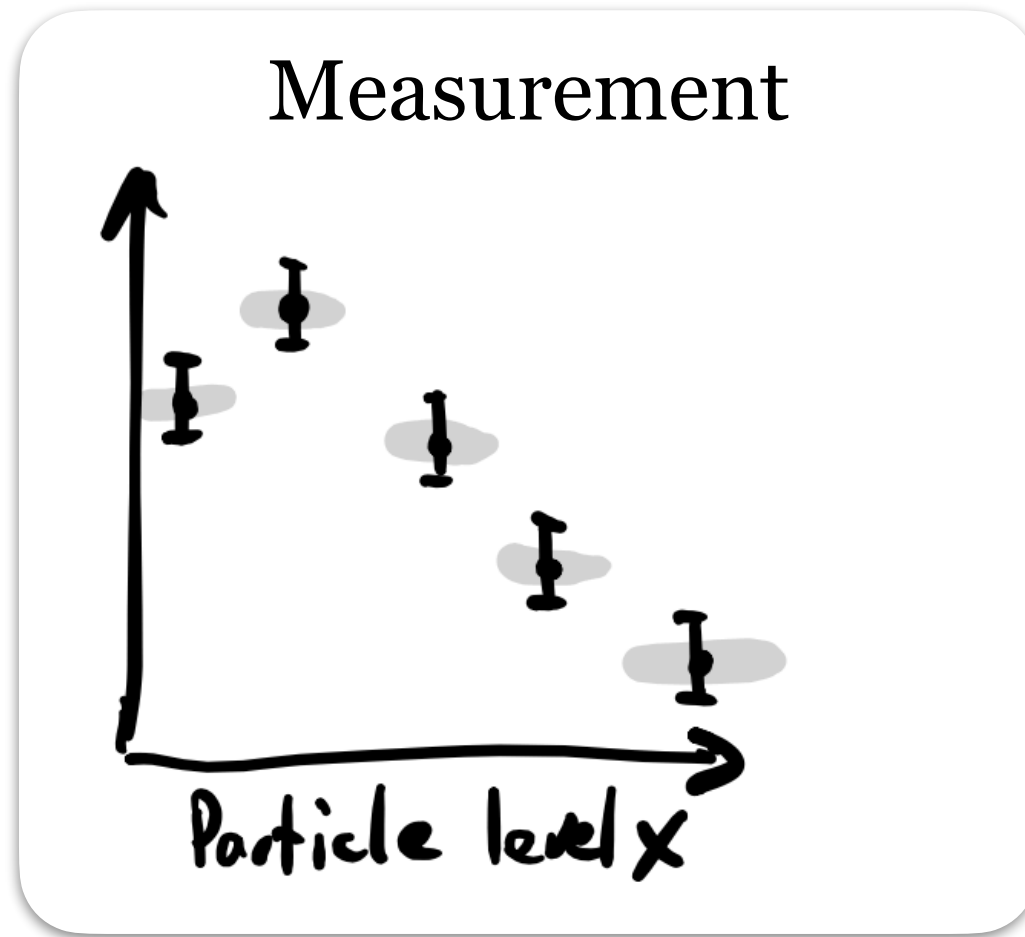
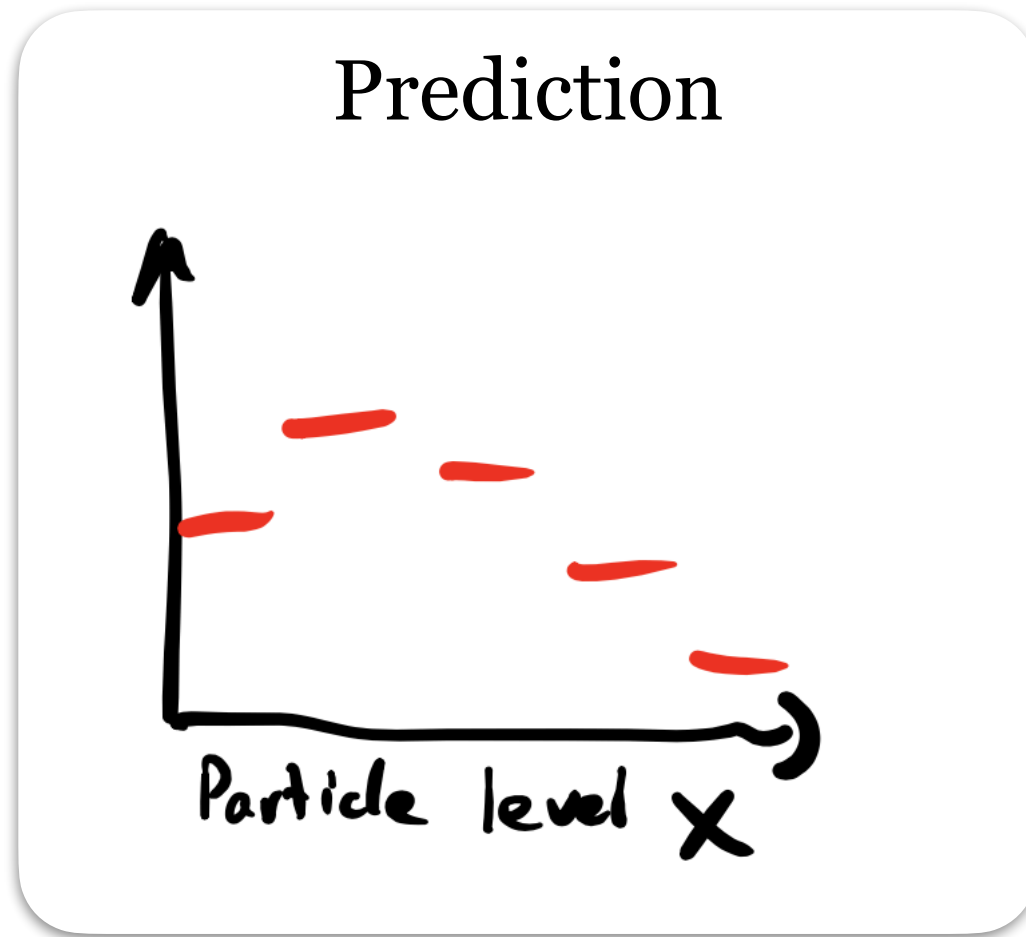
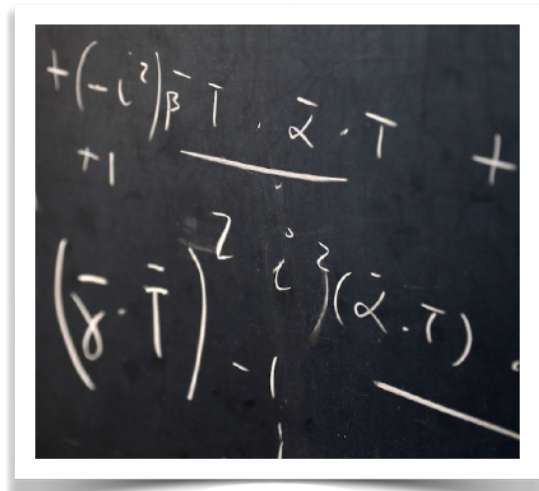
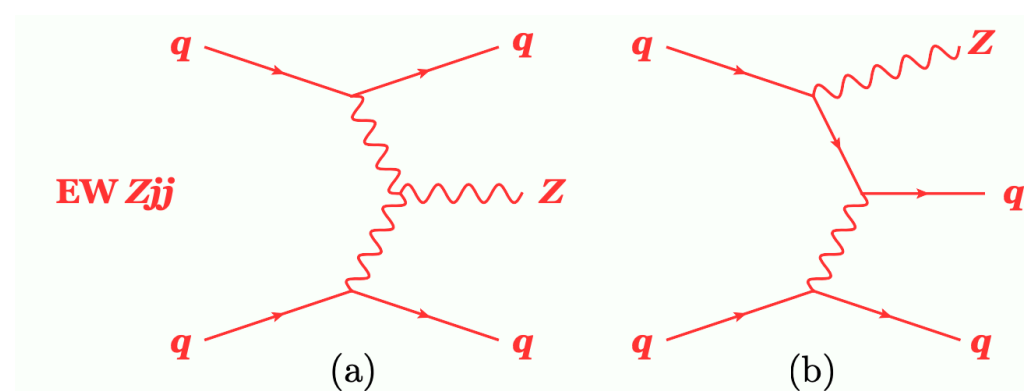
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Final state!
Observable in nature

"What a perfect
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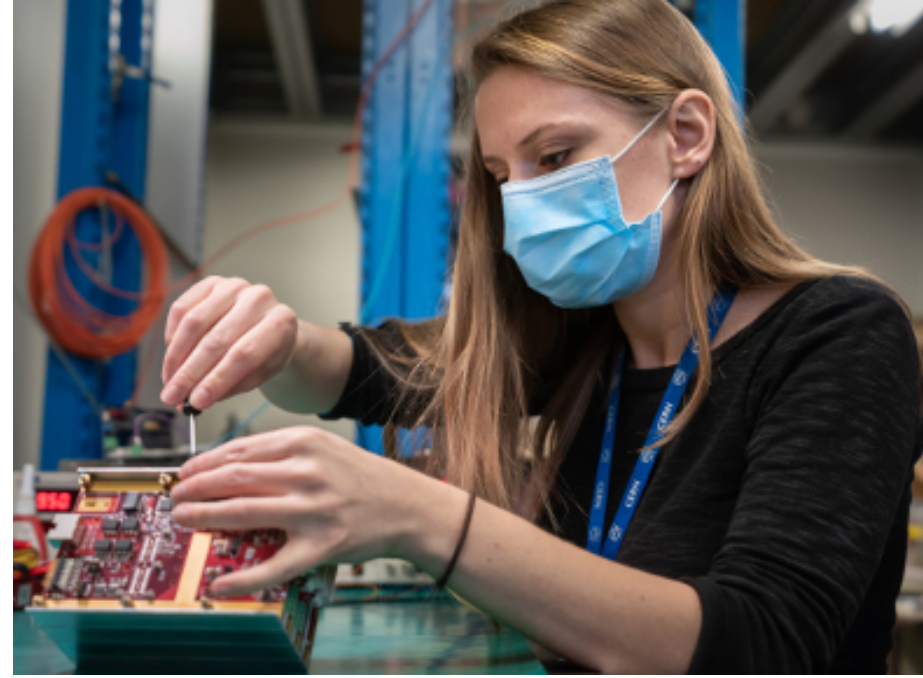
Science at work



Hypothesis test!

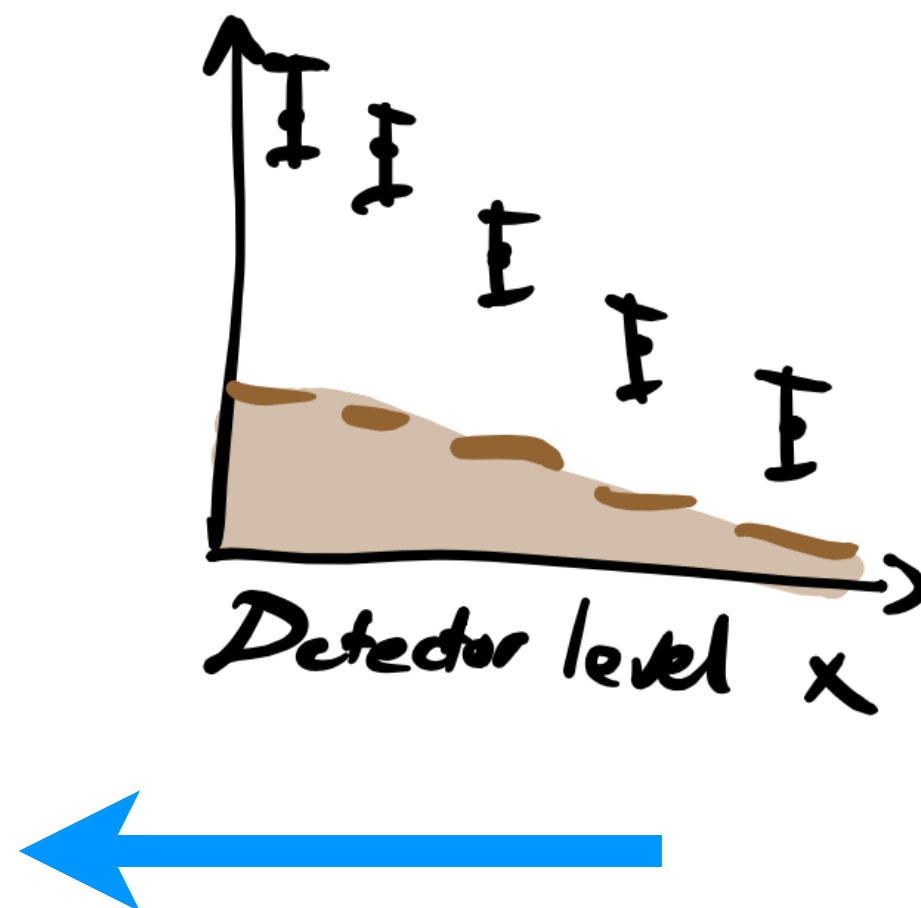
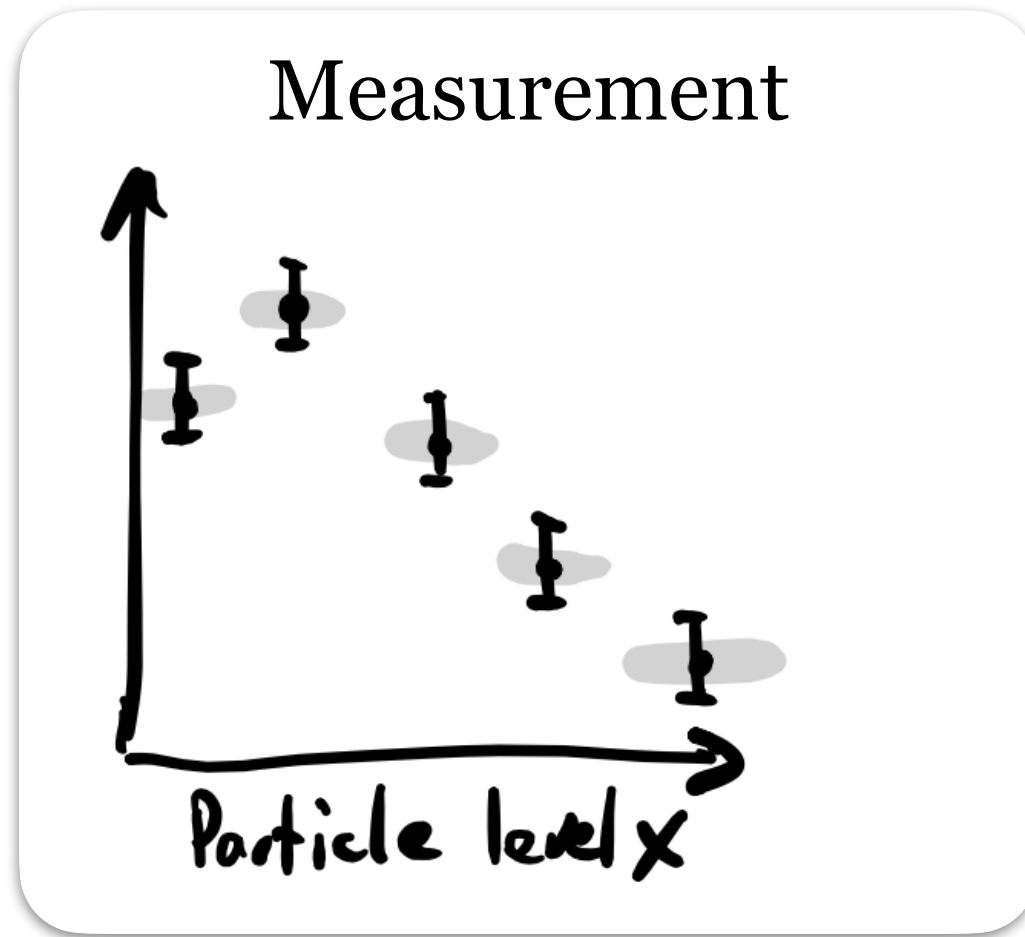
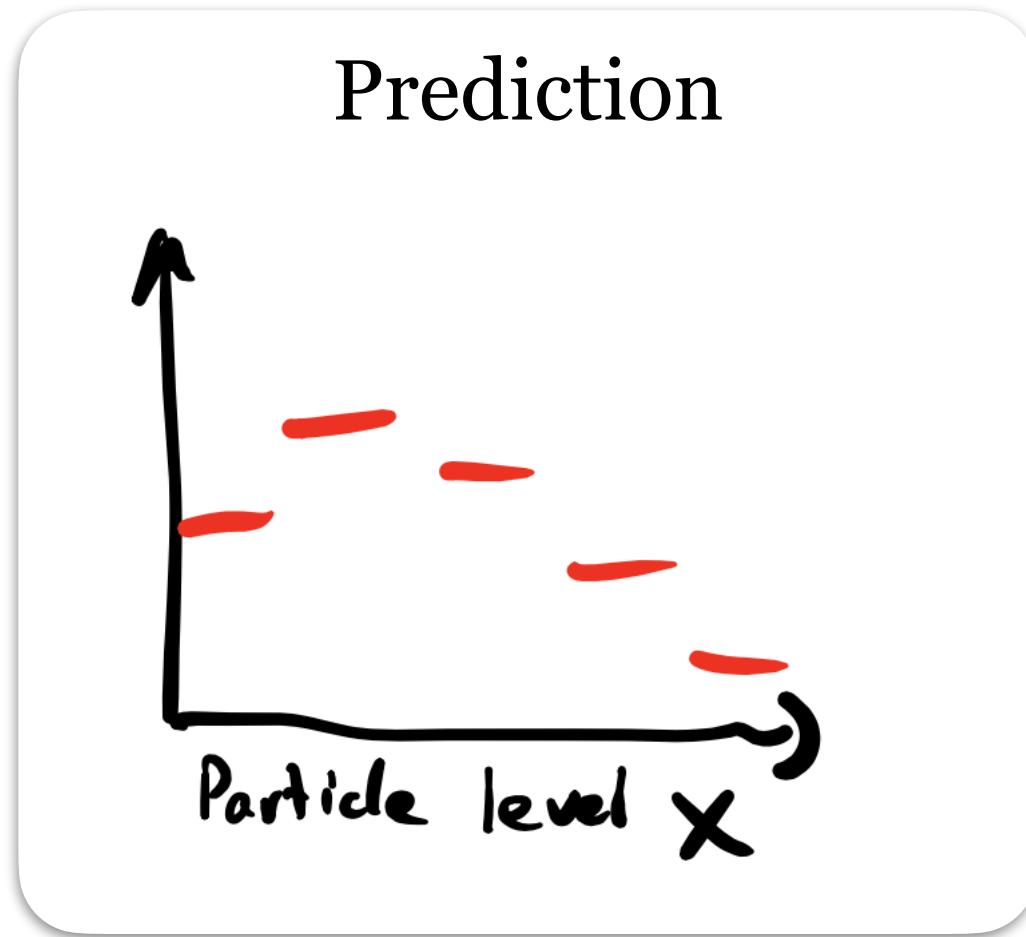
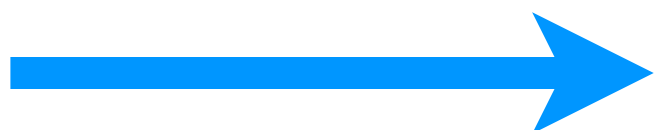
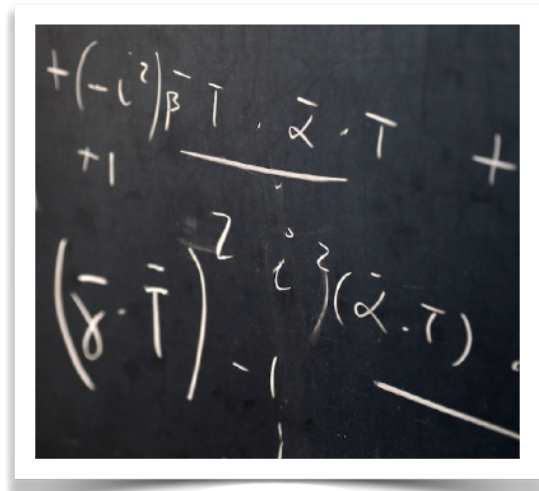
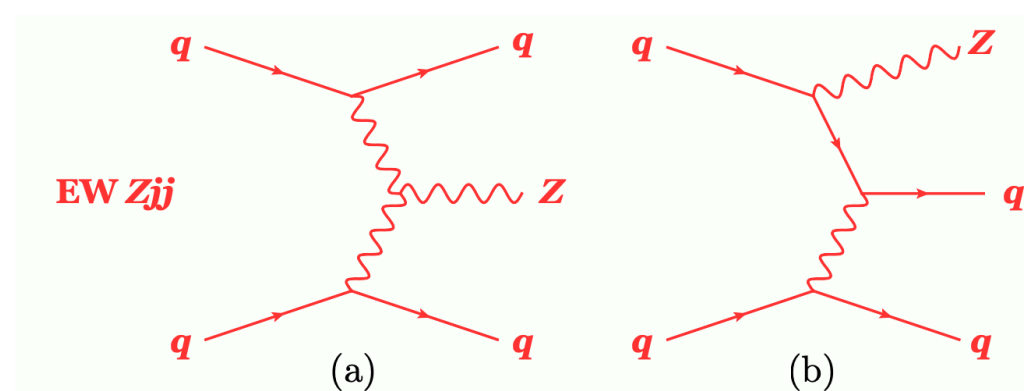


Theorists



Experimentalists

Science at work



Example workflow

1. UFO module → MadGraph5
2. Generate events with parton shower and hadronization (e.g. MG5+Py8)
3. Feed to Rivet

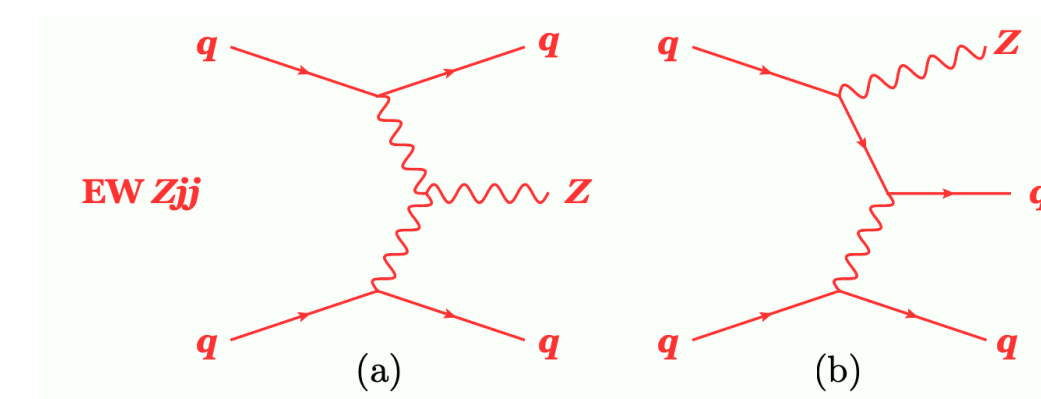
Theorists

Example workflow

0. (Build detector, operate, calibrate)
1. Event reconstruction+analysis
2. Correct for detector effects
3. Make data public

Experimentalists

Science at work

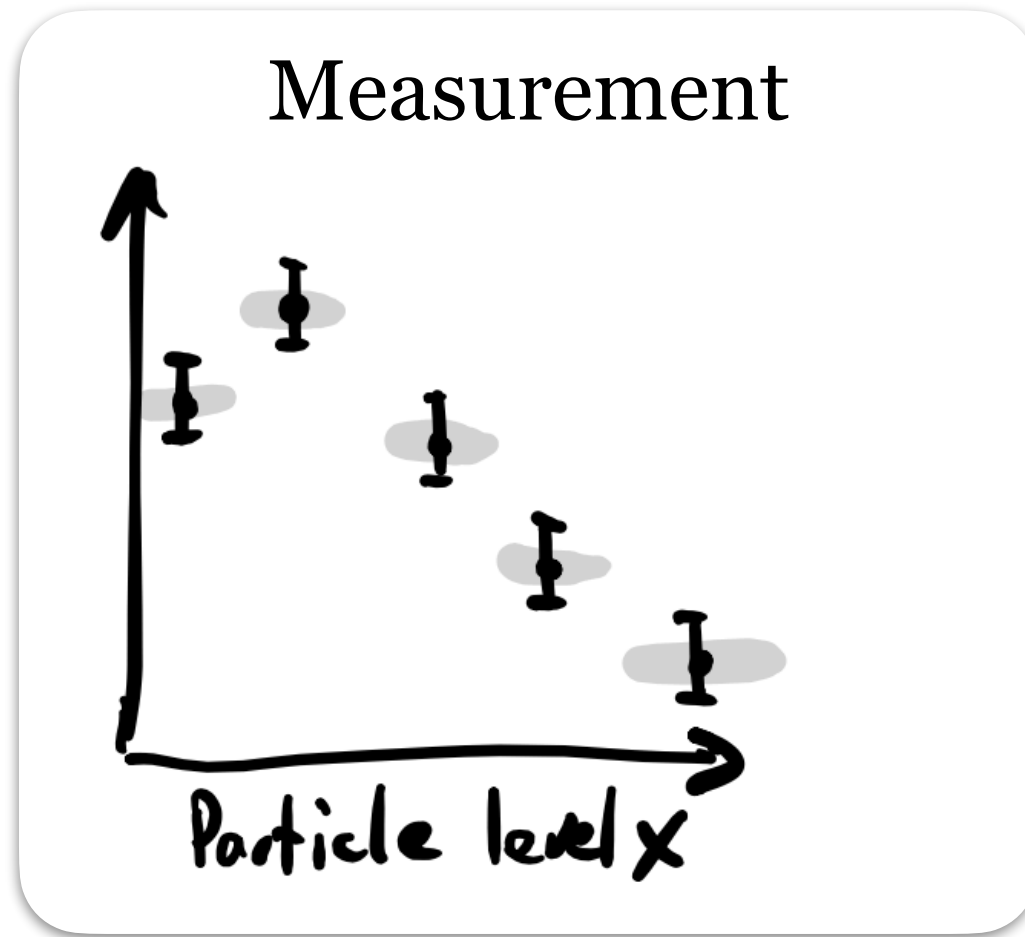
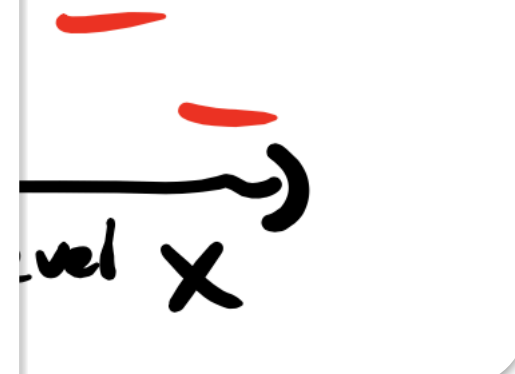


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```

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54 // Perform the per-event analysis
55 void analyze(const Event& event) {
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57 // Access fiducial electrons and muons
58 const Particle *l1 = nullptr, *l2 = nullptr;
59 Particles muons = apply<DressedLeptons>(event, "DressedMuons").particles();
60 Particles elecs = apply<DressedLeptons>(event, "DressedElectrons").particles();
61
62 // Dilepton selection 1: =2 leptons of the same kind
63 if (muons.size()+elecs.size() != 2) vetoEvent;
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72 // Electron-jet overlap removal (note: muons are not included in jet finding)
73 // make sure jets do not overlap with an electron within DR<0.2
74 Jets jets;
75 for (const Jet& j : apply<FastJets>(event, "Jets").jetsByPt(Cuts::pT > 25*GeV && Cuts::absrap < 4.4)) {
76   if (elecs.size() == 2 && (deltaR(j, *l1, RAPIDITY) < 0.2 || deltaR(j, *l2, RAPIDITY) < 0.2 )) {
77     continue;
78   }
79   jets += j;
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86 Variables vars(jets, l1, l2);
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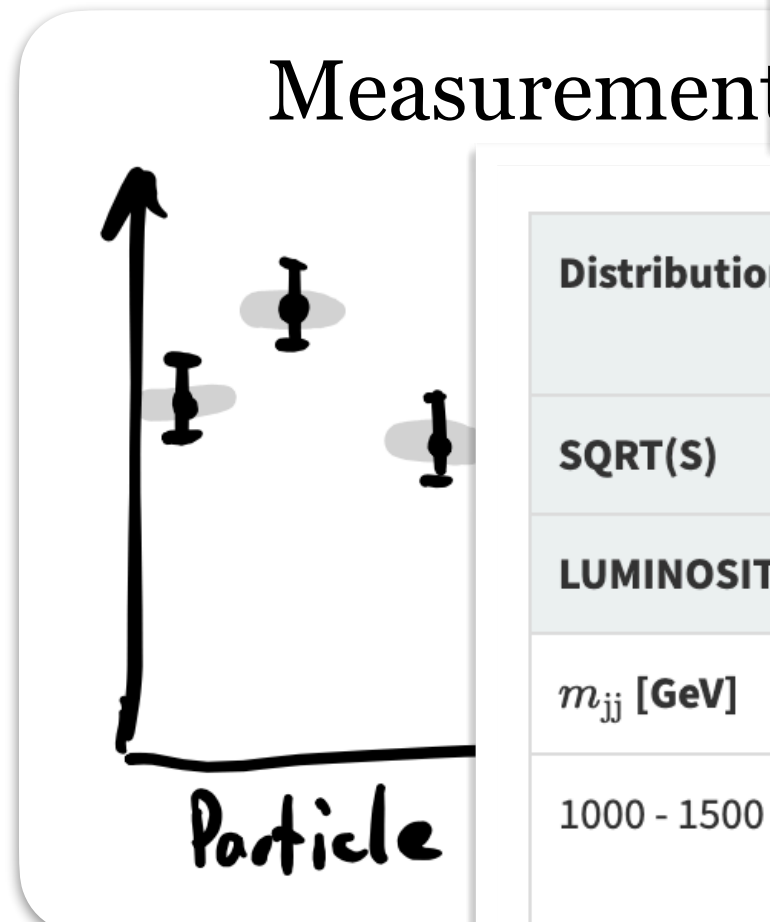
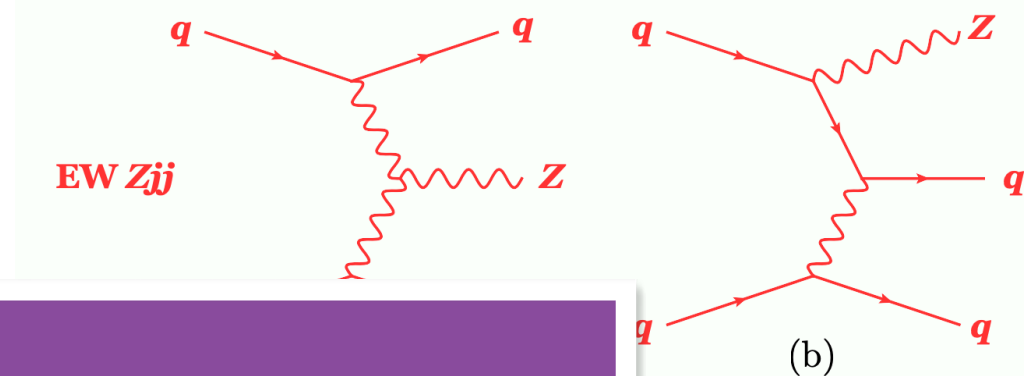
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Distribution	Data	Powheg + Py8	Herwig7 + VBFNLO
SQRT(S)	13000 GeV		
LUMINOSITY	139 fb ⁻¹		
$m_{jj} \text{ [GeV]}$	Differential cross-section [fb/GeV]		
1000 - 1500	0.040673 ±0.00536 stat ±0.00044 JES_EtaIntercalibration_Modelling ±0.000691 JES_EffectiveNP_Modelling1 + 32 more errors Show all	0.044867 +0.00404 -0.00278	0.03775 ±0.000295 JER_EffectiveNP_4 ±4.79e-05 JER_EffectiveNP_5 ±7.6e-05 JER_EffectiveNP_6 ±0.000115 JER_EffectiveNP_7 ±0.000276 JER_EffectiveNP_8 ±0.000641 JER_EffectiveNP_9 ±0.000128 JER_EffectiveNP_10 ±0.000234 JER_EffectiveNP_11 ±0.000125 JER_EffectiveNP_12restTerm ±0.000778 JER_DataVsMC ±4.18e-05 MUON_SAGITTA_RHO ±0.00027 ELECTRON_ID ±0.000233 MUON_EFF ±1.76e-05 pileup_model ±0.00463 strongZjj_gen_choice ±0.000575 strongZjj_pdf ±0.00277 strongZjj_qcd ±0.00137 ewStrong_interference ±2.33e-06 ewZjj_pdf ±0.00105 ewZjj_qcd ±0.000924 unf_MCgen ±0.000187 unf_DataRew ±0.000701 Lumi
1500 - 2250	0.014316 ±0.00179 stat ±0.00021 JES_EtaIntercalibration_Modelling ±0.000232 JES_EffectiveNP_Modelling1 + 32 more errors Show all	0.020374 +0.00234 -0.00173	

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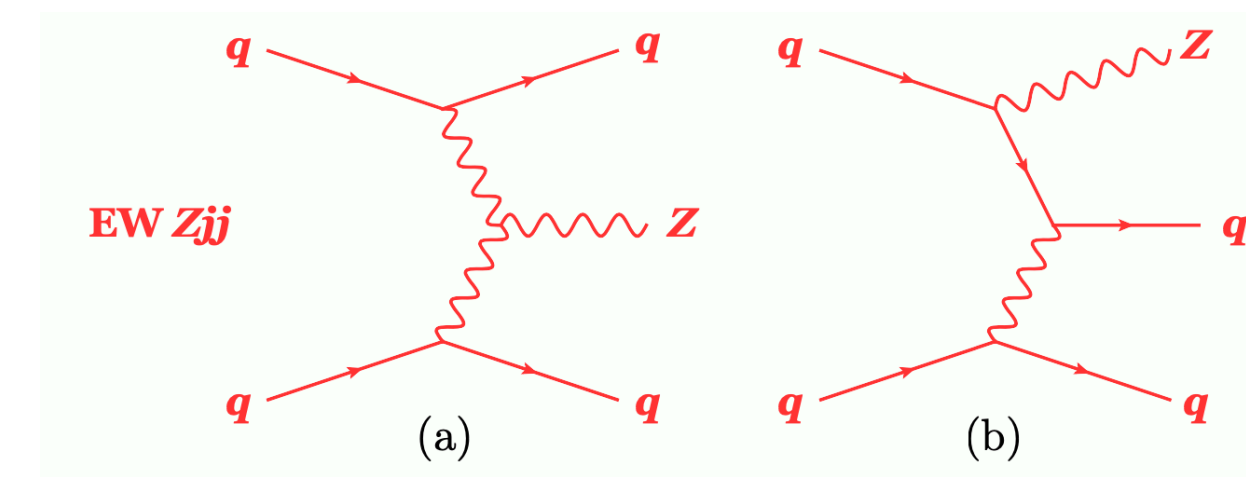
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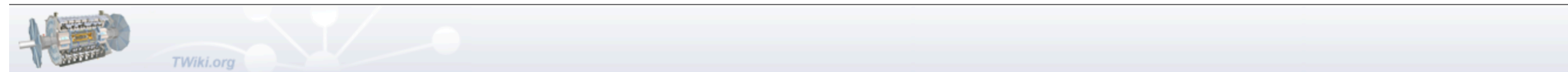
Theorists

Experimenters

Useful tools at hand



- HepData stores the measurements with associated uncertainties
 - hepdata.net
- Rivet is synchronized with the HepData entry
 - Ensures predictions defined in accordance with the data
- Fast and effective



Differential cross-section measurements for the electroweak production of dijets in association with a Z boson in proton-proton collisions at ATLAS

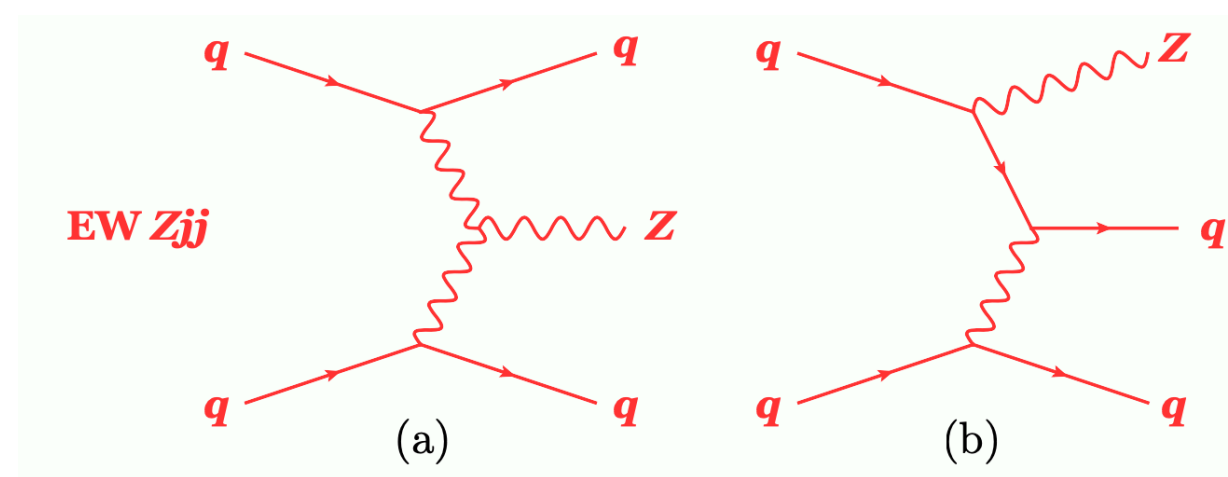
[Eur. Phys. J. C 81 \(2021\) 163](#)

27 June 2020

Contact: [ATLAS Standard Model conveners](#)

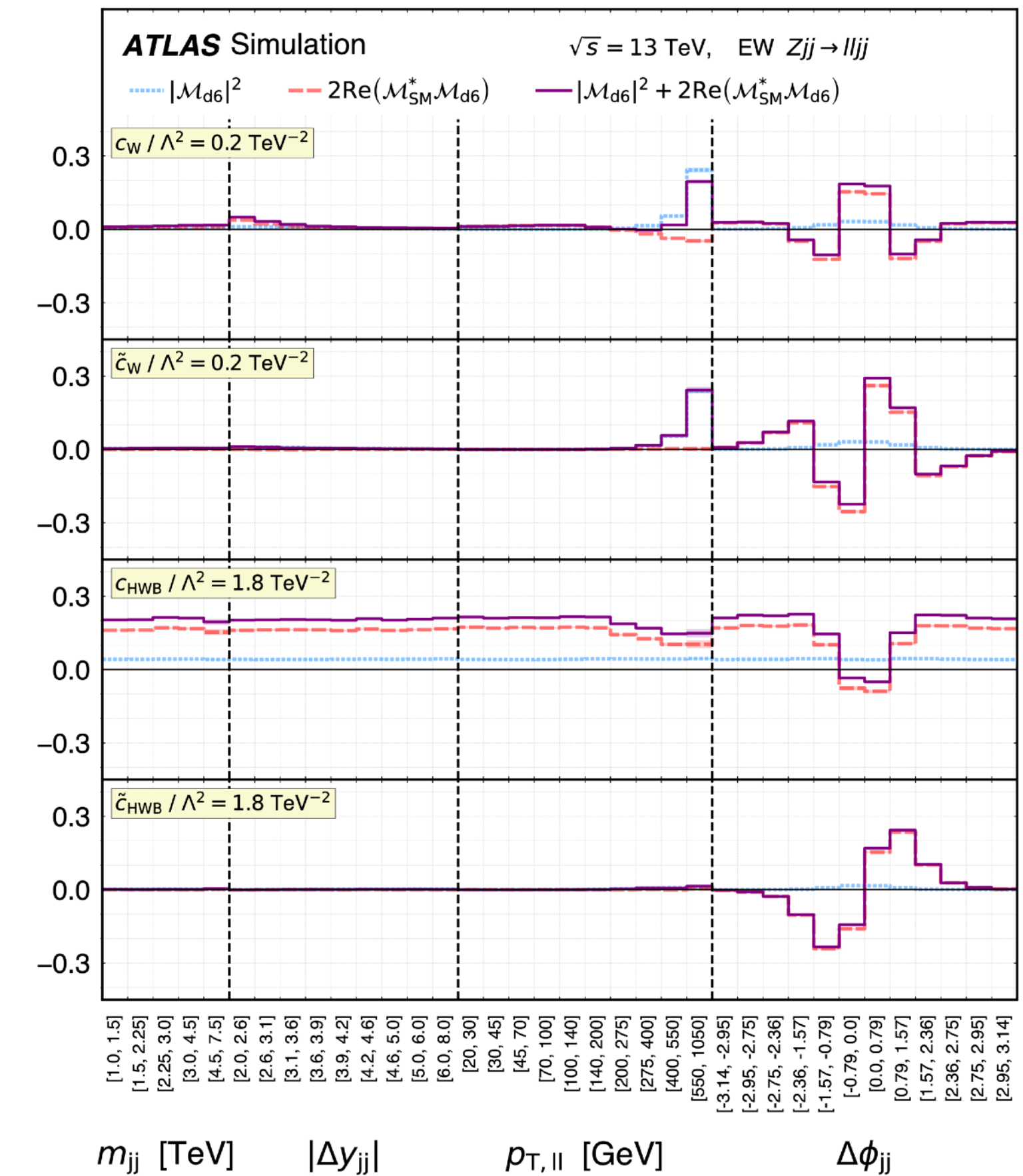
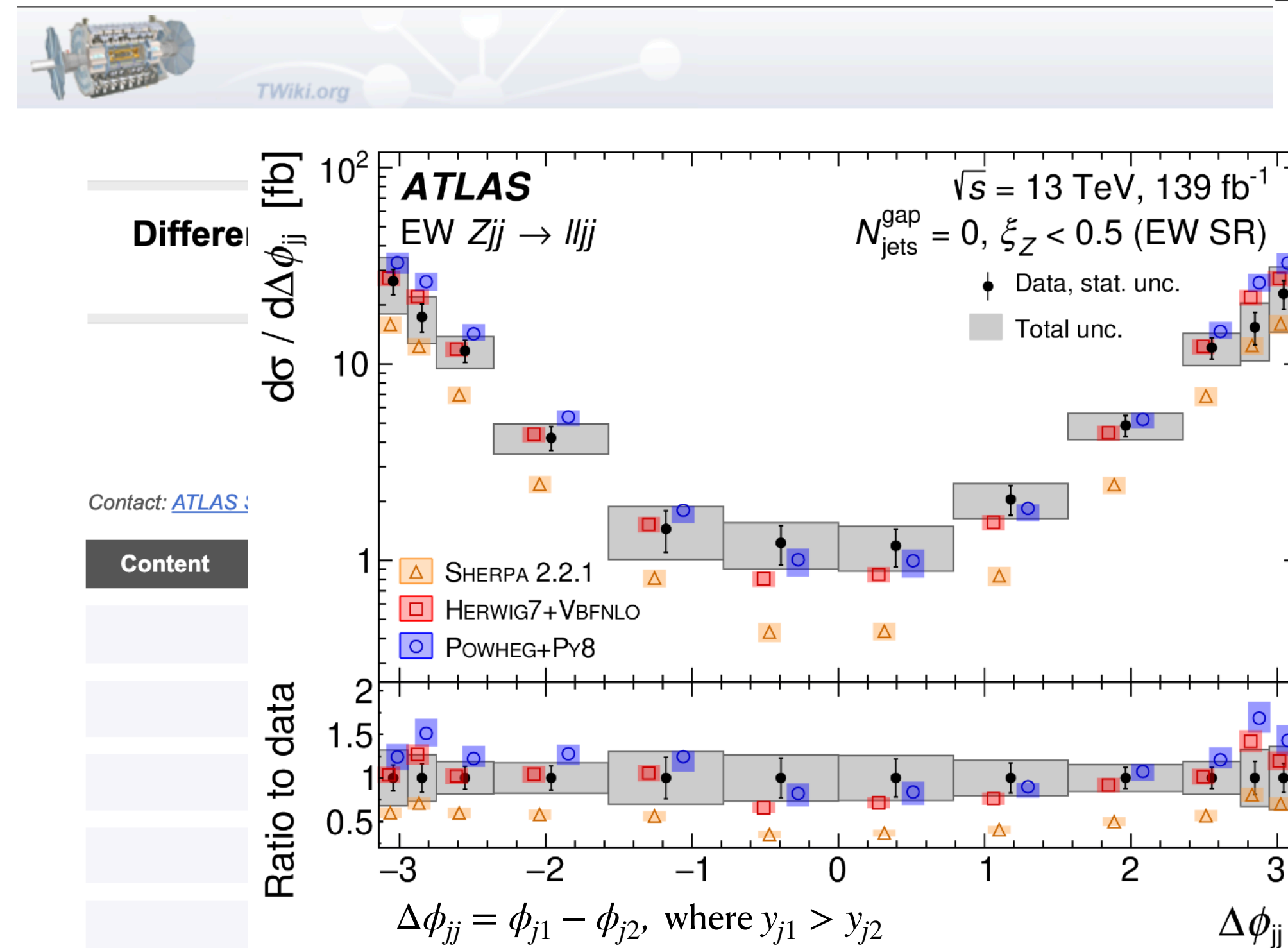
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Inspire record	-
Data points	-
Rivet analysis routine	-
Figures Tables Auxiliary Material	-

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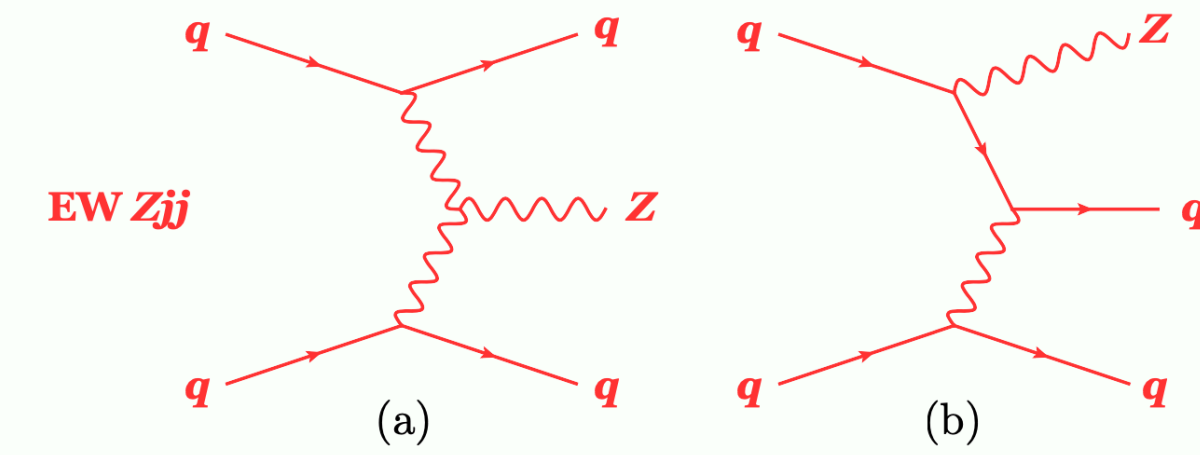


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Impact from BSM modifications on the measured EW Z_{jj} differential cross sections



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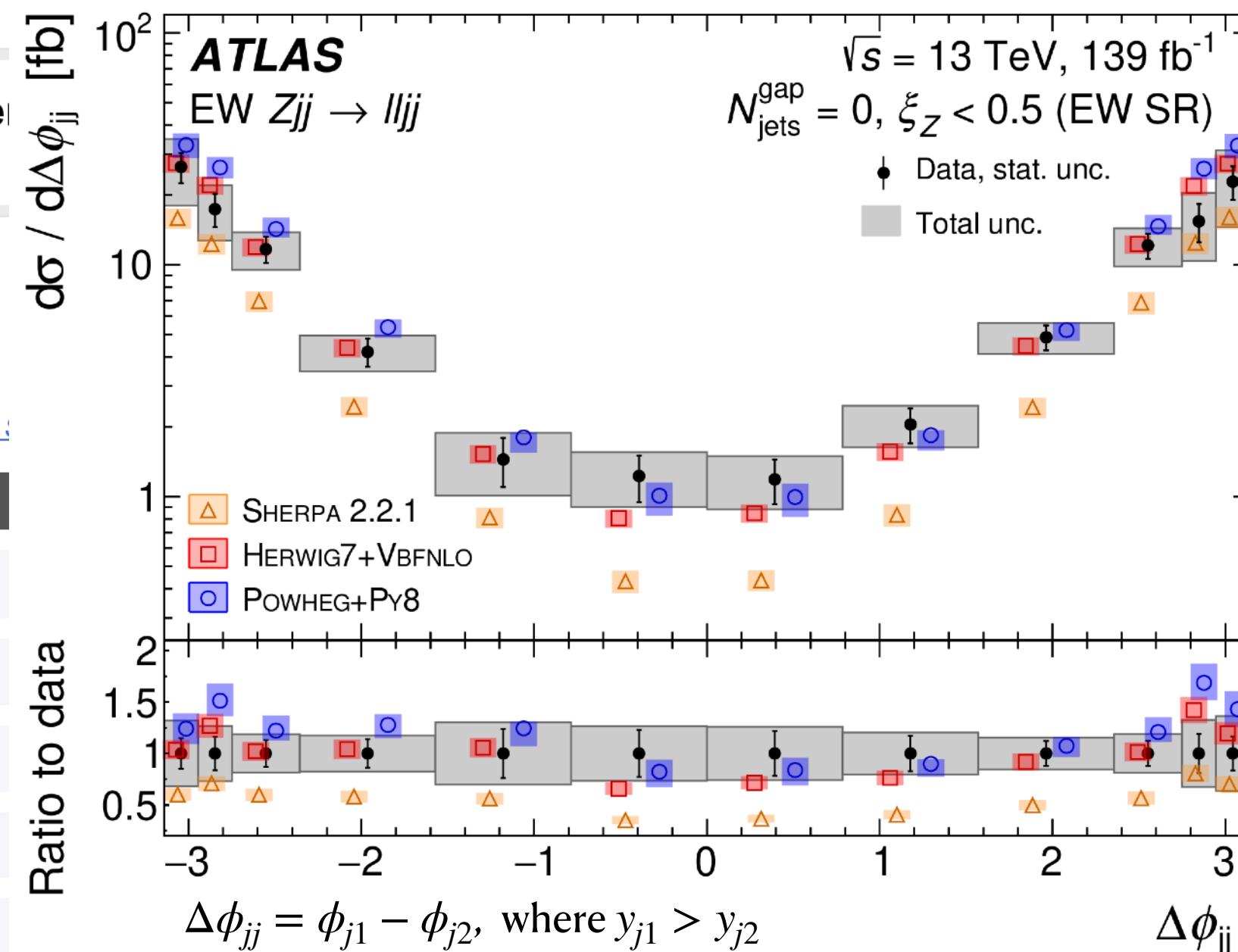
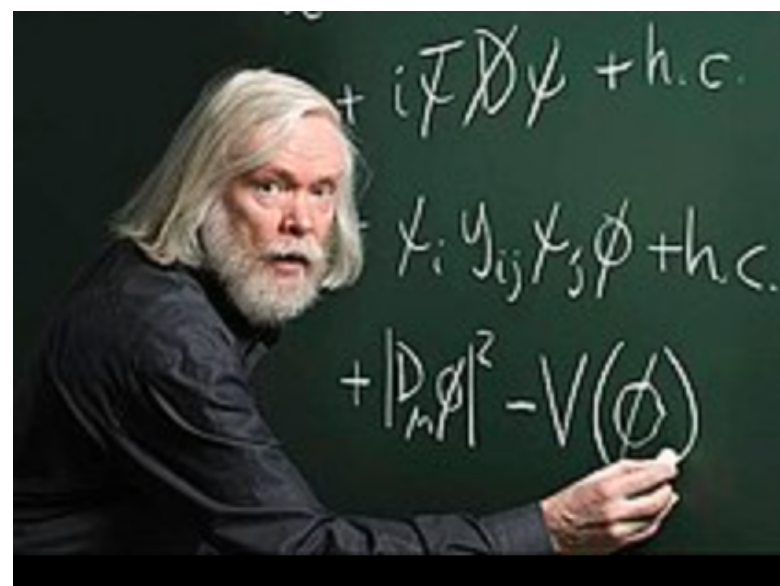
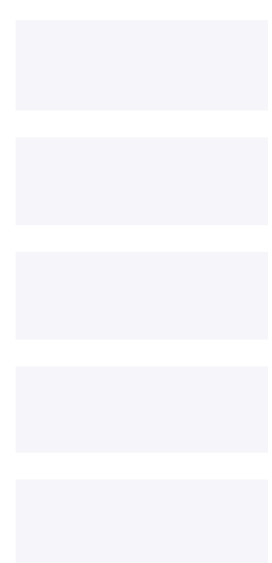
Top, Higgs, Diboson and Electroweak Fit to the Standard Model Effective Field Theory

John Ellis,^{a,b,c} Maeve Madigan,^d Ken Mimasu,^a Veronica Sanz^{e,f} and Tevong You^{b,d,g}

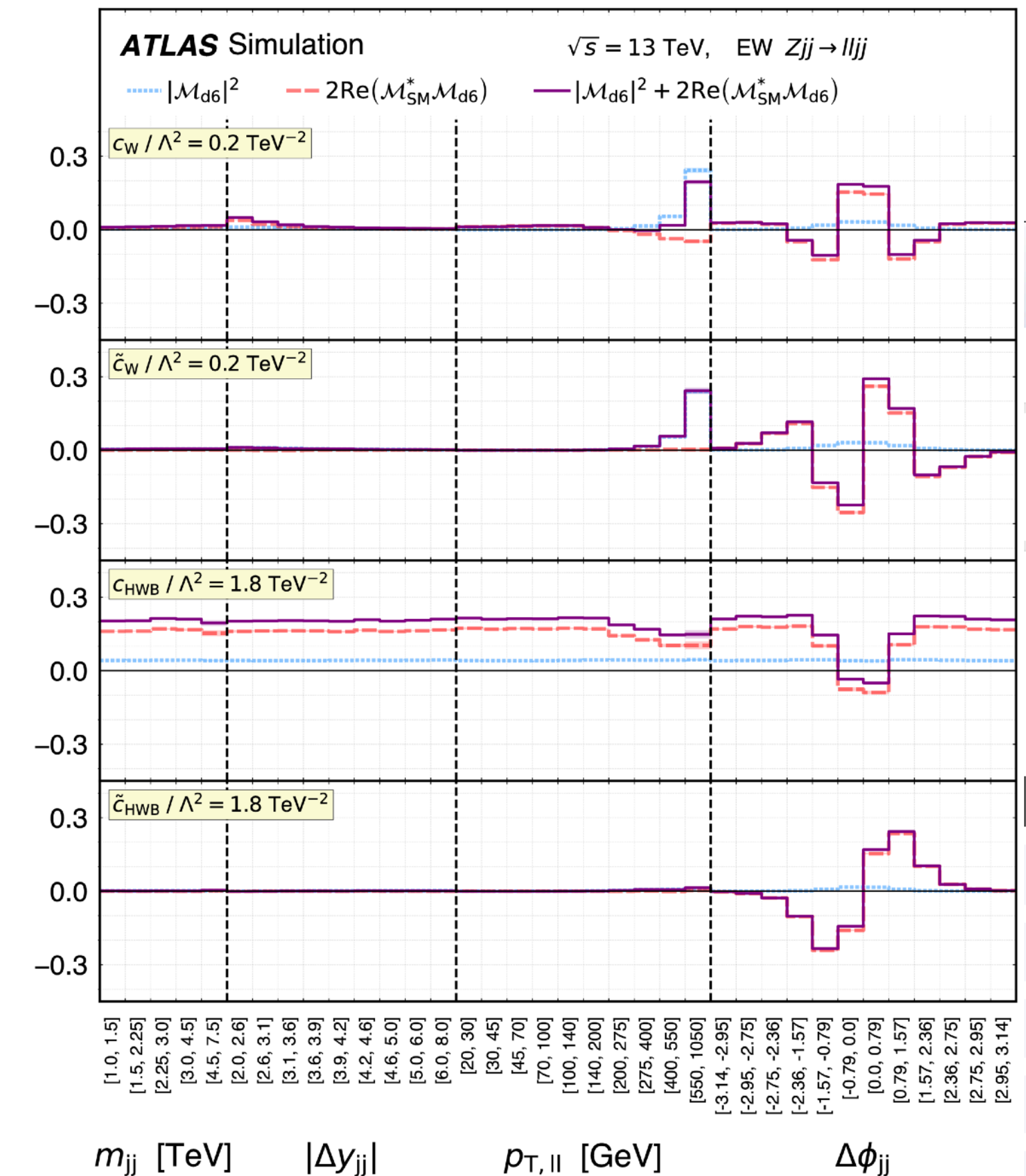
[arXiv:2012.02779](https://arxiv.org/abs/2012.02779), JHEP 04 (2021) 279

Contact: ATLAS@CERN.ch

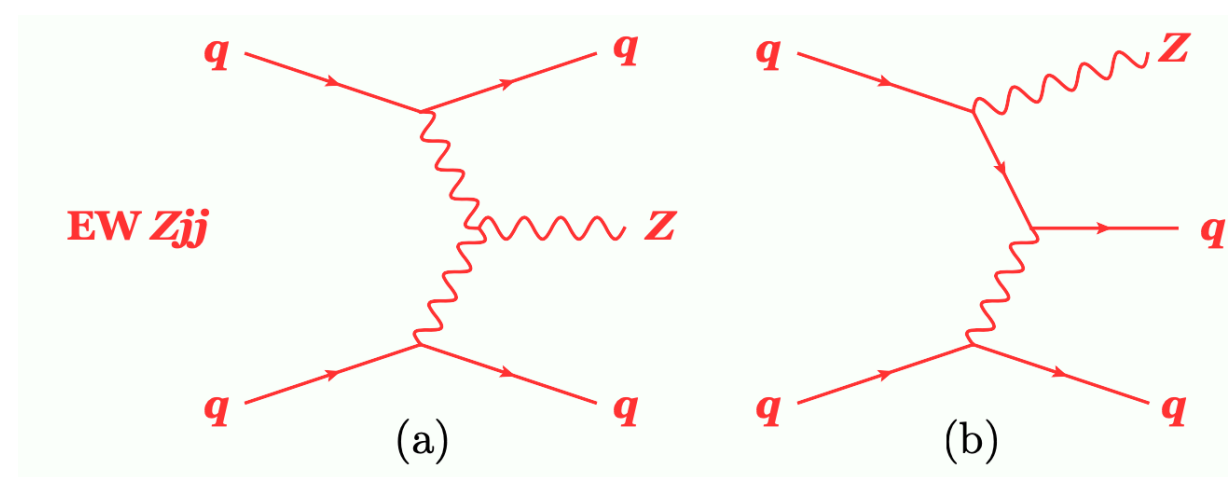
Content



Impact from BSM modifications on the measured EW Z_{jj} differential cross sections



Useful tools at hand



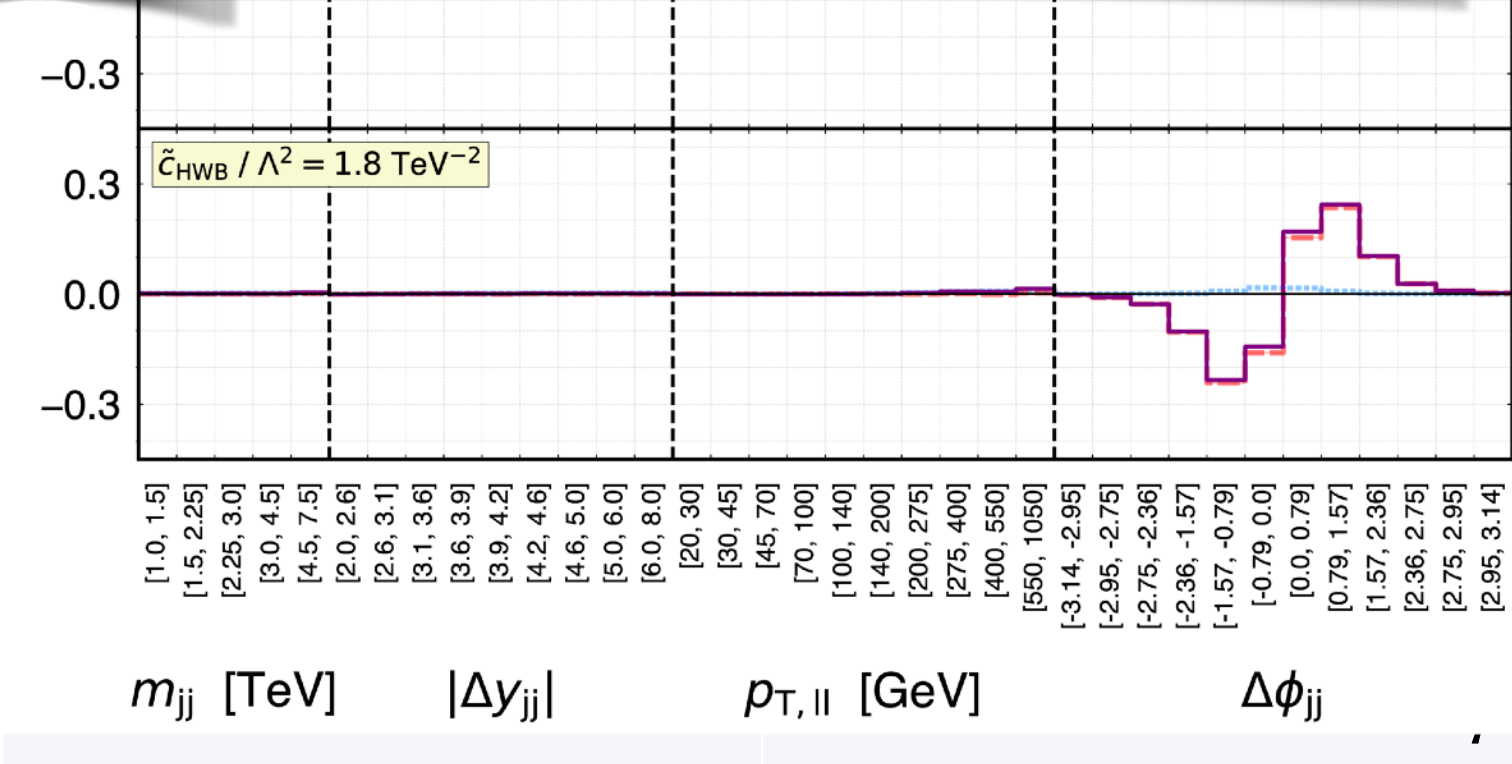
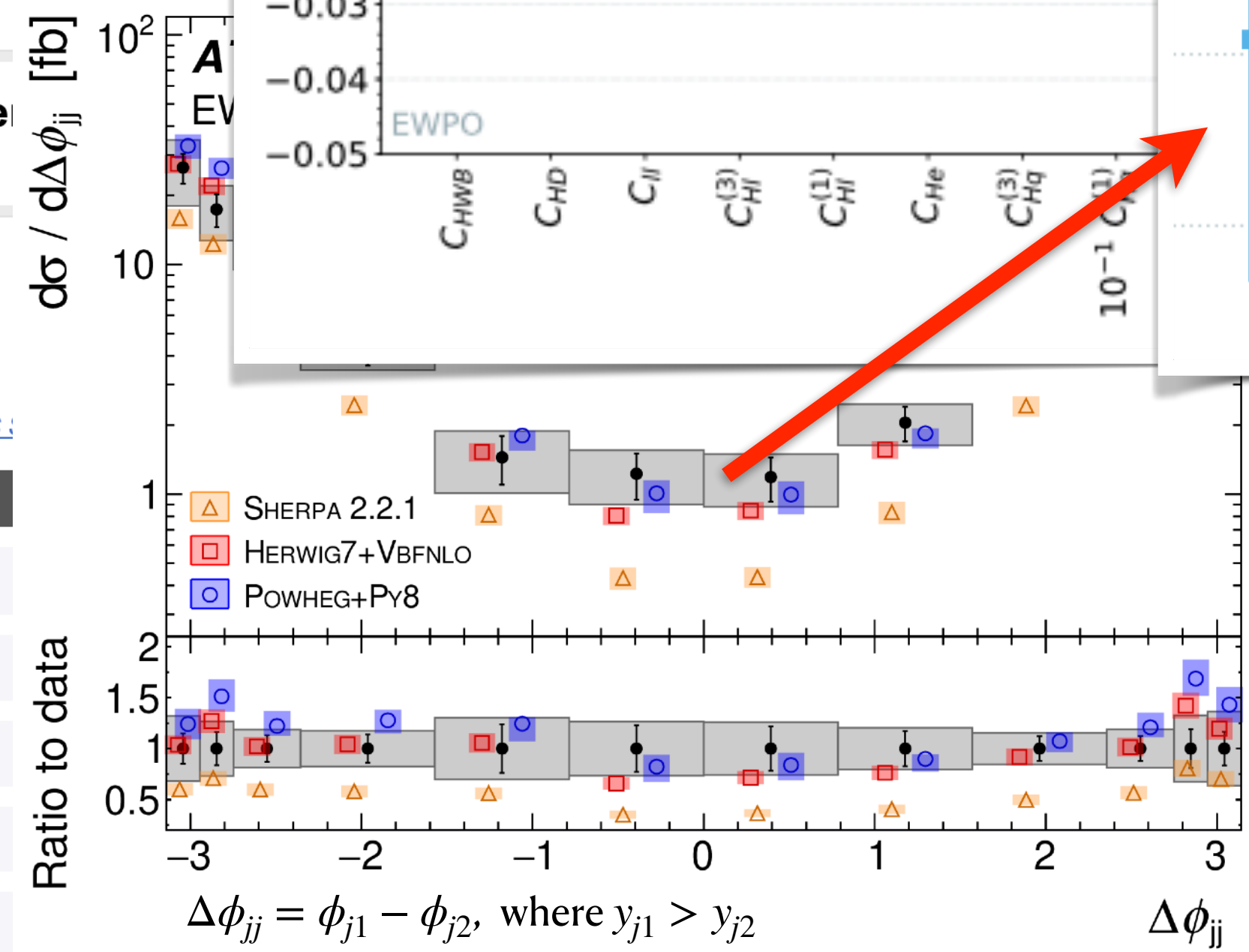
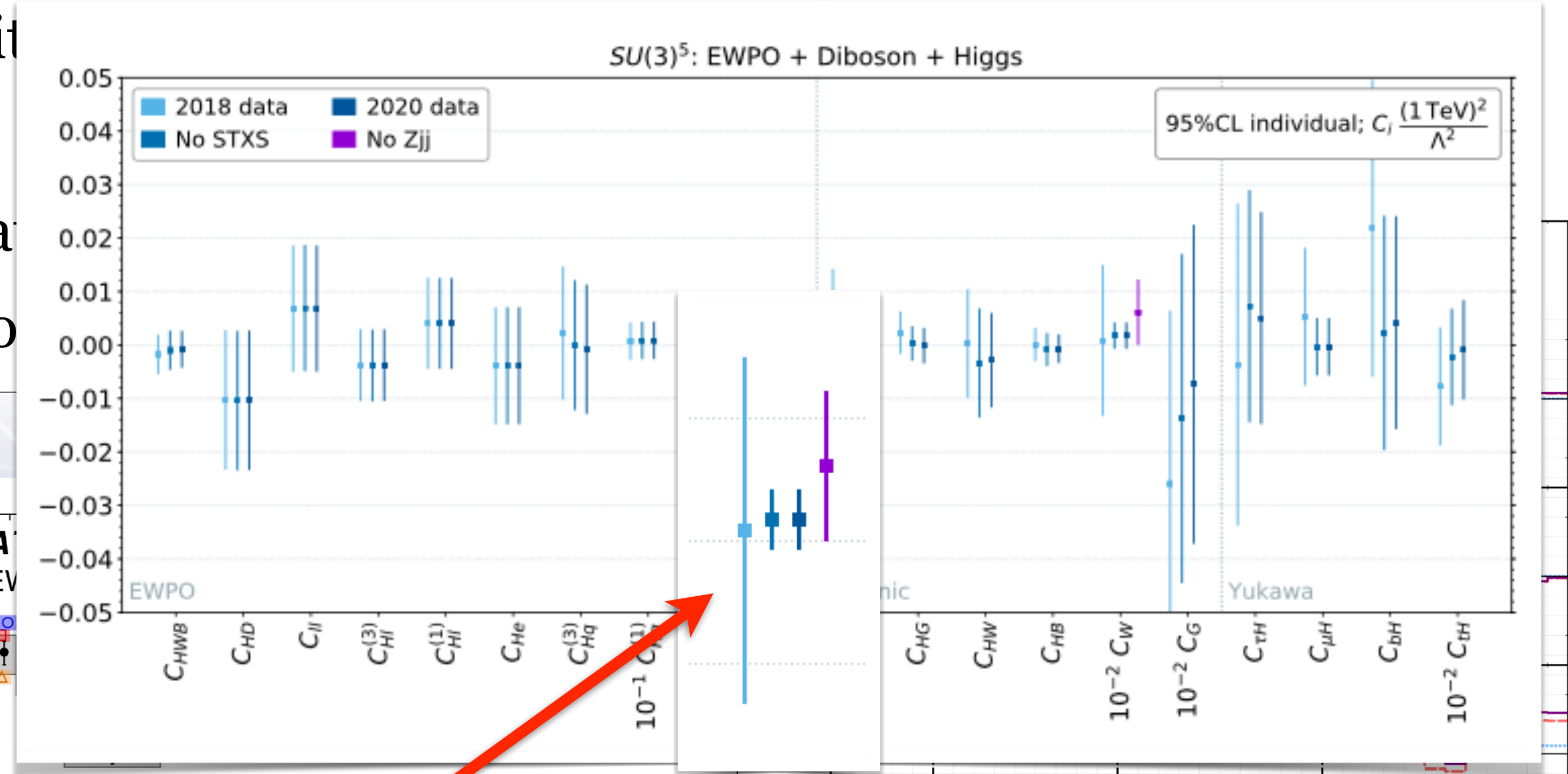
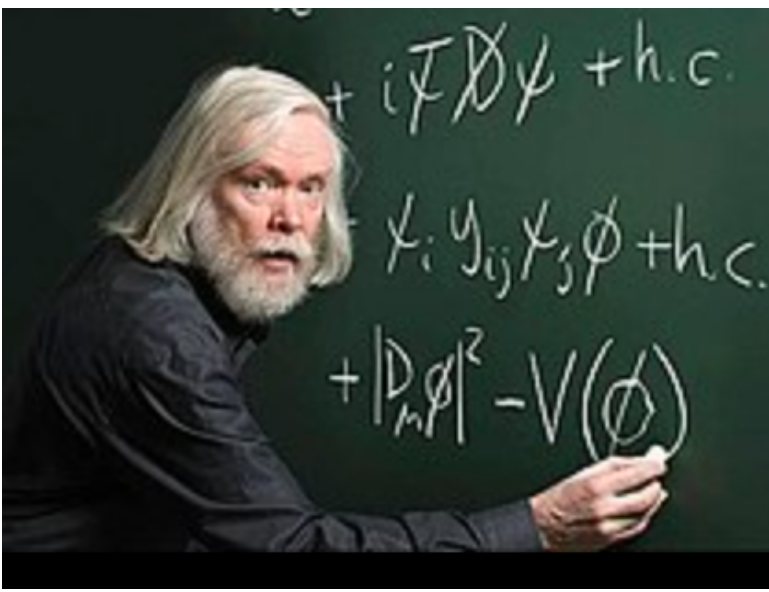
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Limitations with current approach

- As we have seen, current approach for precision measurements is quite nice
- However there are a few short-comings
- When designing our measurement, we need to a-priori settle on
 - A. Exact list of observables to measure
 - B. Bin-boundaries for each measurement
 - C. We are limited to measure one (or a few) observables at the time

Recent developments in machine learning opens up new possibilities

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- When designing our measurement, we need to a-priori settle on
 - A. Exact list of observables to measure **User can combine measured variables**
 - B. Bin-boundaries for each measurement **Unbinned**
 - C. We are limited to measure one (or a few) observables at the time **High dimensionality**

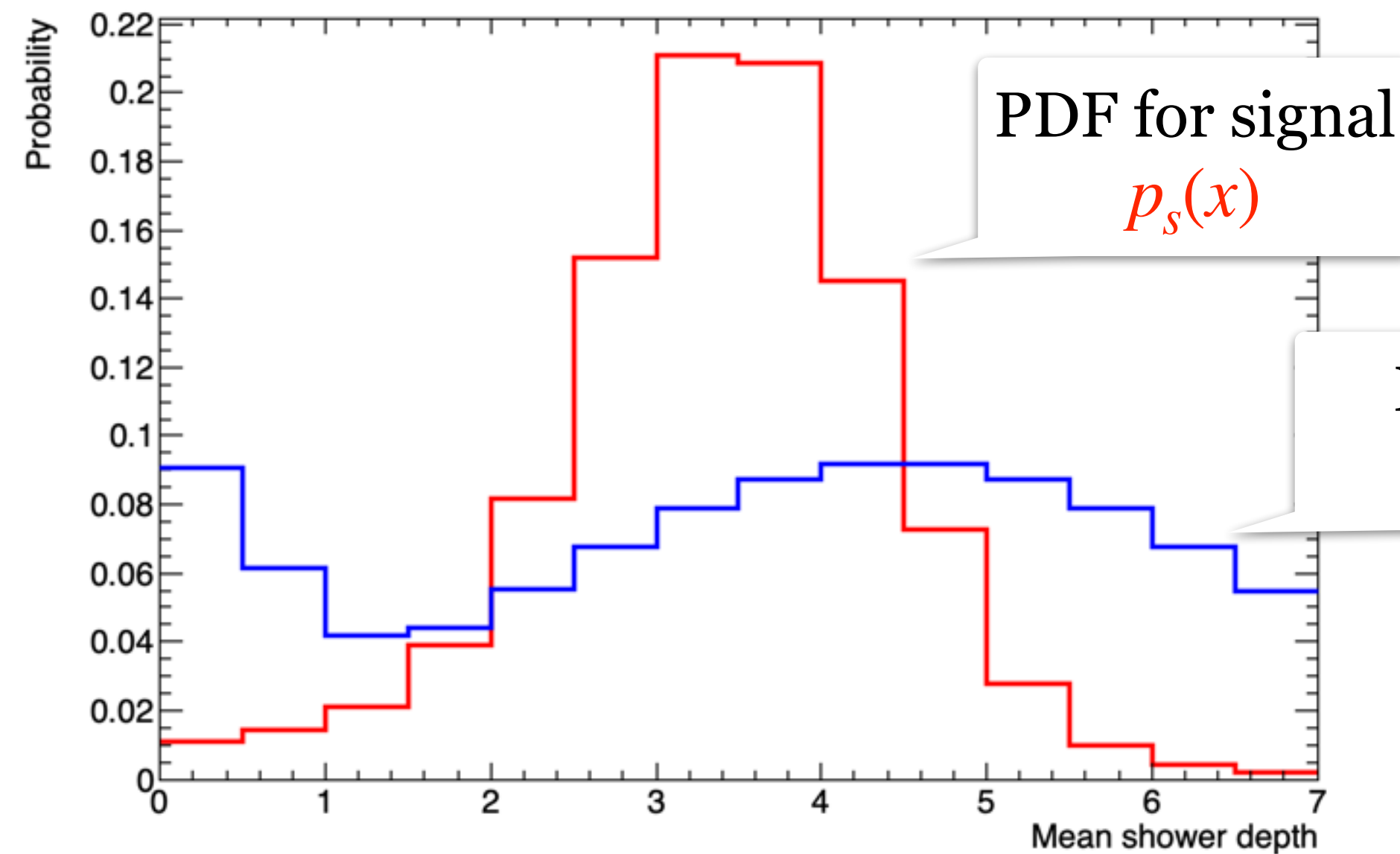
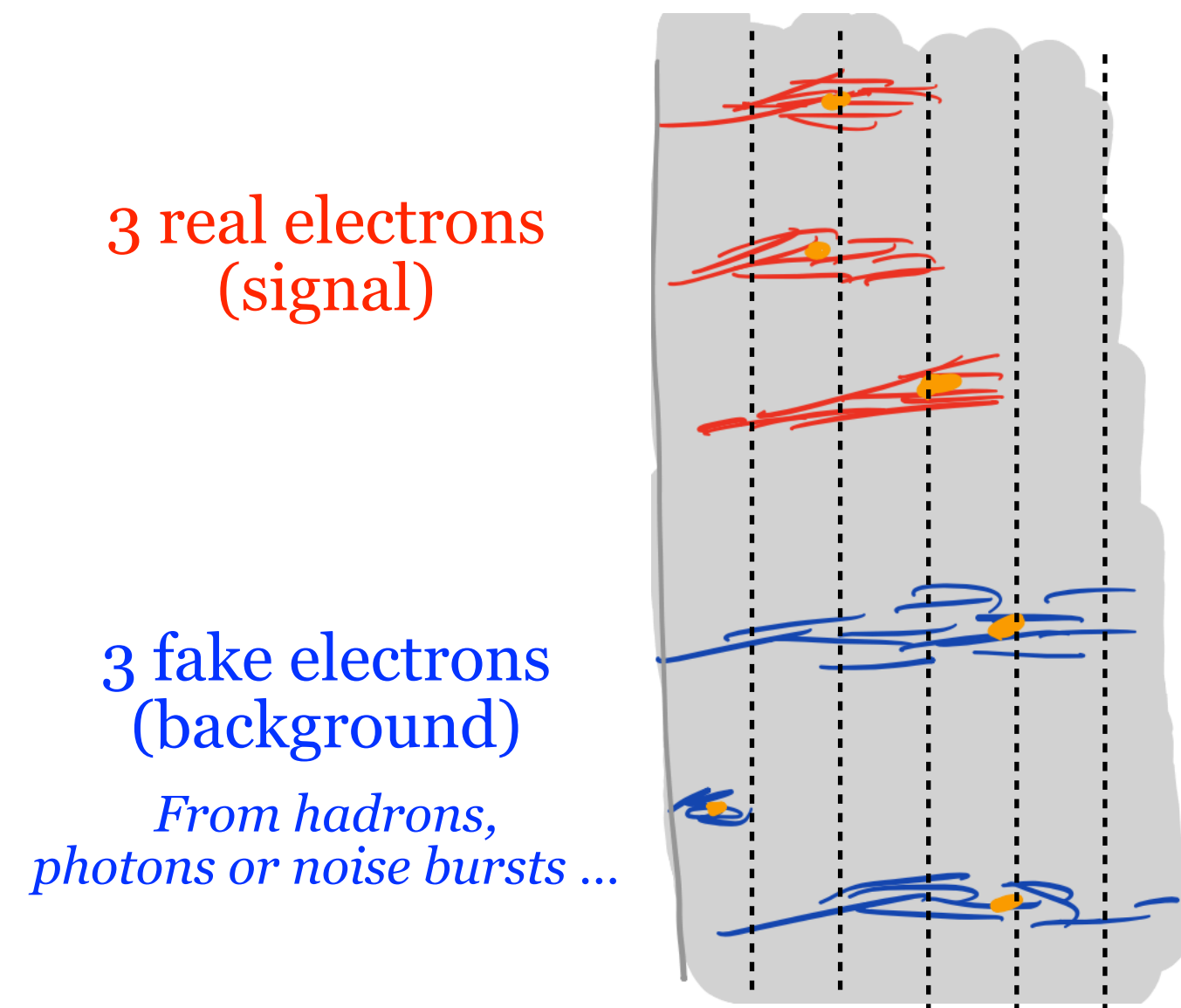
Recent developments in machine learning opens up new possibilities

Classification

Classifier
 $f(\vec{x})$

- Most common application of machine learning in particle physics is classification
- Goal: discriminate 'signal' from 'background'
 - Example: Detector signals from **real electrons** vs **hadrons/photons**

PDF:
 $\int p(x) dx = 1$

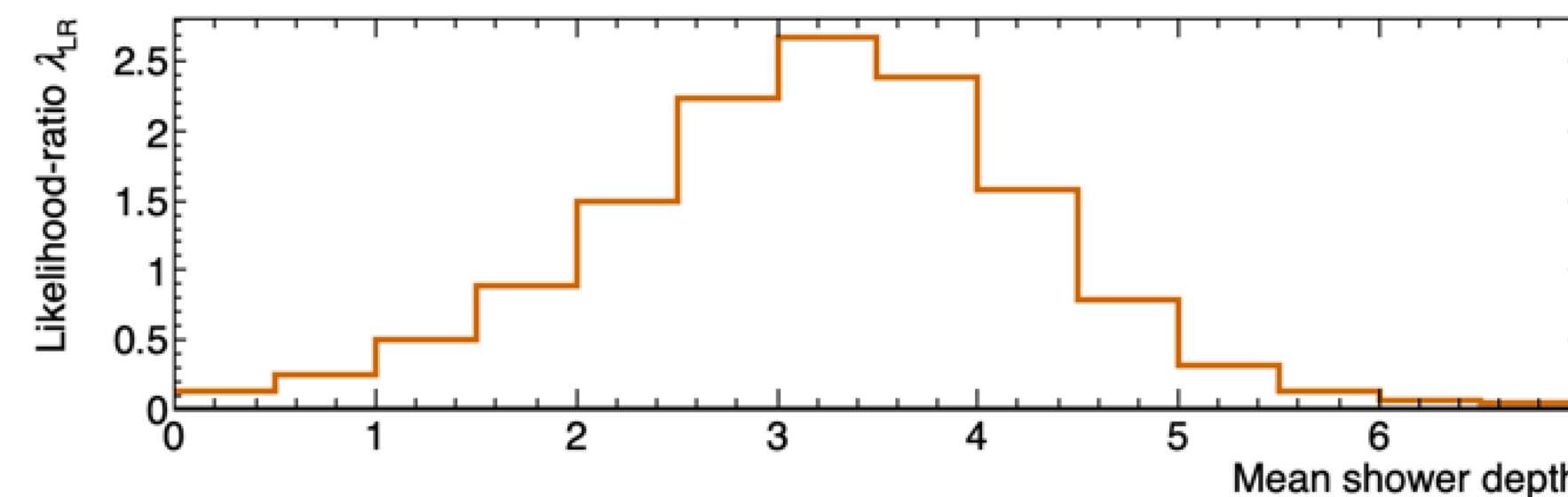
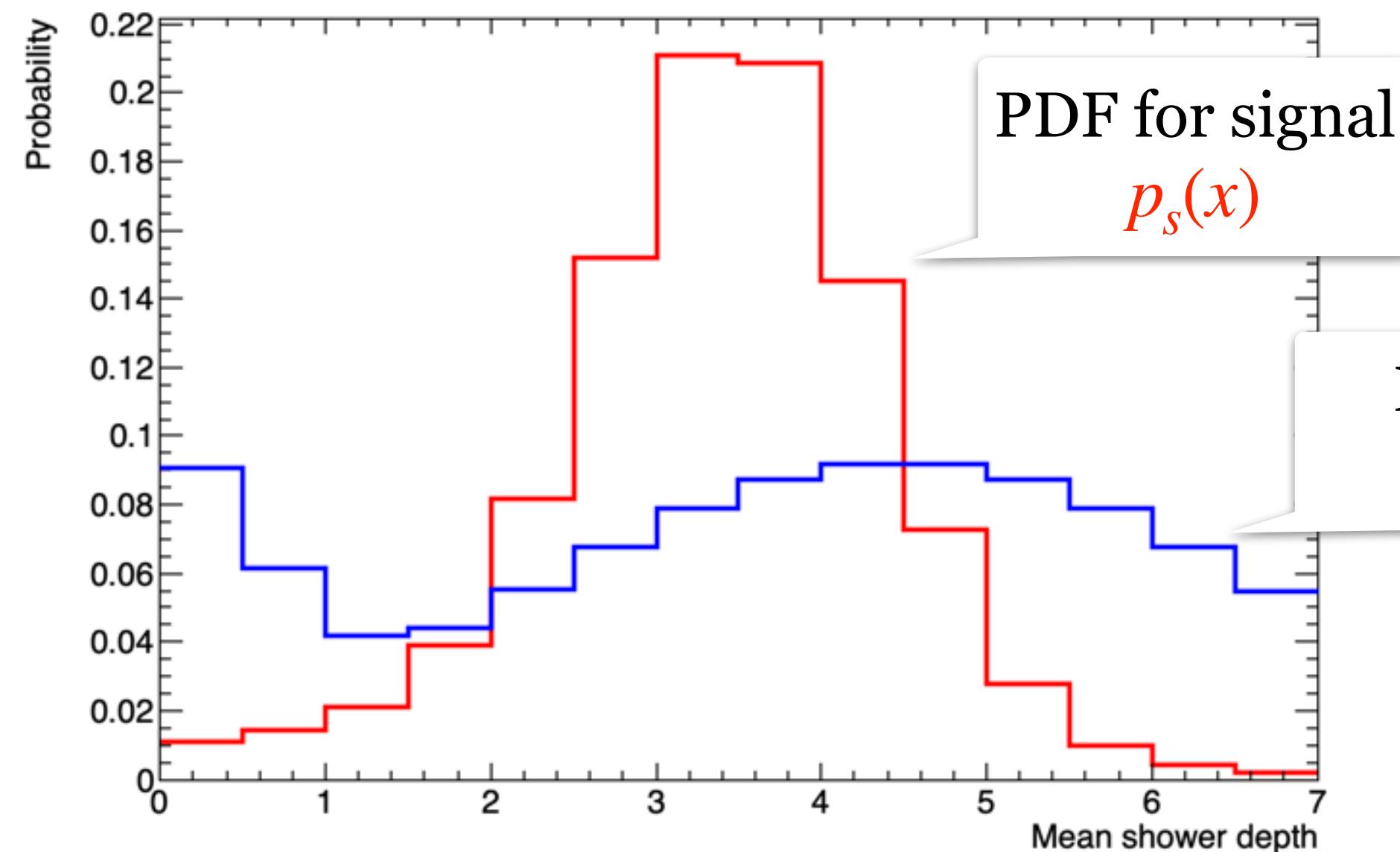
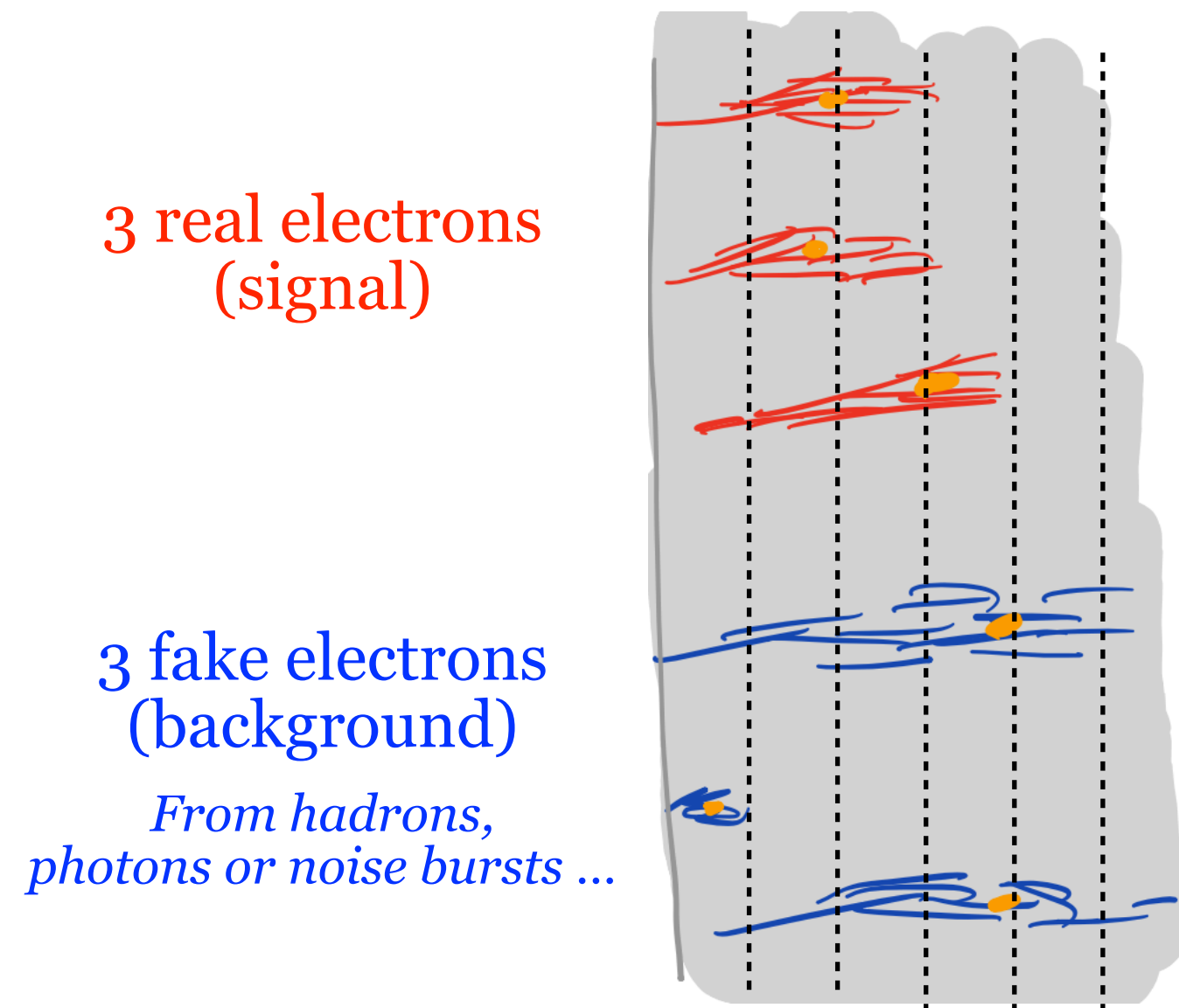


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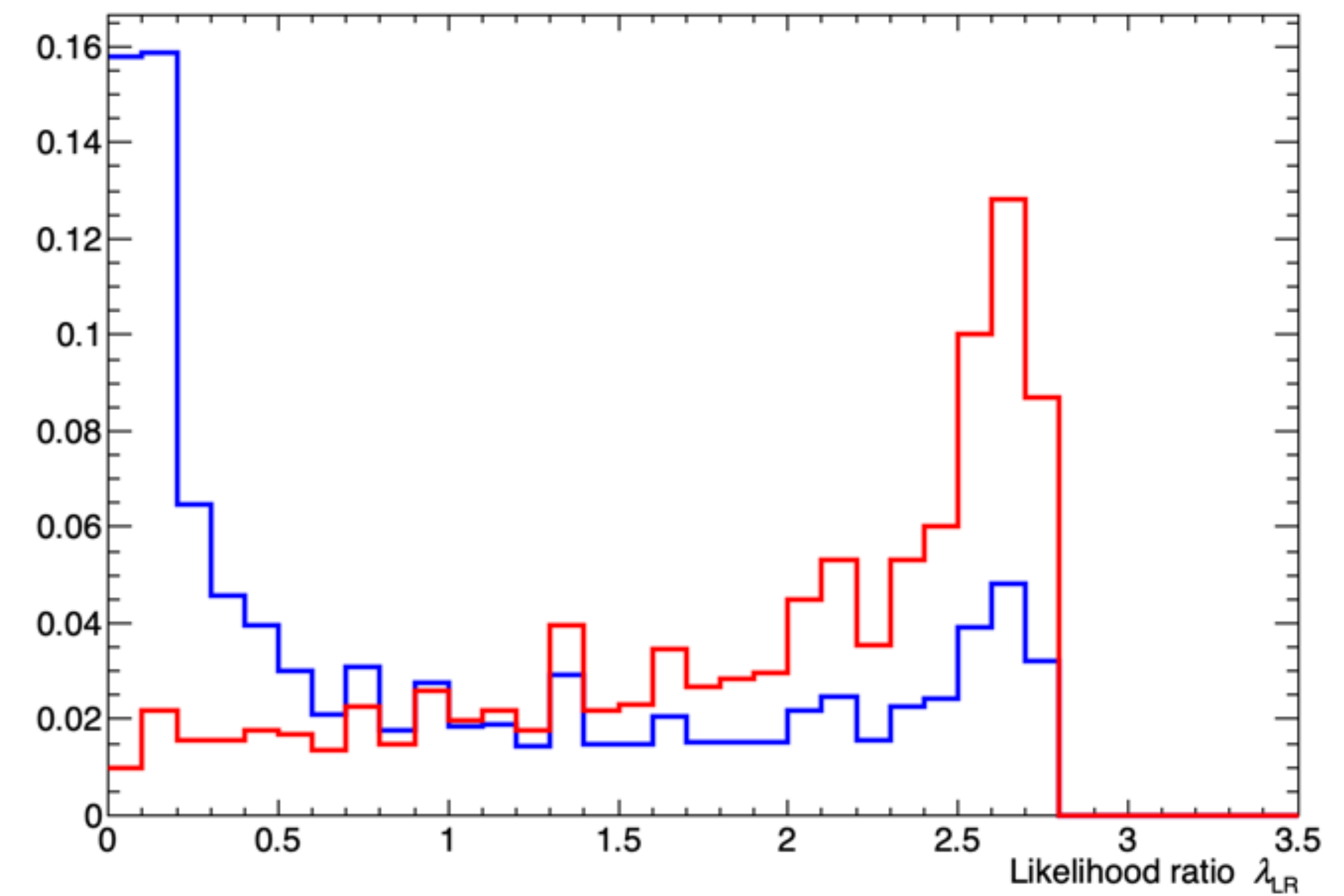
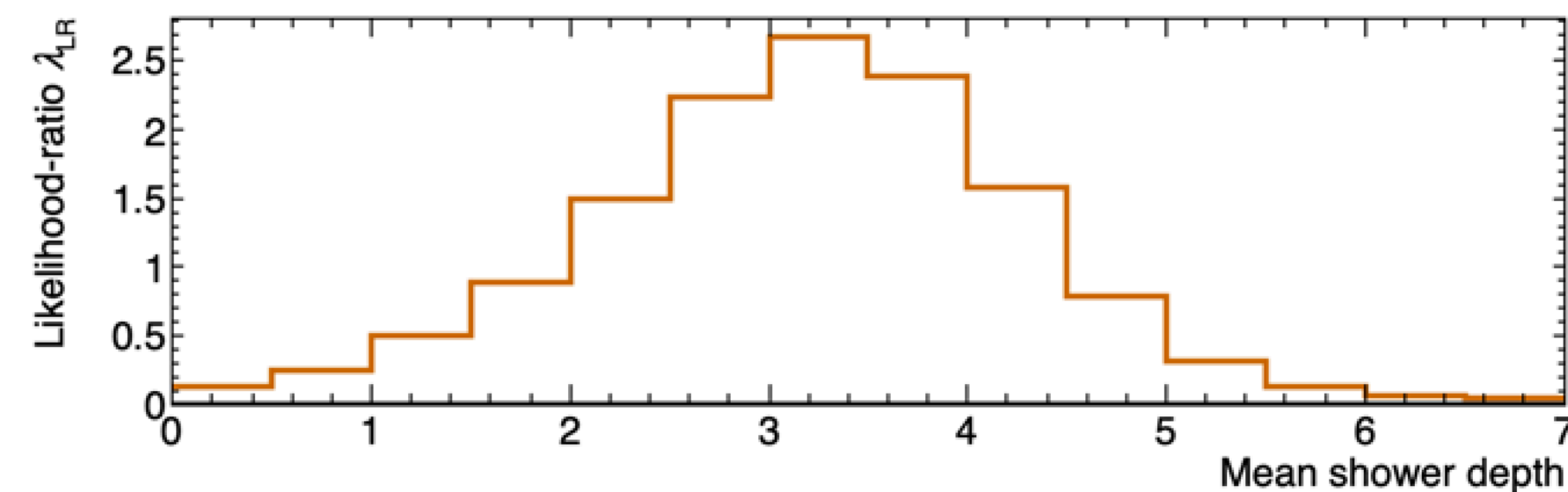
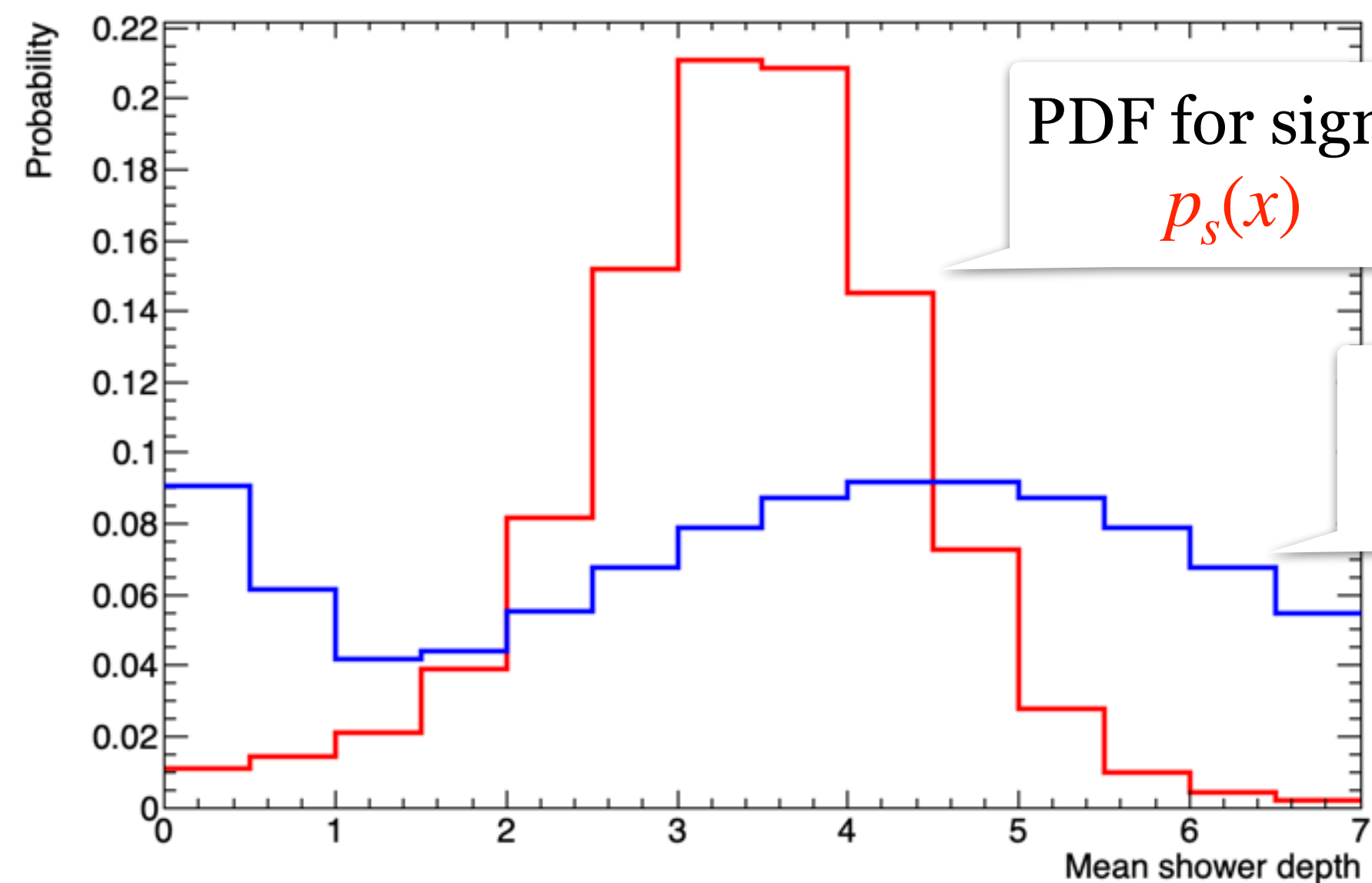


Likelihood ratio:

$$\lambda_{LR} = \frac{p_s(x)}{p_b(x)}$$

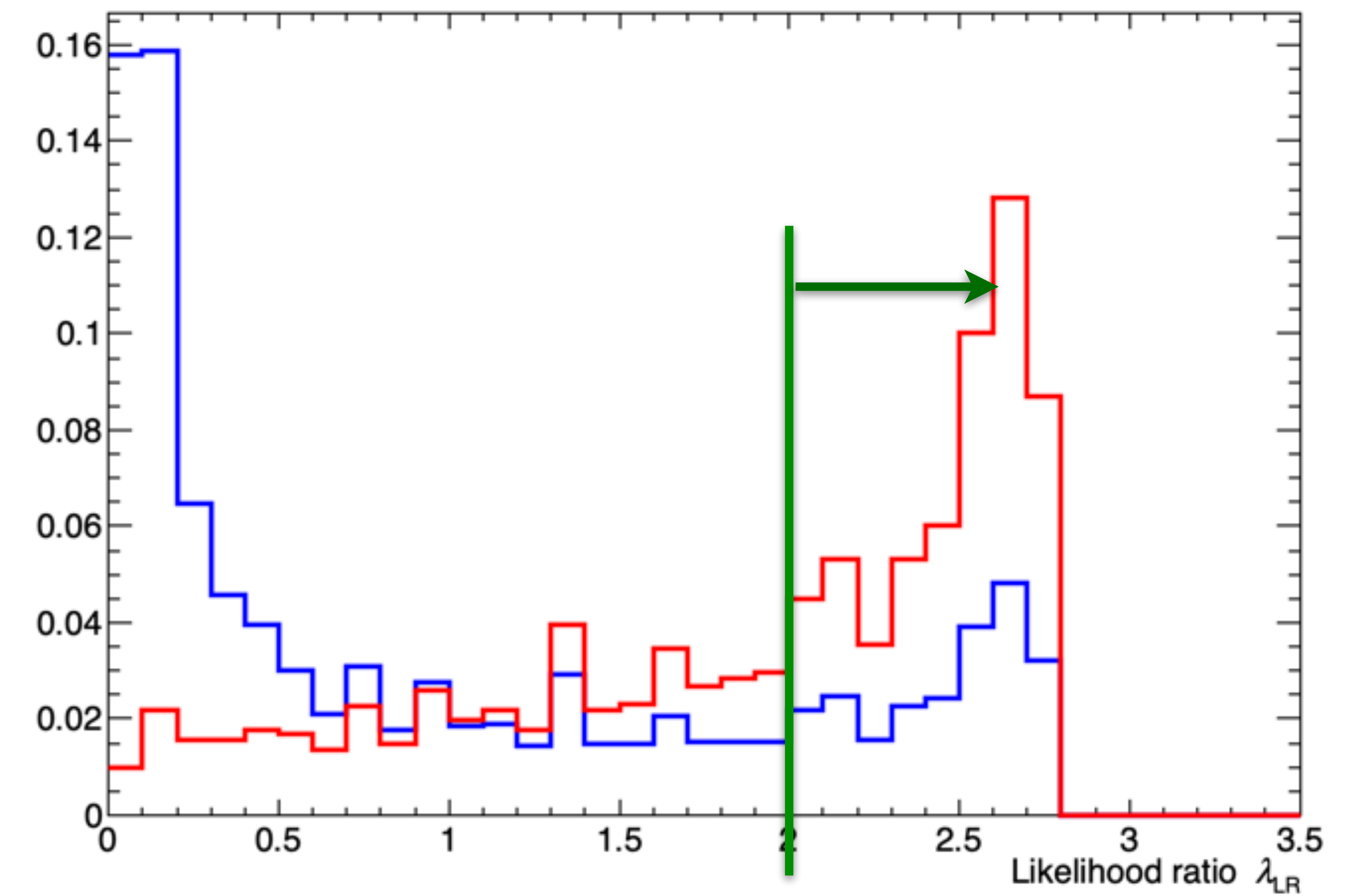
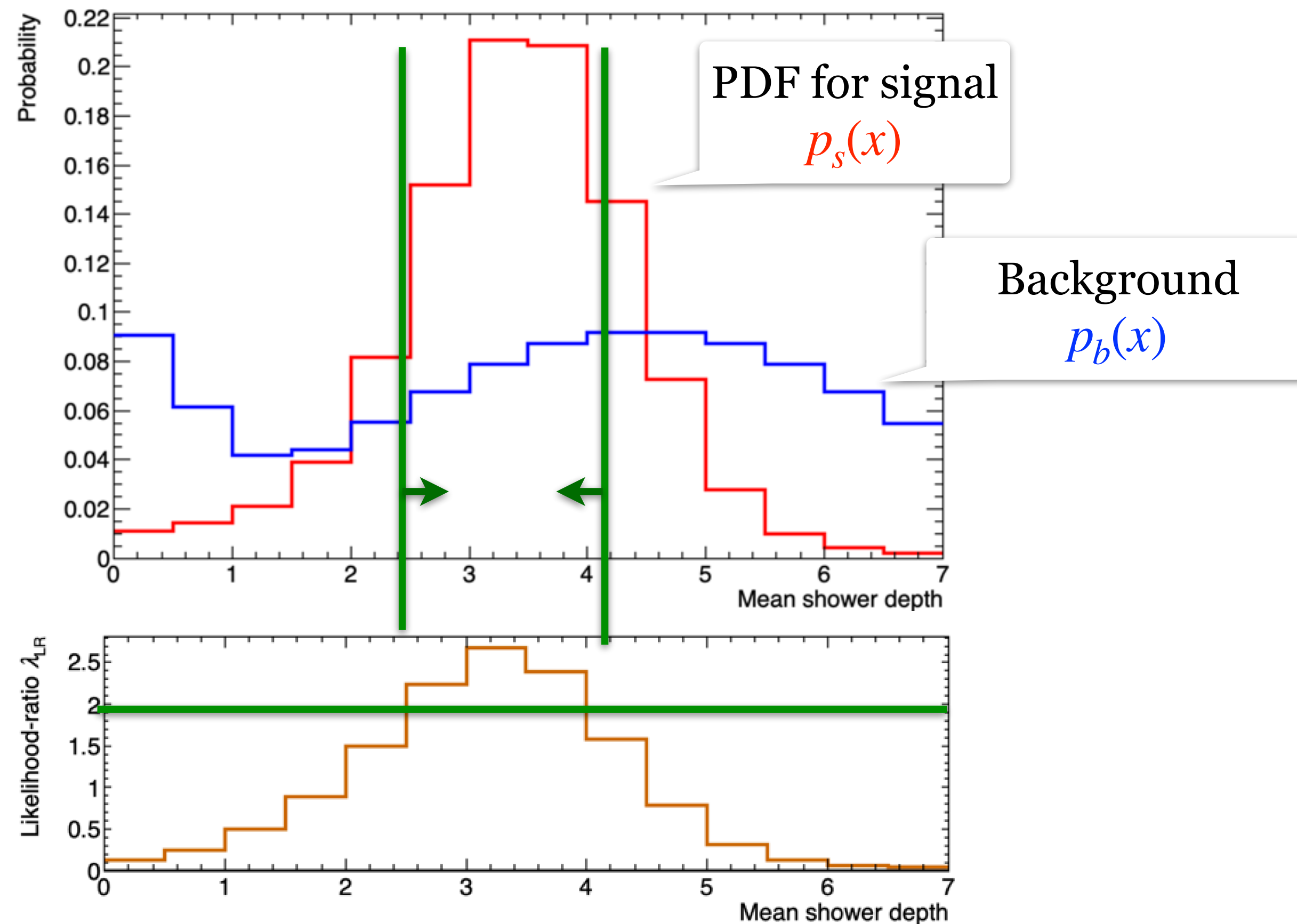
The Neyman-Pearson lemma

- The Neyman-Pearson lemma states that the best achievable discriminant will be the likelihood ratio λ_{LR} (or any monotonic function of it)



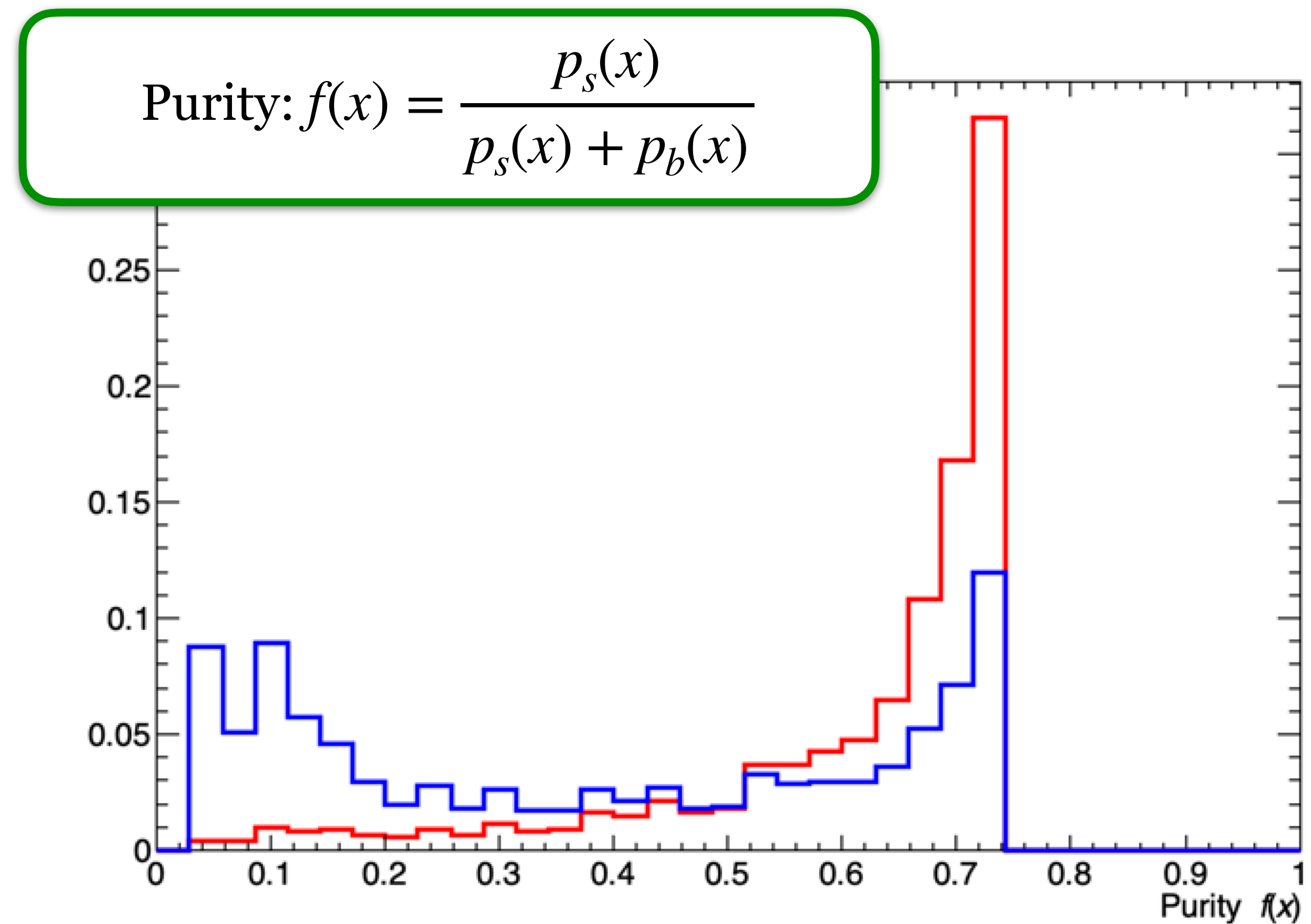
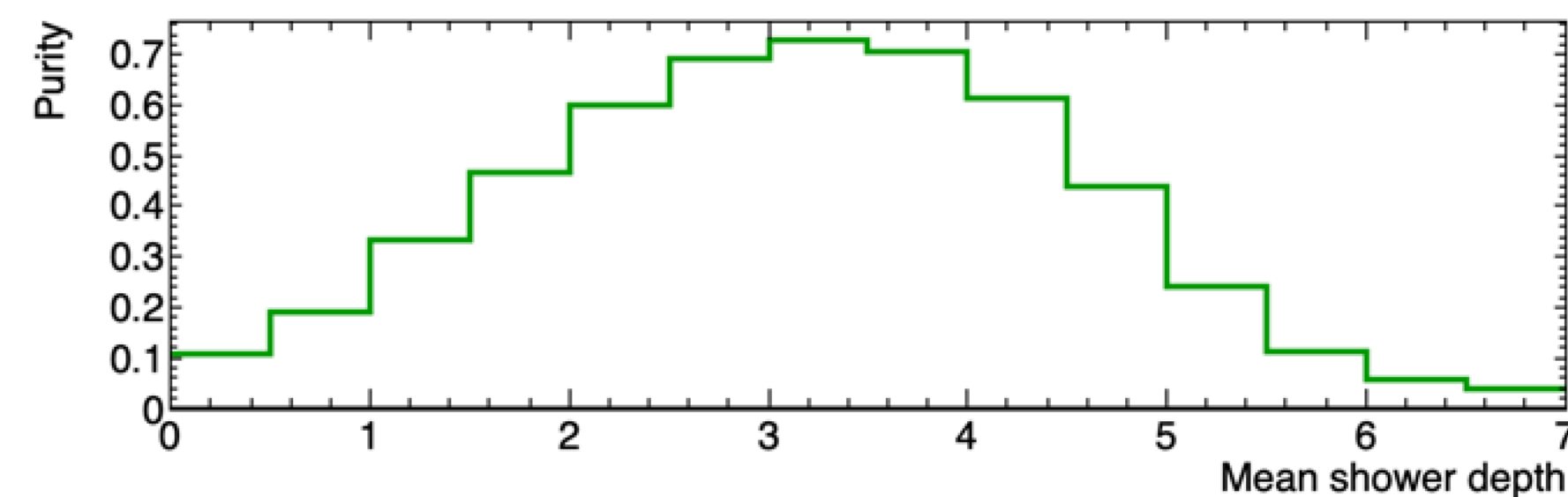
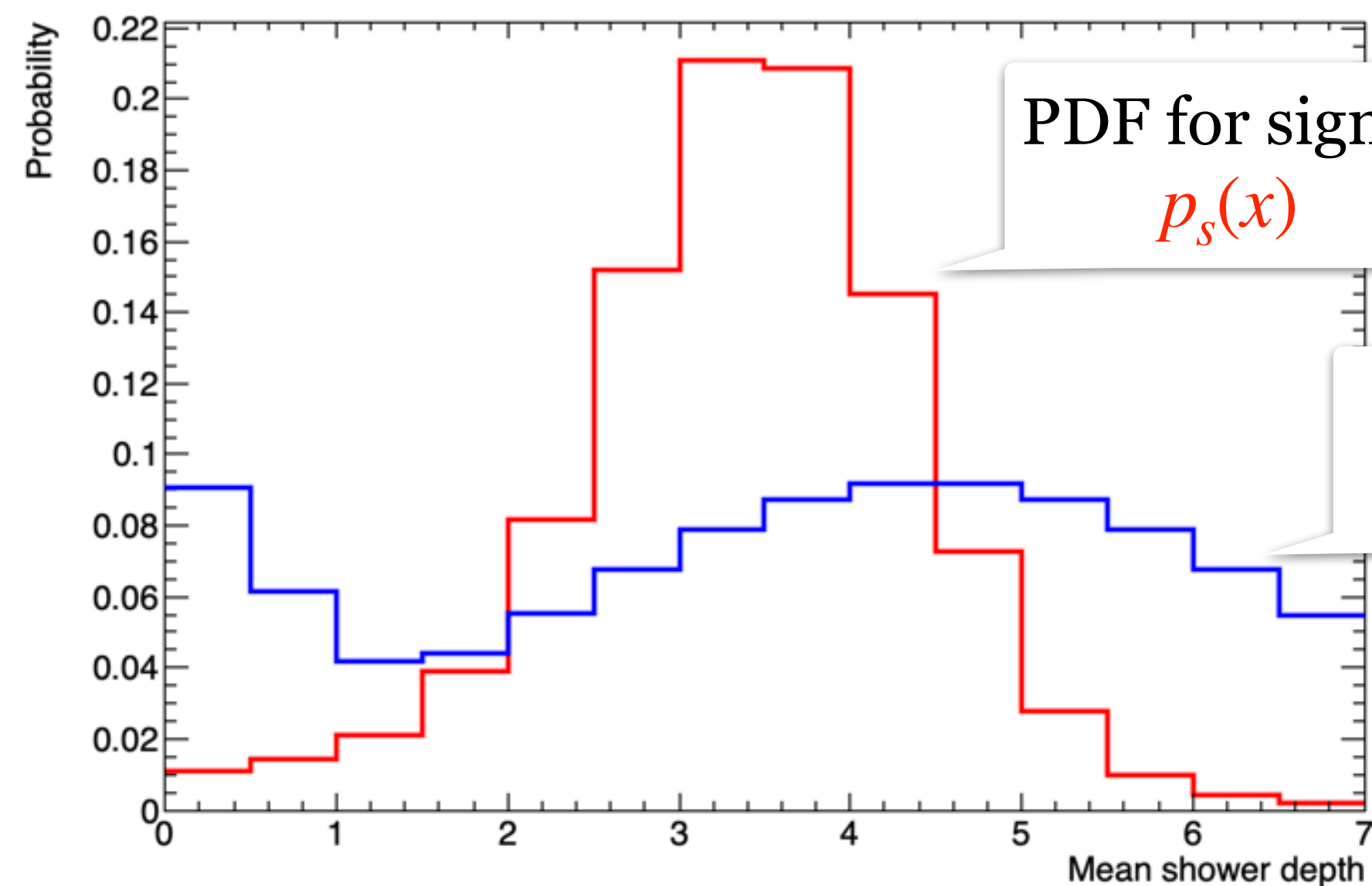
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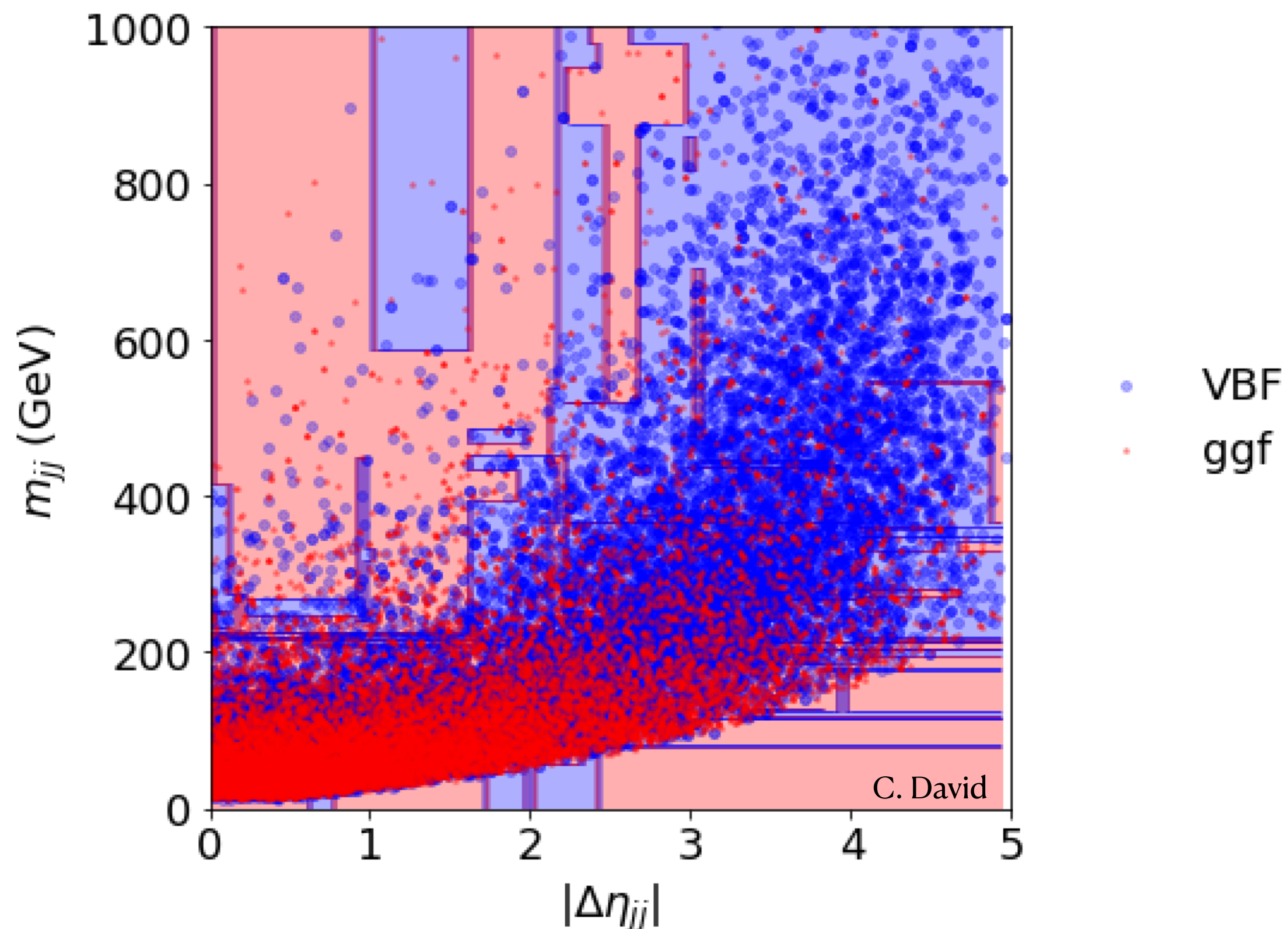


Many machine learning algorithm returns the purity as output
It is closely related to the likelihood ratio

Multivariate analysis

Classifier
 $f(\vec{x})$

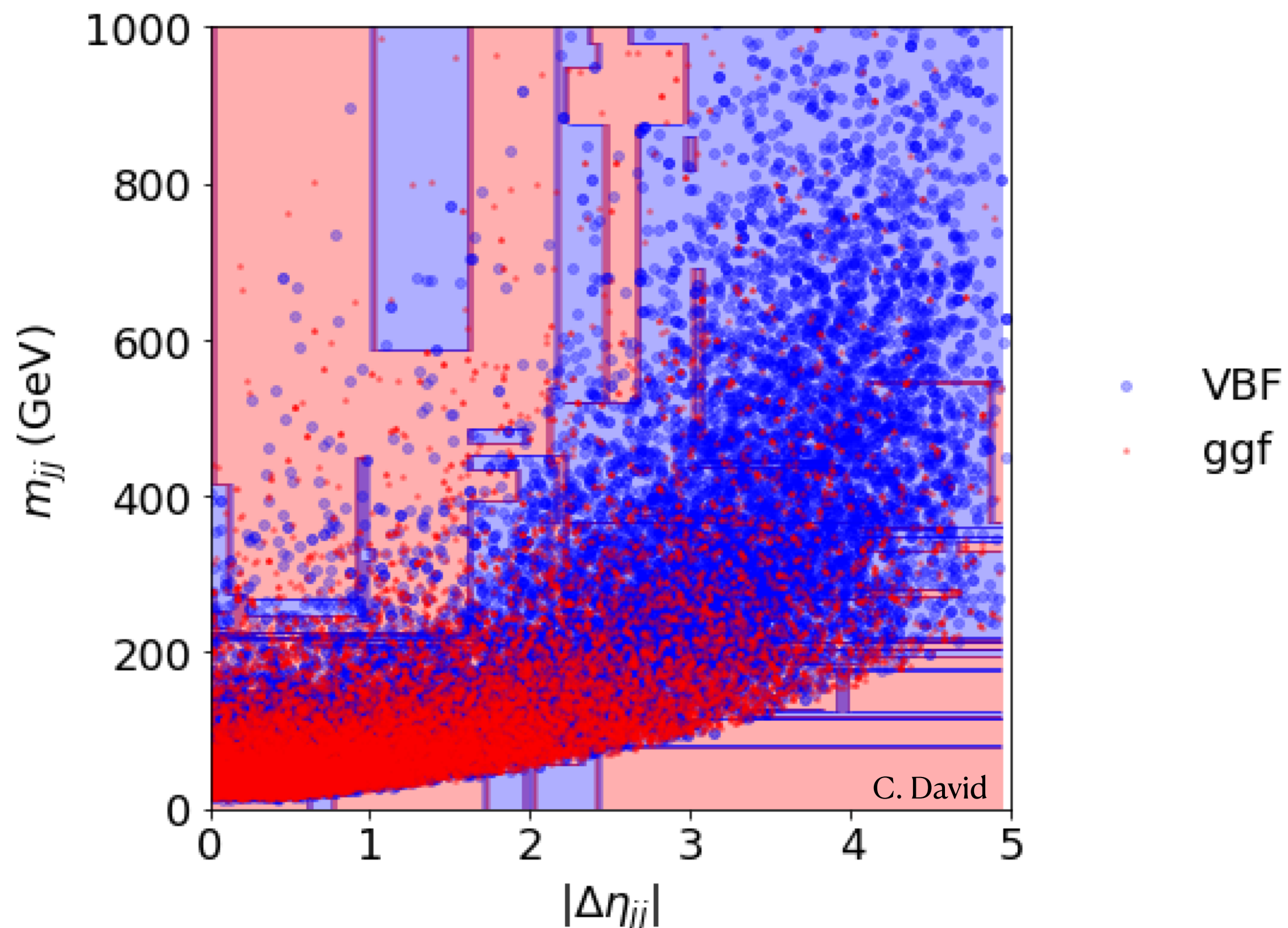
- Previous example only dealt with one input variable (the shower depth)
- We can perform much better if we use more information, i.e. more distinguish features (input variables): $x \rightarrow \vec{x}$
- Neyman-Pearson lemma still holds, but quickly challenging to estimate $p_s(\vec{x})$ and $p_b(\vec{x})$



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Multivariate techniques to the rescue

ML used for classification:
features \vec{x} as input, returns $f(\vec{x})$
 $f(\vec{x})$ separates signal from background

**For many implementations $f(\vec{x})$
will be an estimate of the purity**

True for traditional BDTs, and NNs trained with the
cross entropy as loss function

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$$\text{Likelihood ratio: } \lambda_{\text{LR}}(\vec{x}) = \frac{p_s(\vec{x})}{p_b(\vec{x})}$$

$$\text{Purity: } f(\vec{x}) = \frac{p_s(\vec{x})}{p_s(\vec{x}) + p_b(\vec{x})}$$

$$\rightarrow \lambda_{\text{LR}}(\vec{x}) = \frac{f(\vec{x})}{1 - f(\vec{x})}$$

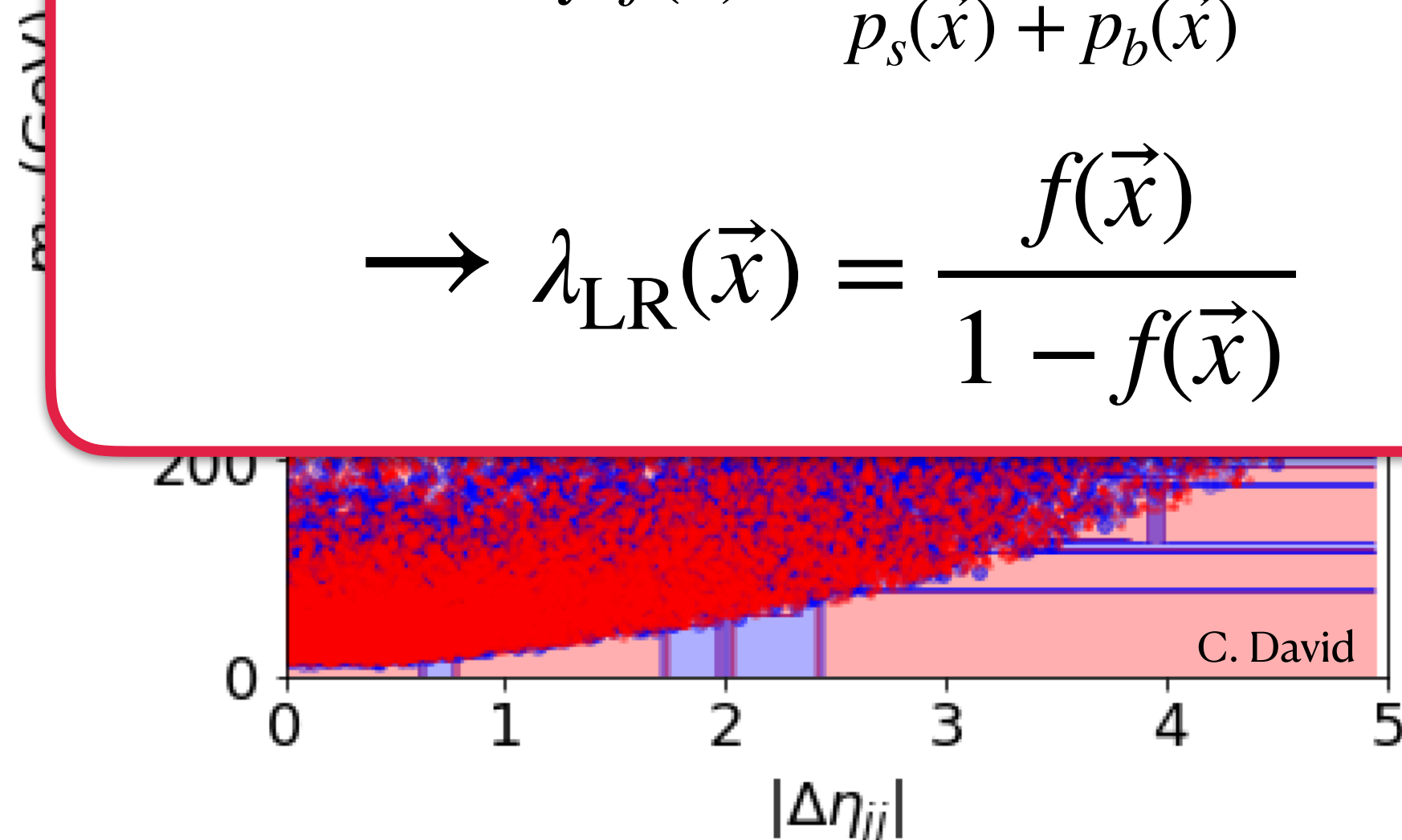
VBF
ggf

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Using **cross entropy** as loss function, finds $f(\vec{x})$ that maximizes:

$$\sum_{\text{sig}} w_i \ln(f(\vec{x}_i)) + \sum_{\text{bkg}} w_i \ln(1 - f(\vec{x}_i))$$

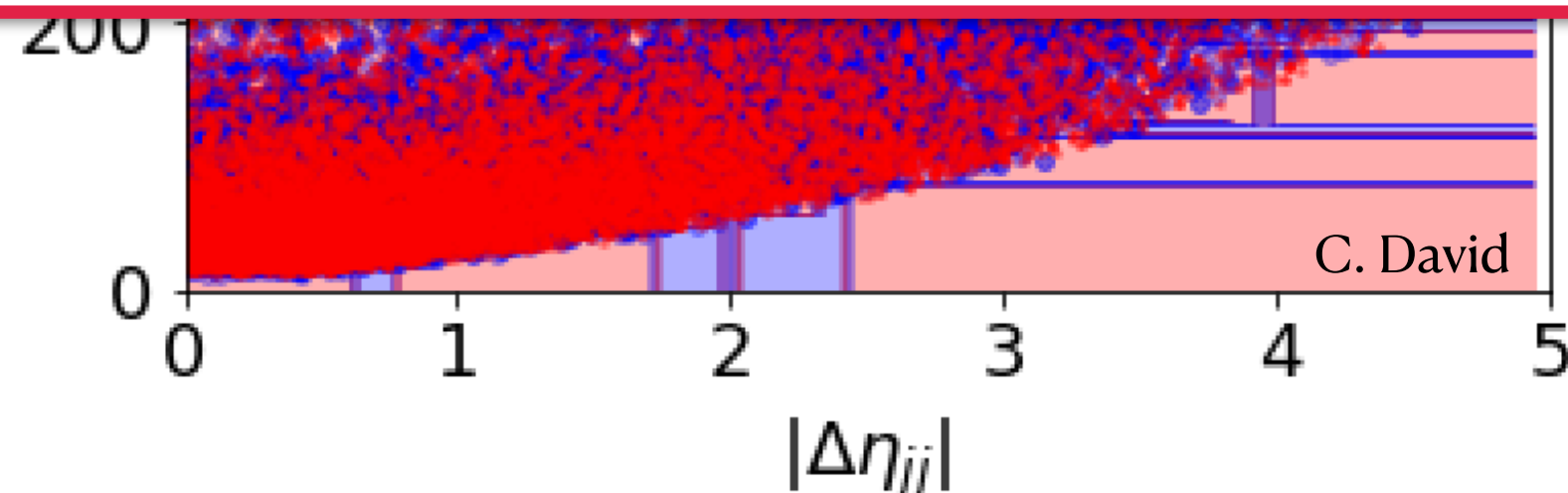
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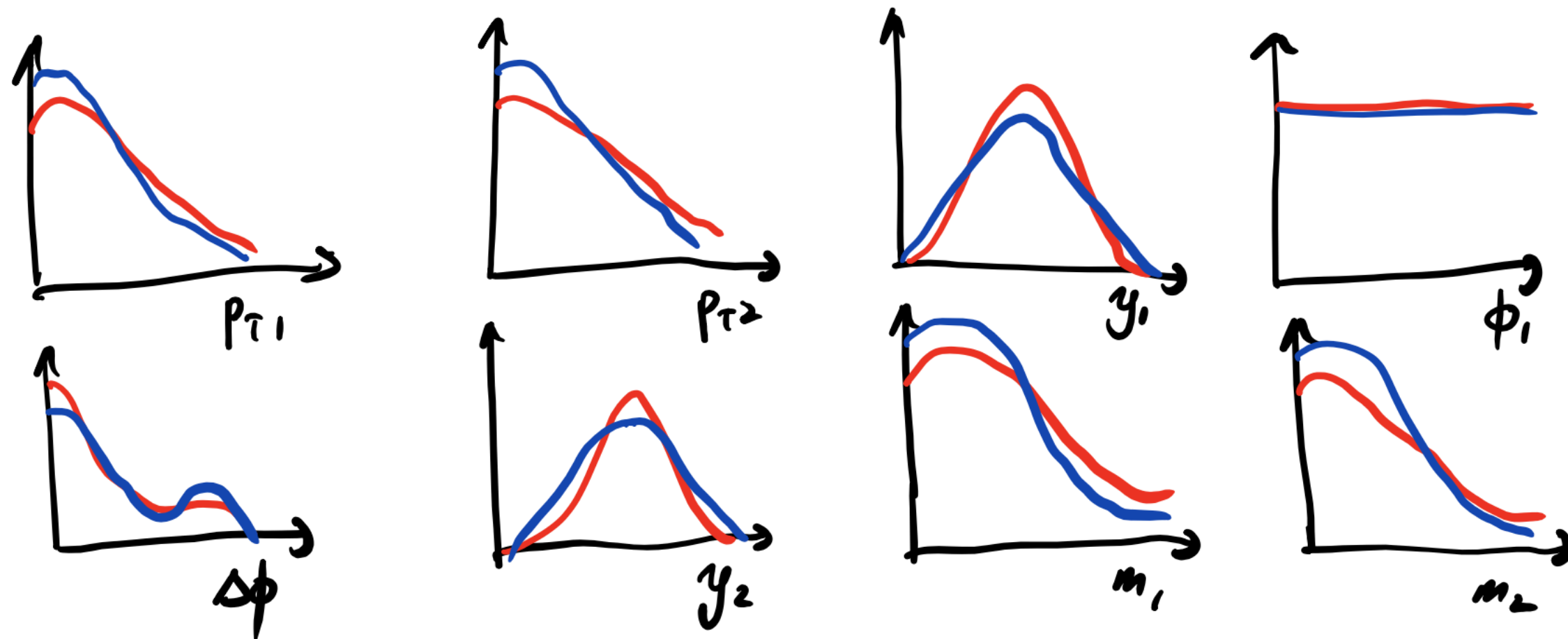
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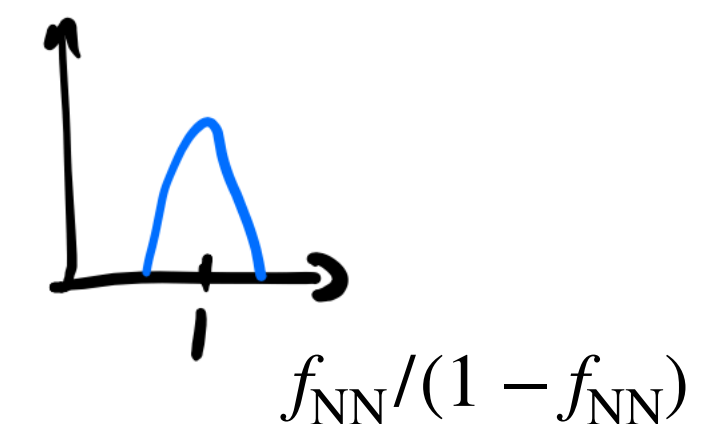
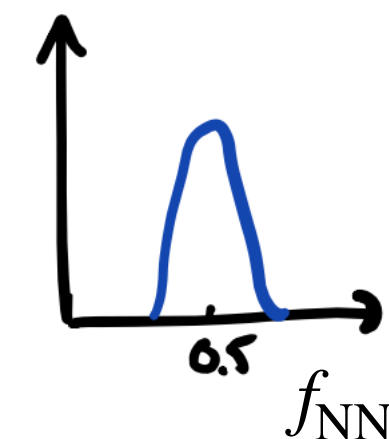
Using ML to reweight event samples

- Consider two MC samples of the same process
 - One **fancy MC** that takes a lot of computer resources (**‘signal’**)
 - One **simple MC**, that is very fast to generate **‘background’**
- Next, we train a ML to separate the two using, say 8 input variables $\vec{x} = (x_1, \dots, x_8)$



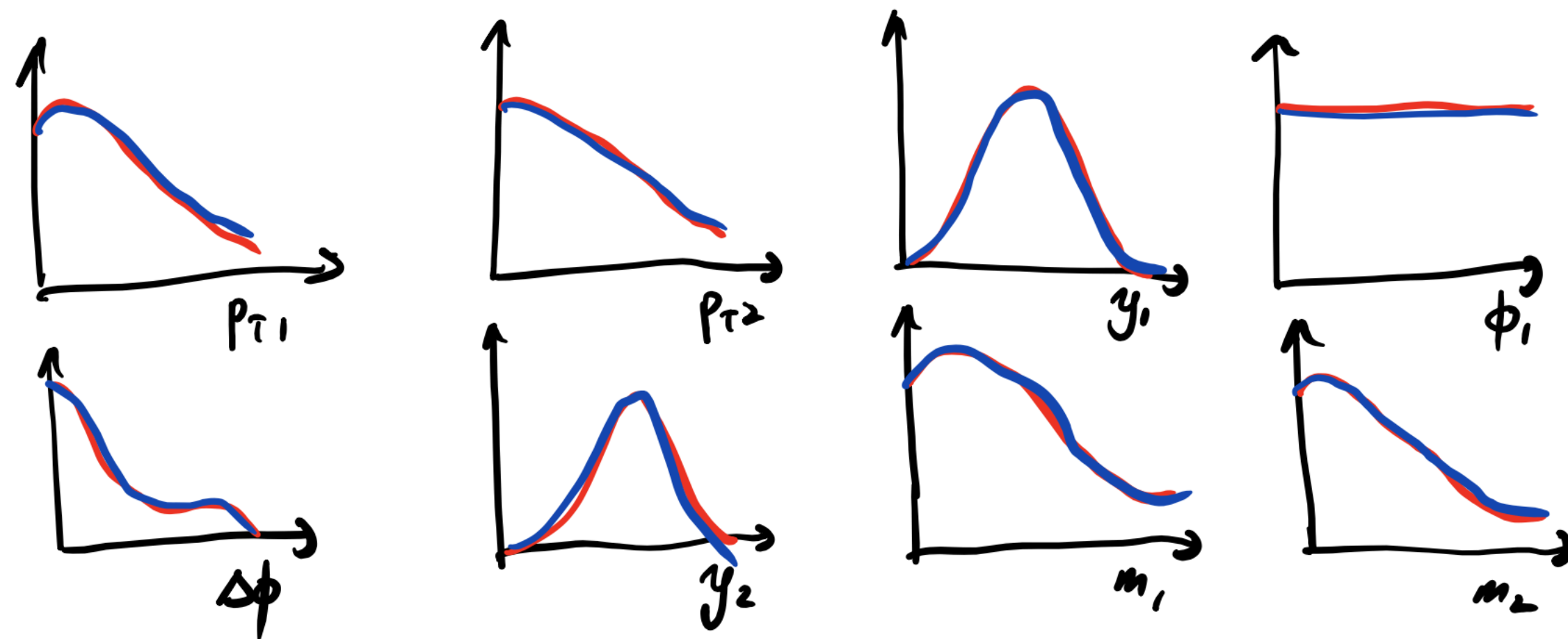
A neural network trained with cross entropy as loss function will return $f_{\text{NN}}(\vec{x})$, that estimates the purity. An estimate of the likelihood ratio is given by

$$\hat{\lambda}(\vec{x}) = \frac{f_{\text{NN}}(\vec{x})}{1 - f_{\text{NN}}(\vec{x})}$$



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$$\hat{\lambda}(\vec{x}) = \frac{f_{\text{NN}}(\vec{x})}{1 - f_{\text{NN}}(\vec{x})}$$

We can use this quantity as a per-event weight to the cheap MC to make it agree with the fancy one!

$$w(\vec{x}) = f_{\text{NN}}(\vec{x}) / 1 - f_{\text{NN}}(\vec{x})$$

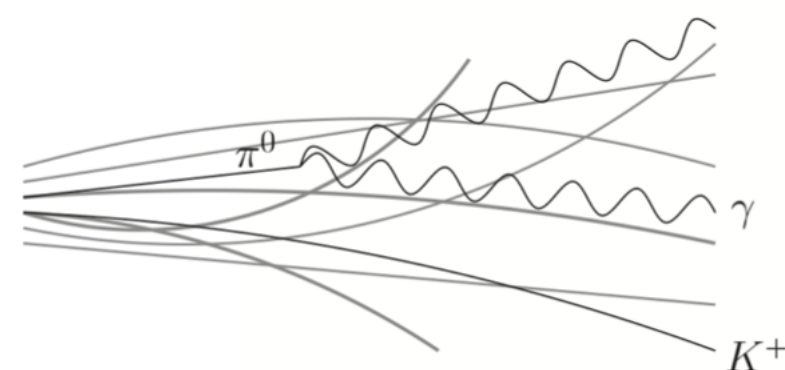
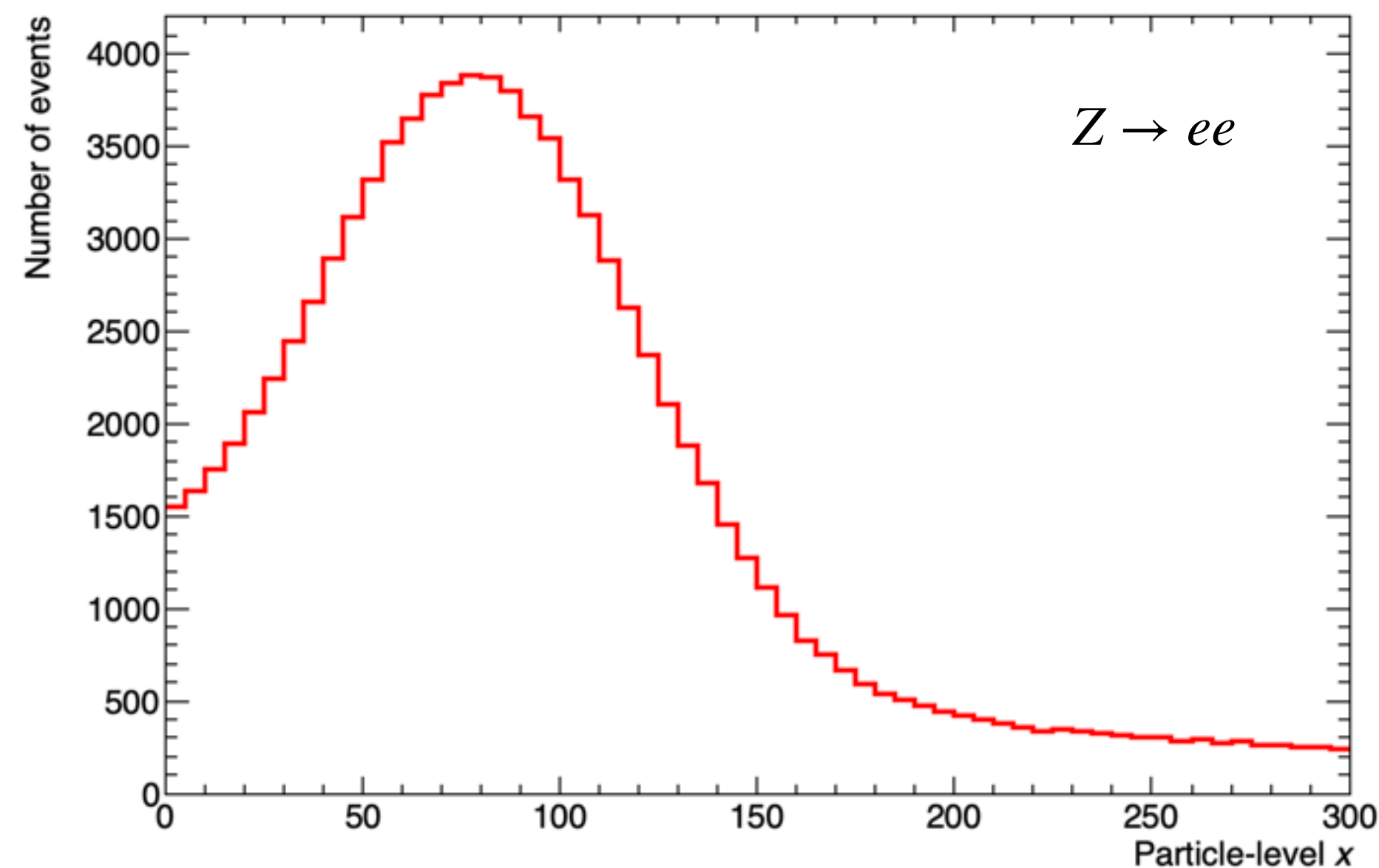
The NN \rightarrow an 8-dimensional reweighting function

Using ML to weight events

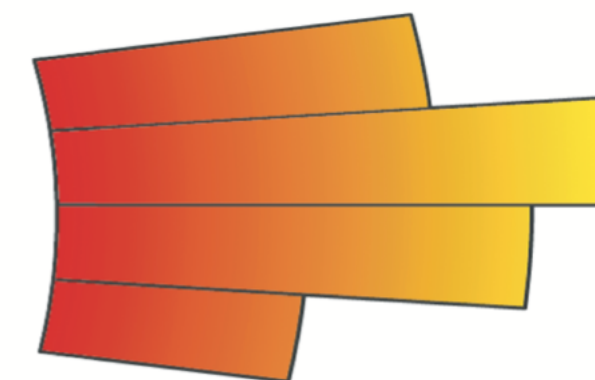
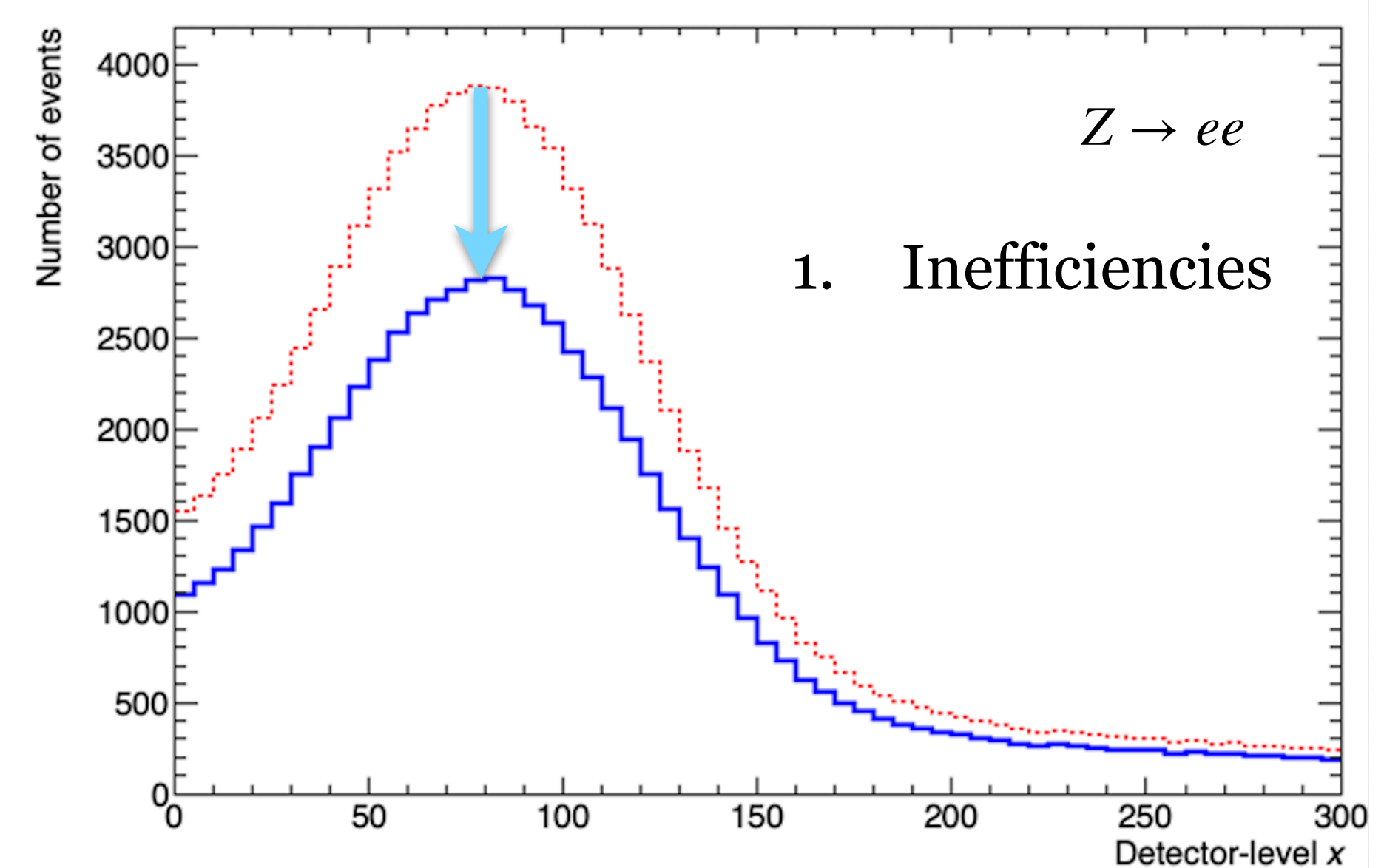
- Using ML classification to estimate the likelihood ratio, and use this as a weighting function has many relevant applications
- Early use/adoption were done by researchers at LHCb in 2015
 - In other fields ‘density ratio estimation’ has been used earlier.
- A few examples of applications in particle physics:
 - Neural networks for full phase-space reweighting and parameter tuning
<https://arxiv.org/abs/1907.08209>
 - Neural resample for MC reweighting and uncertainty preservation
<https://arxiv.org/abs/2007.11586>
 - Omnifold method to perform unfolded precision measurements ...

The Omnifold method

- The Omnifold method uses ML to perform unbinned, high-dimensional measurements
- This includes unfolding to the particle-level

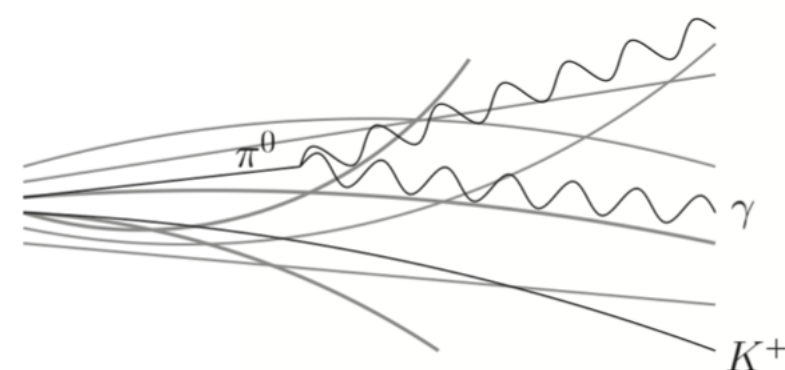
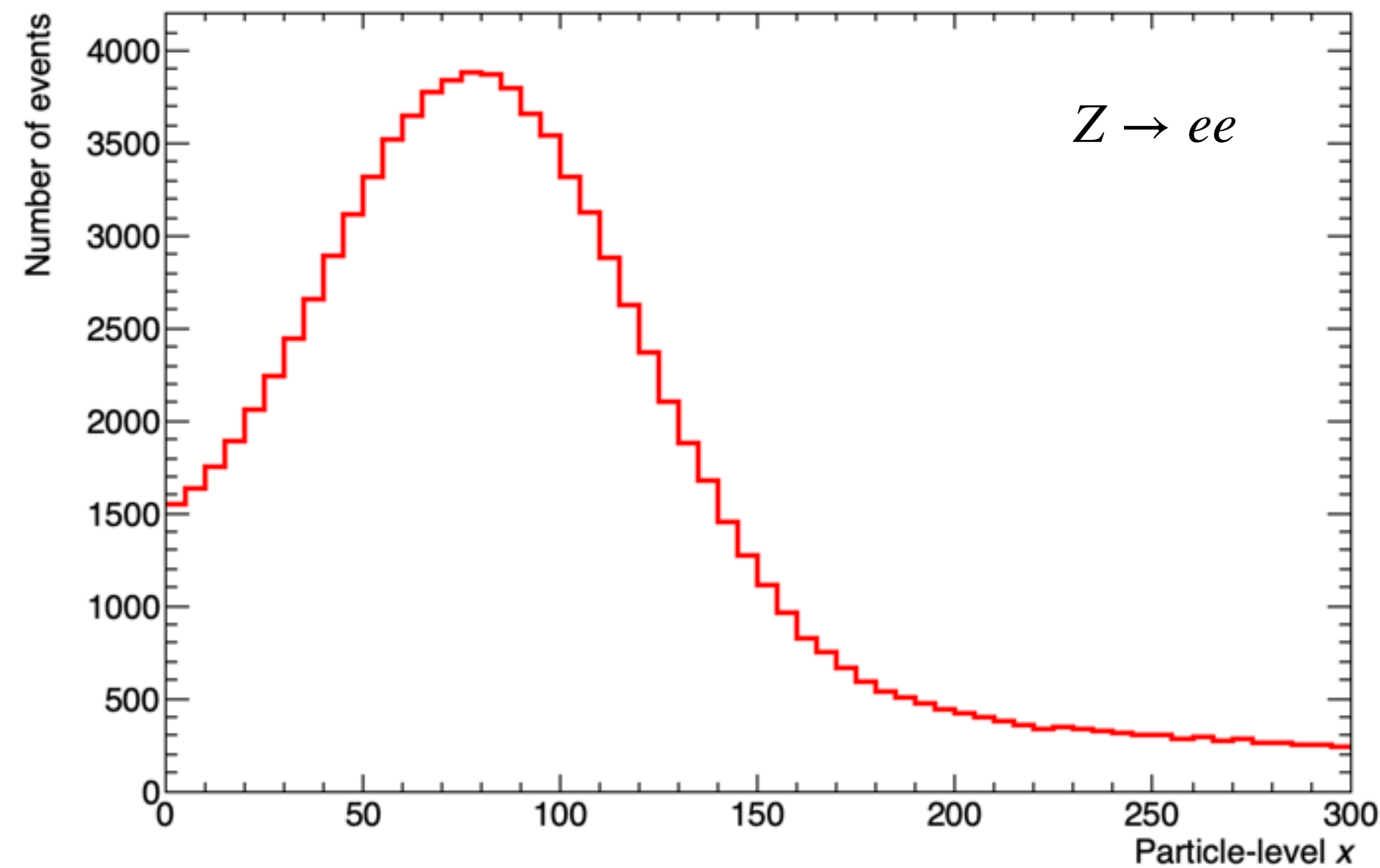


Interaction with the detector, two major effects

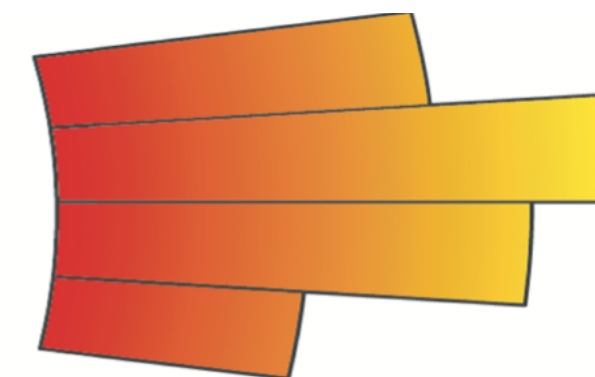
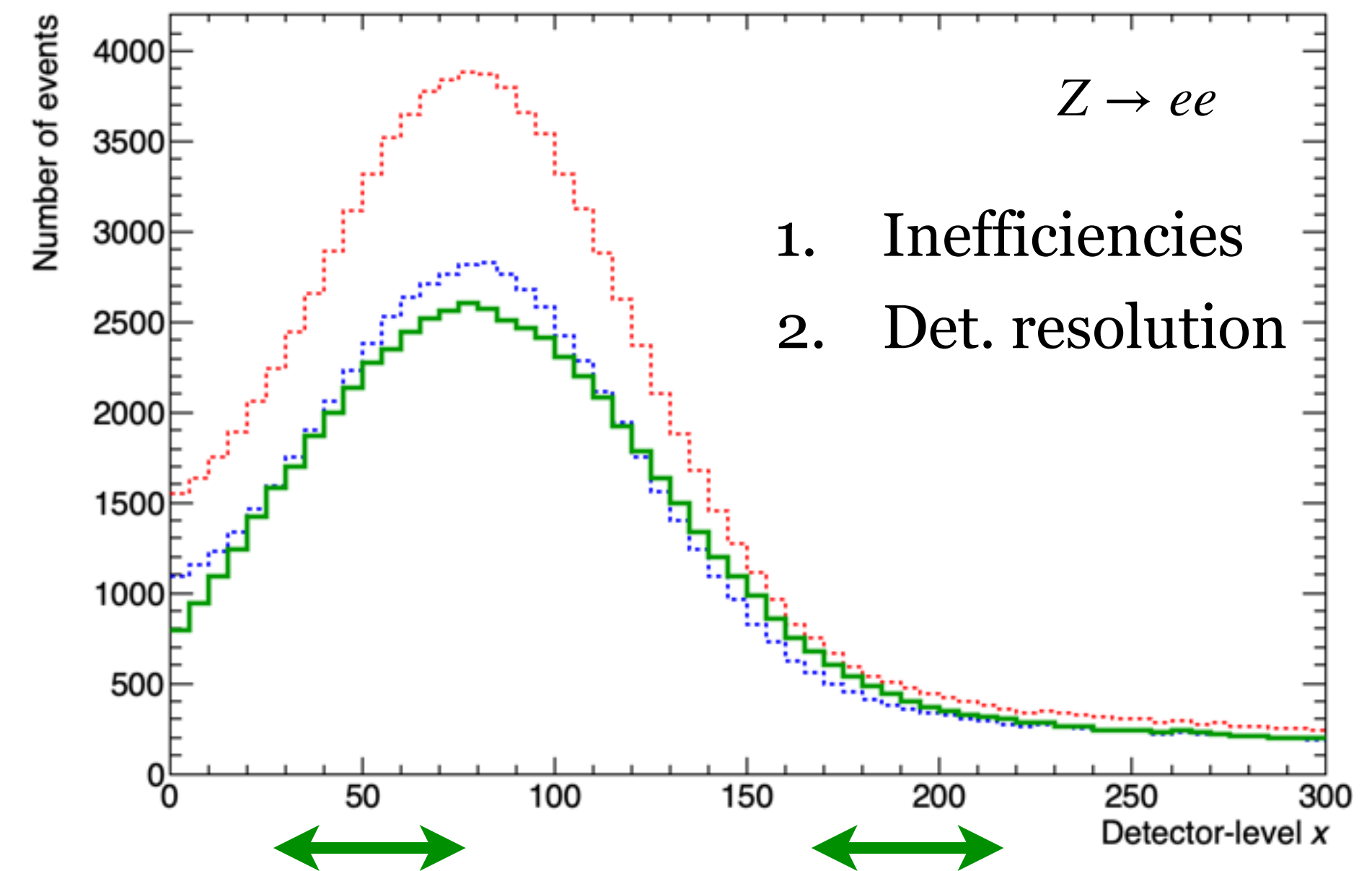


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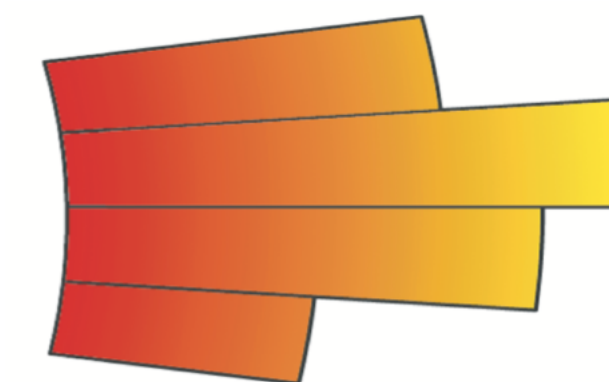
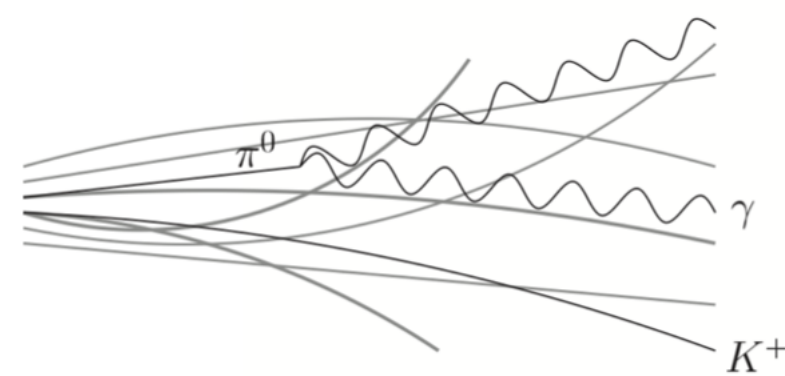
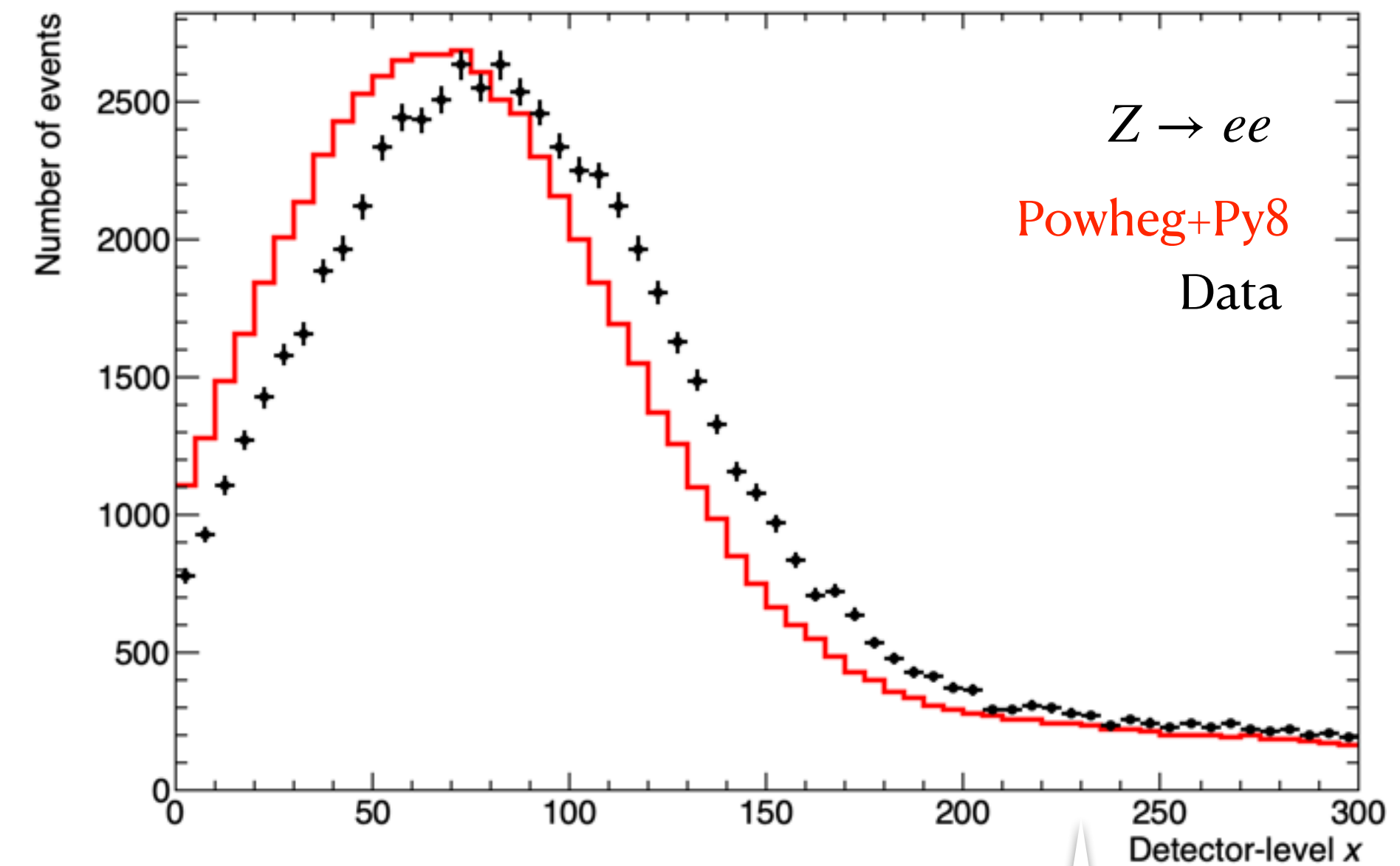
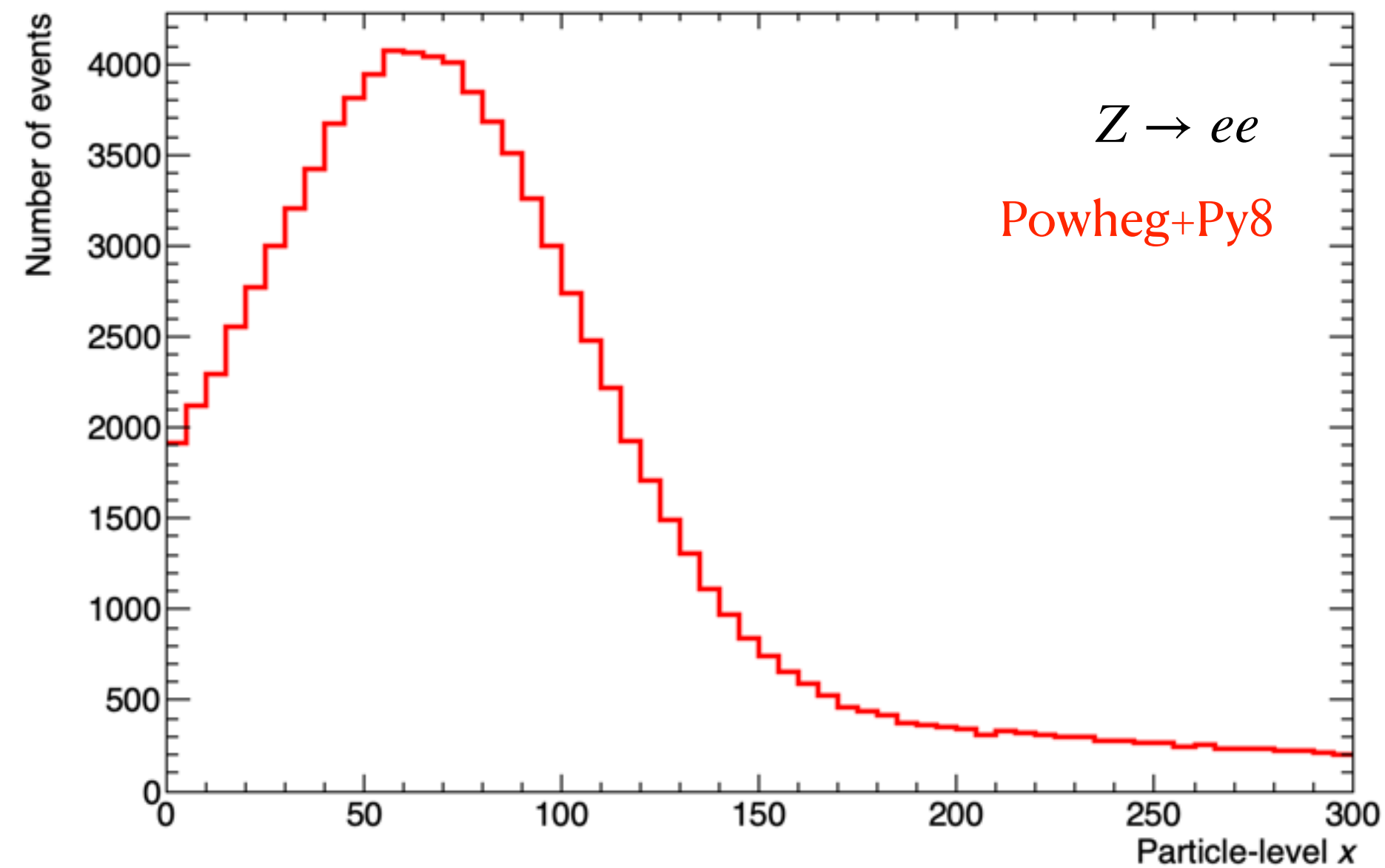
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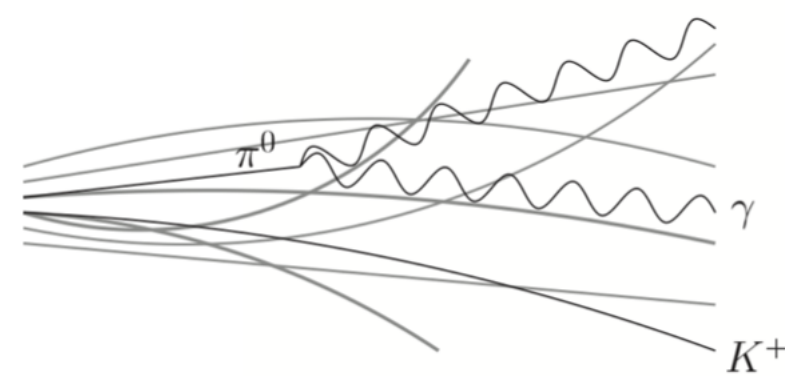
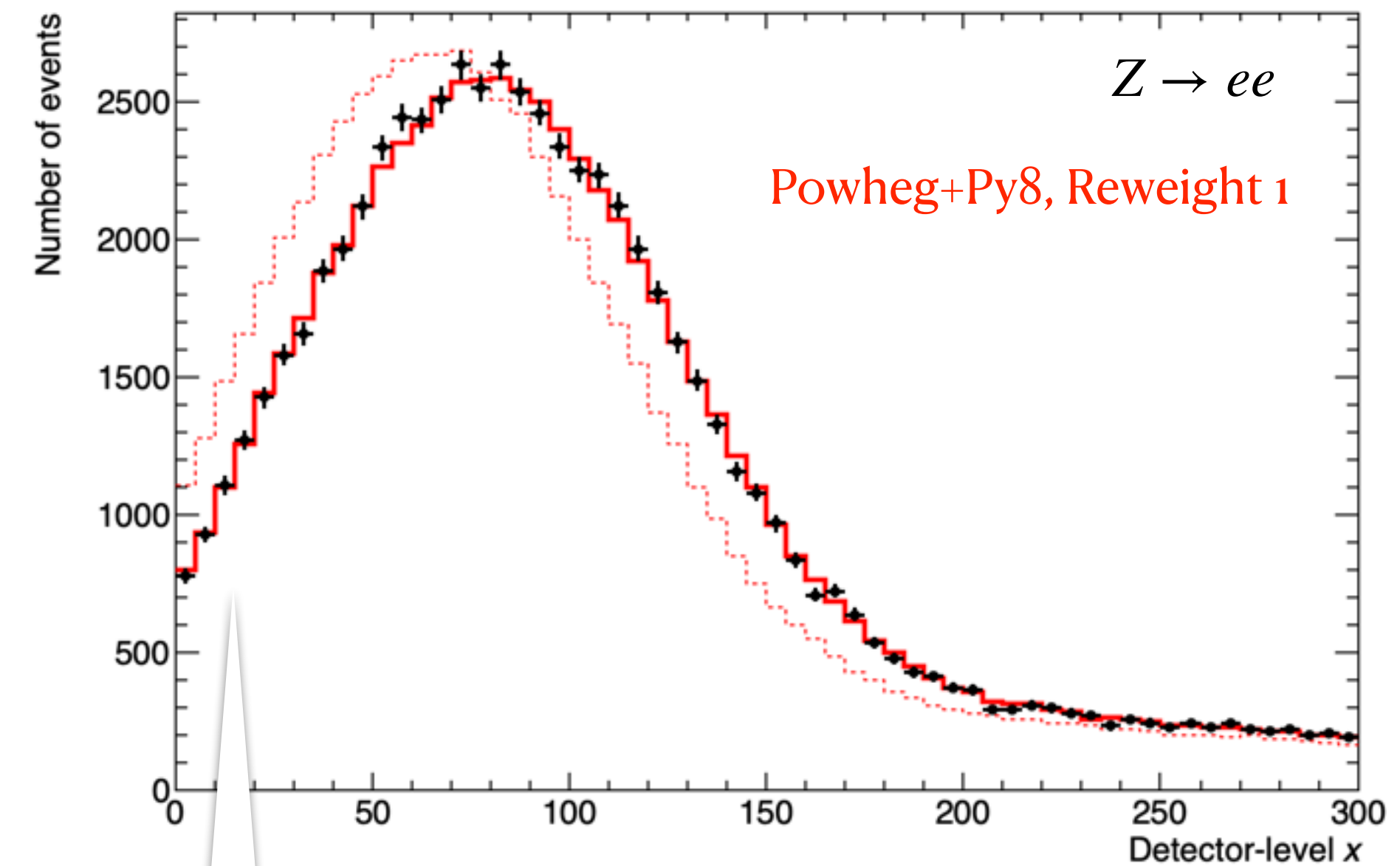
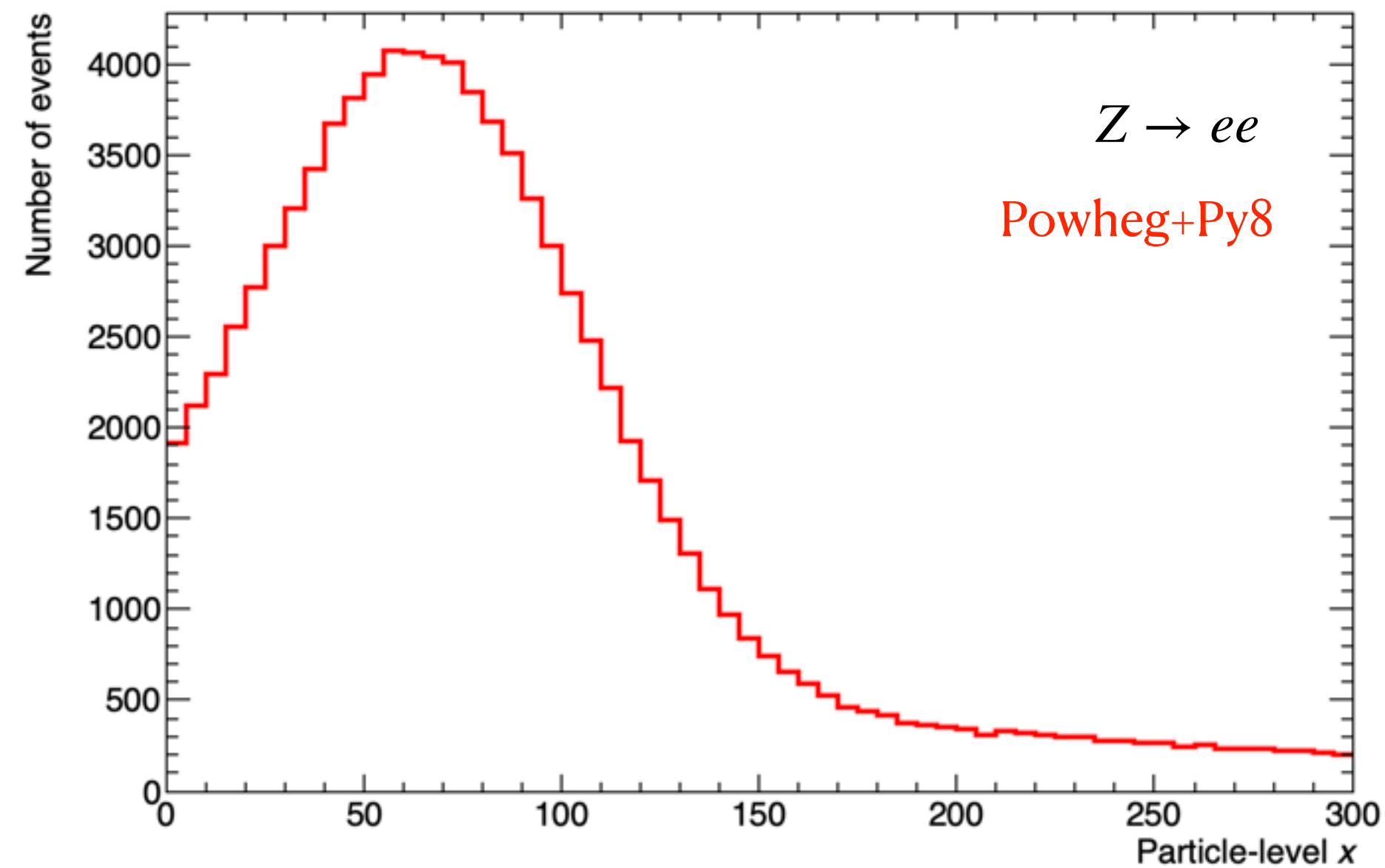


1. Train NN with data as signal, MC bkg
Use to reweight!

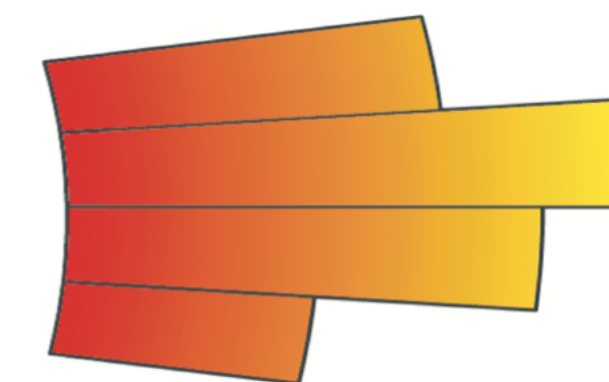
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2. Each simulated event has obtained a weight. Propagate this to the particle level distribution

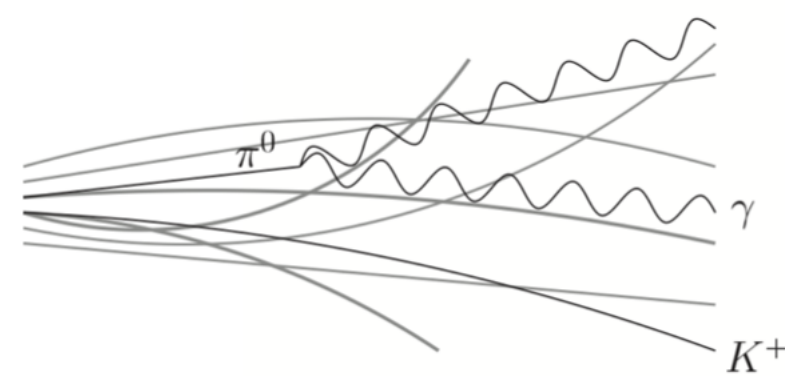
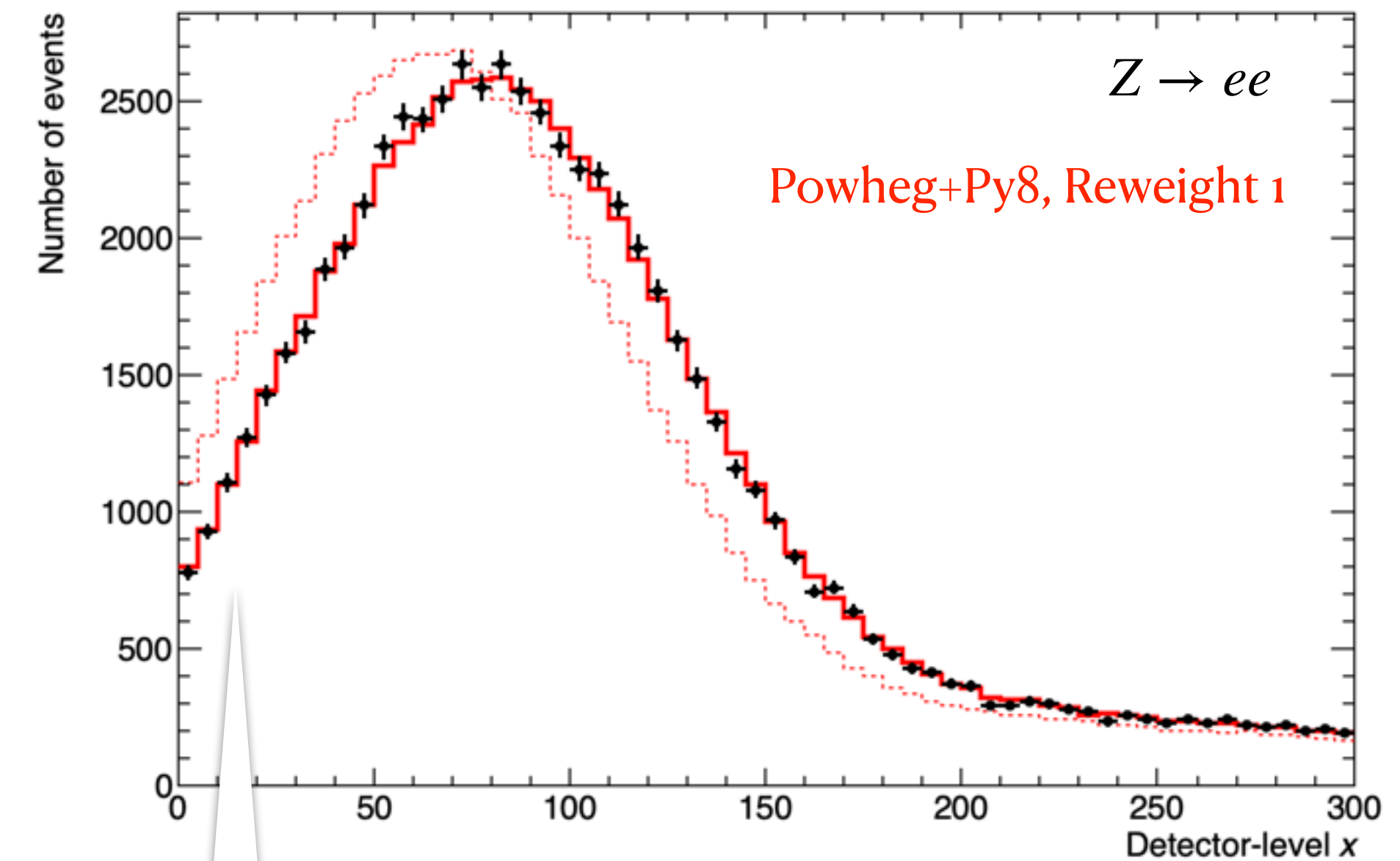
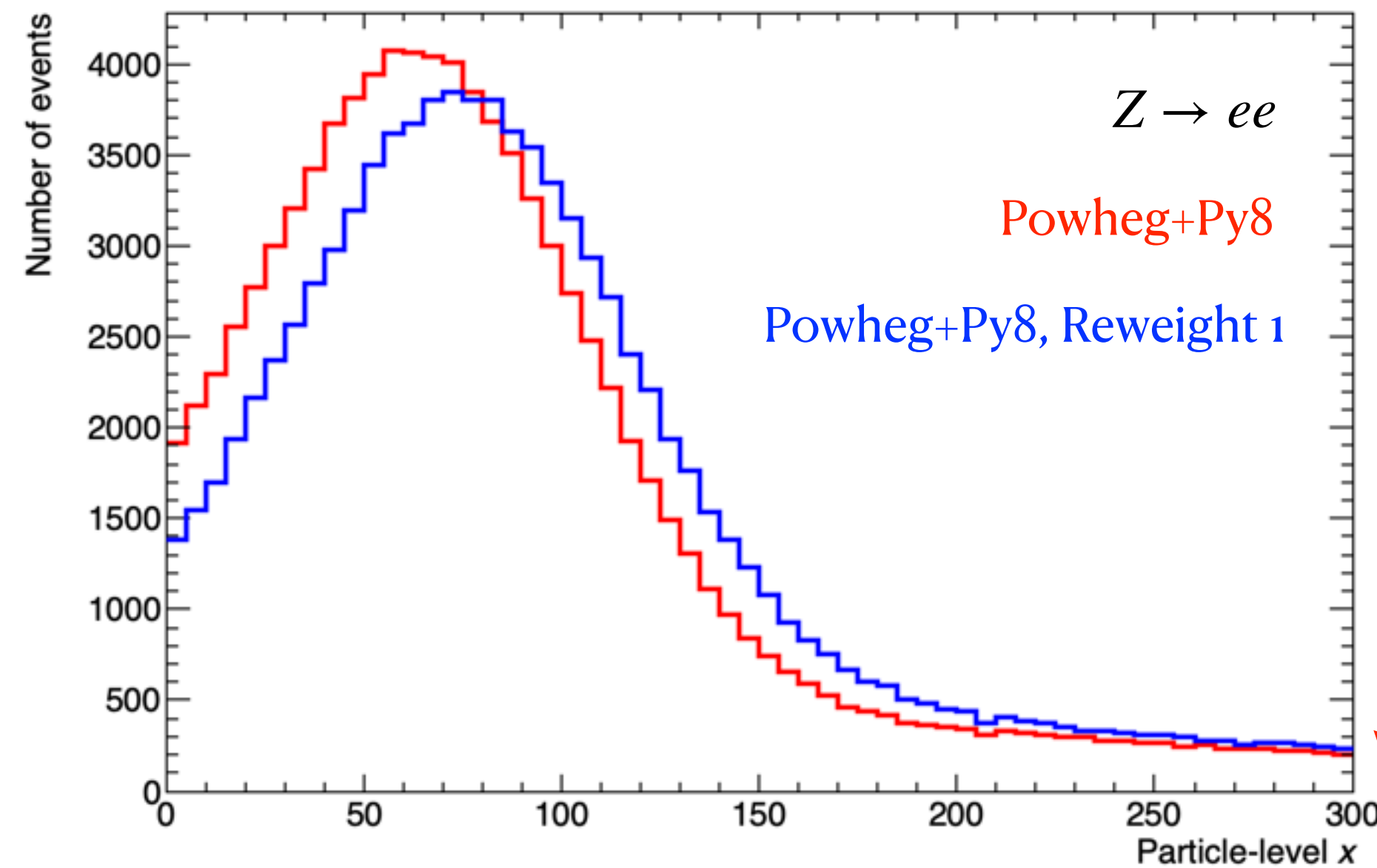


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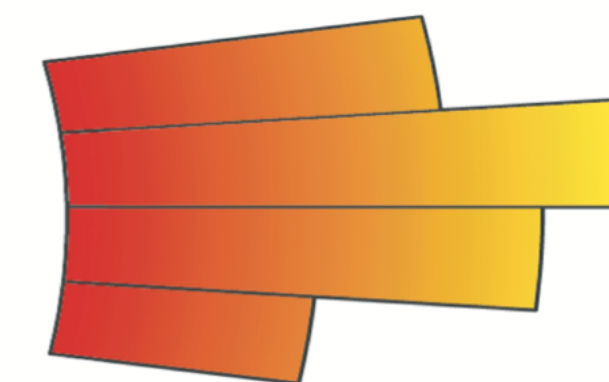
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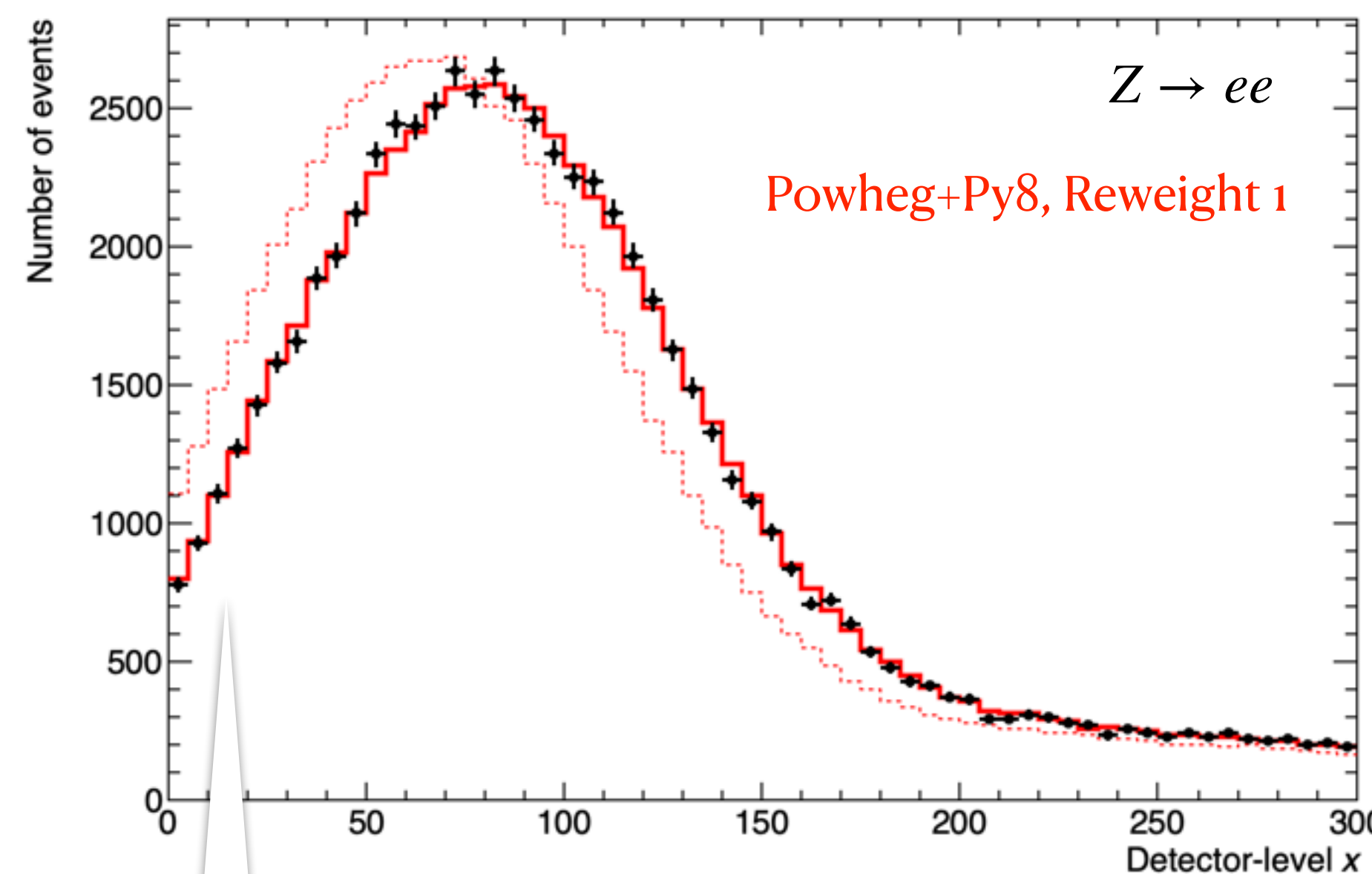
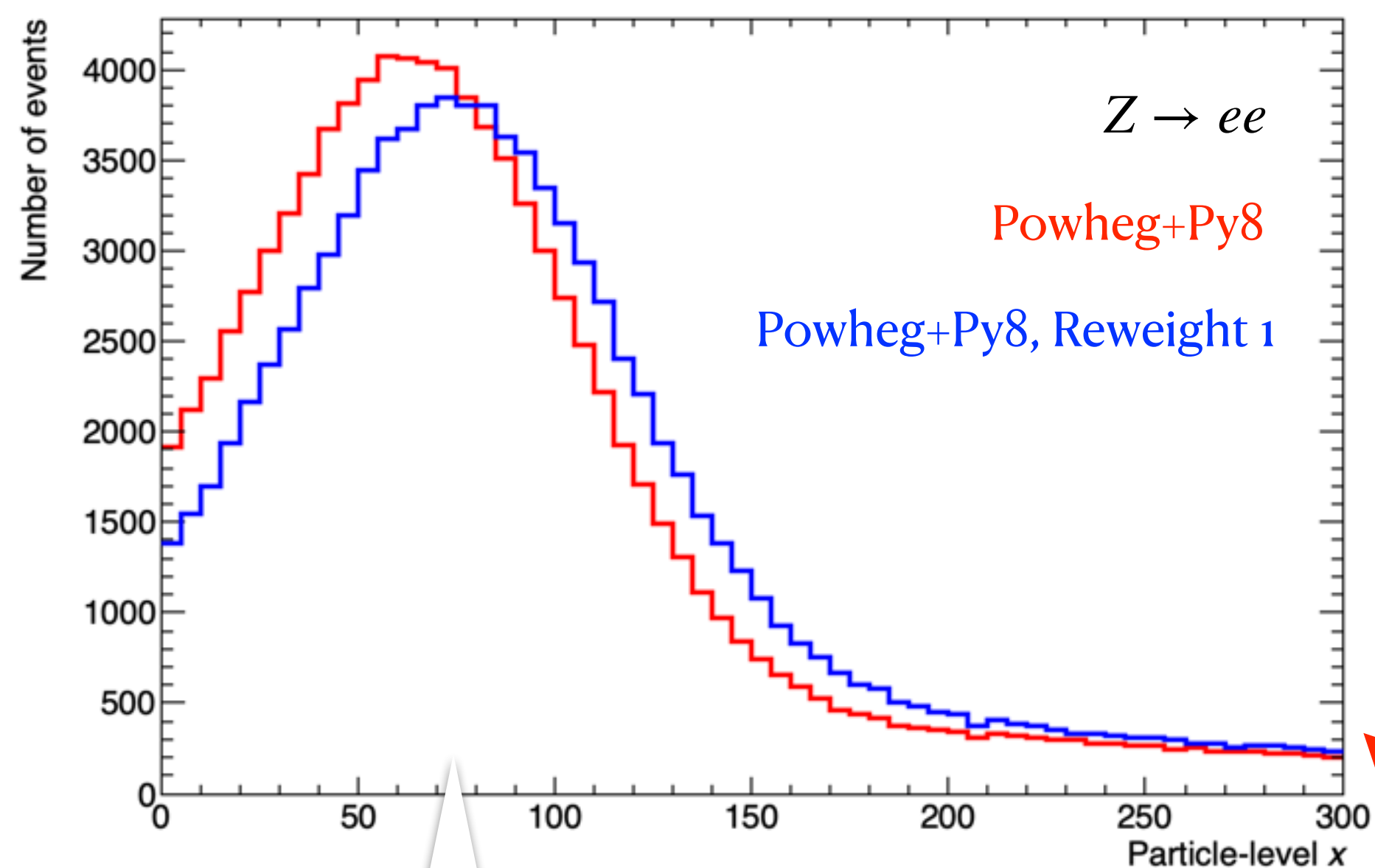
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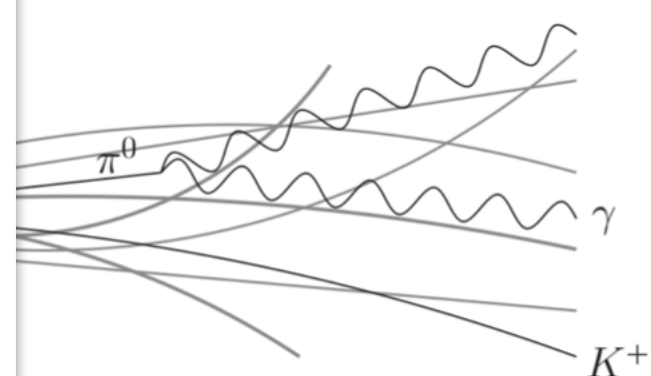
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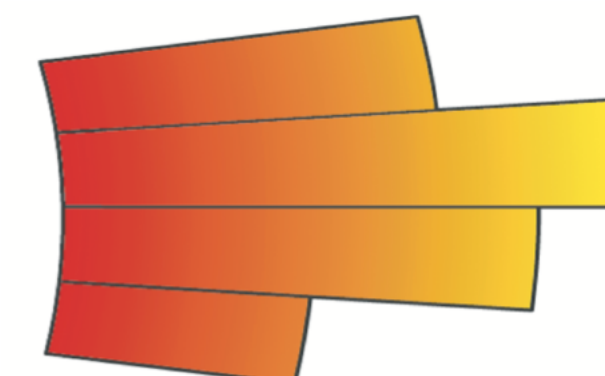
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3. Train a new network using blue as signal, red background (MC-MC). Use to reweight red!



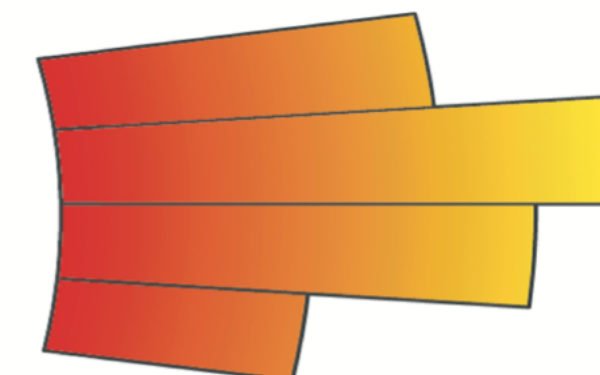
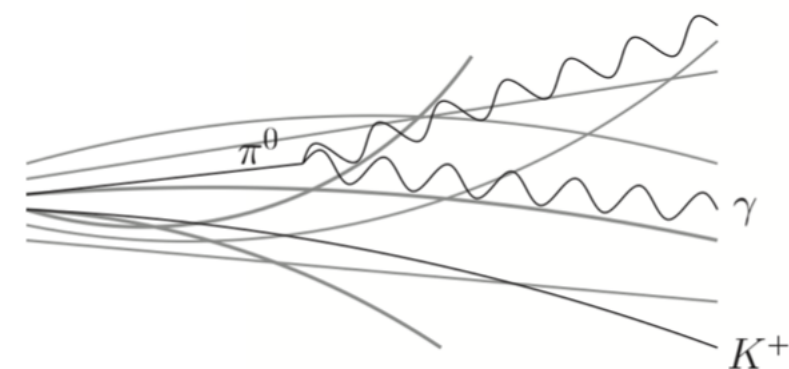
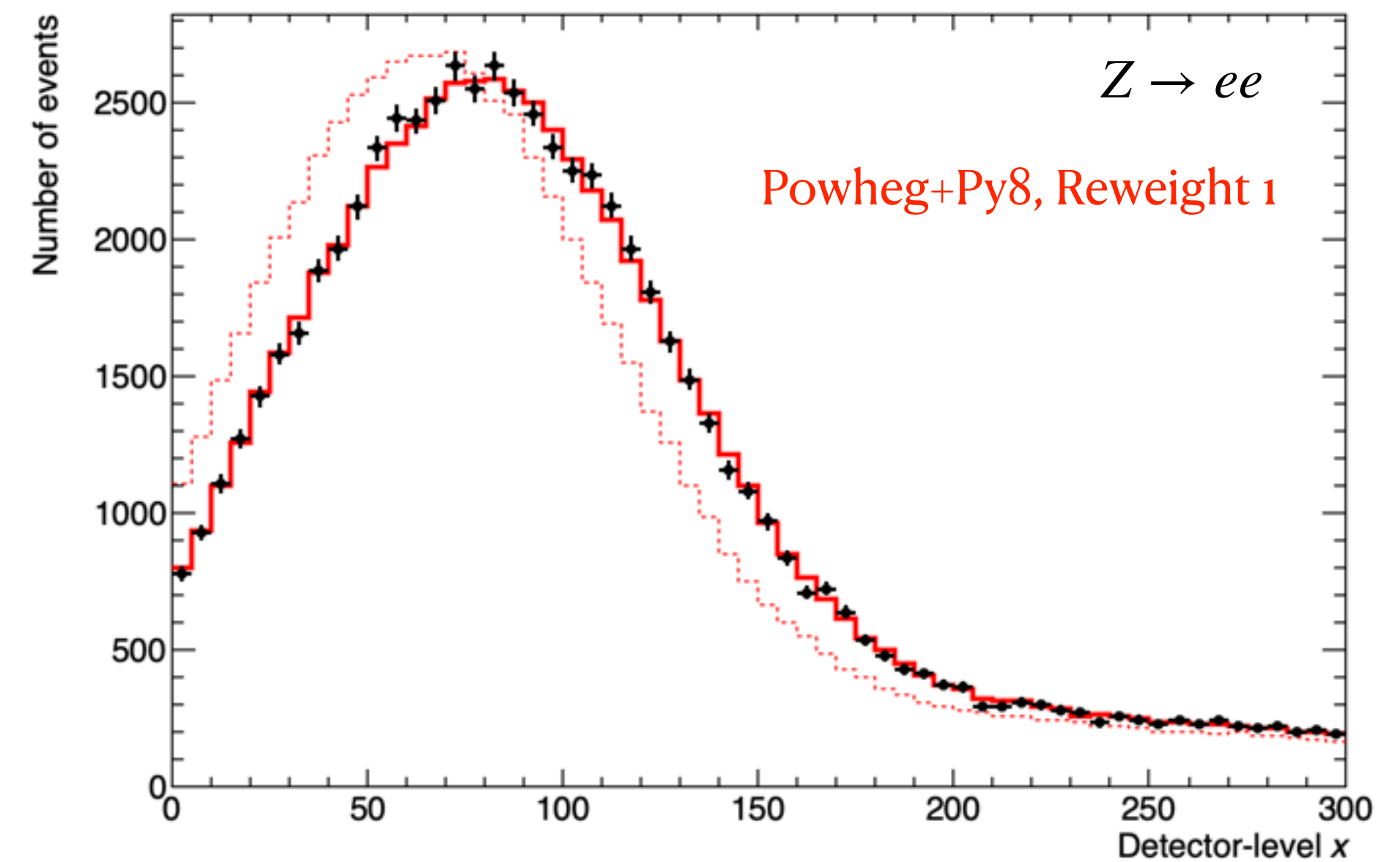
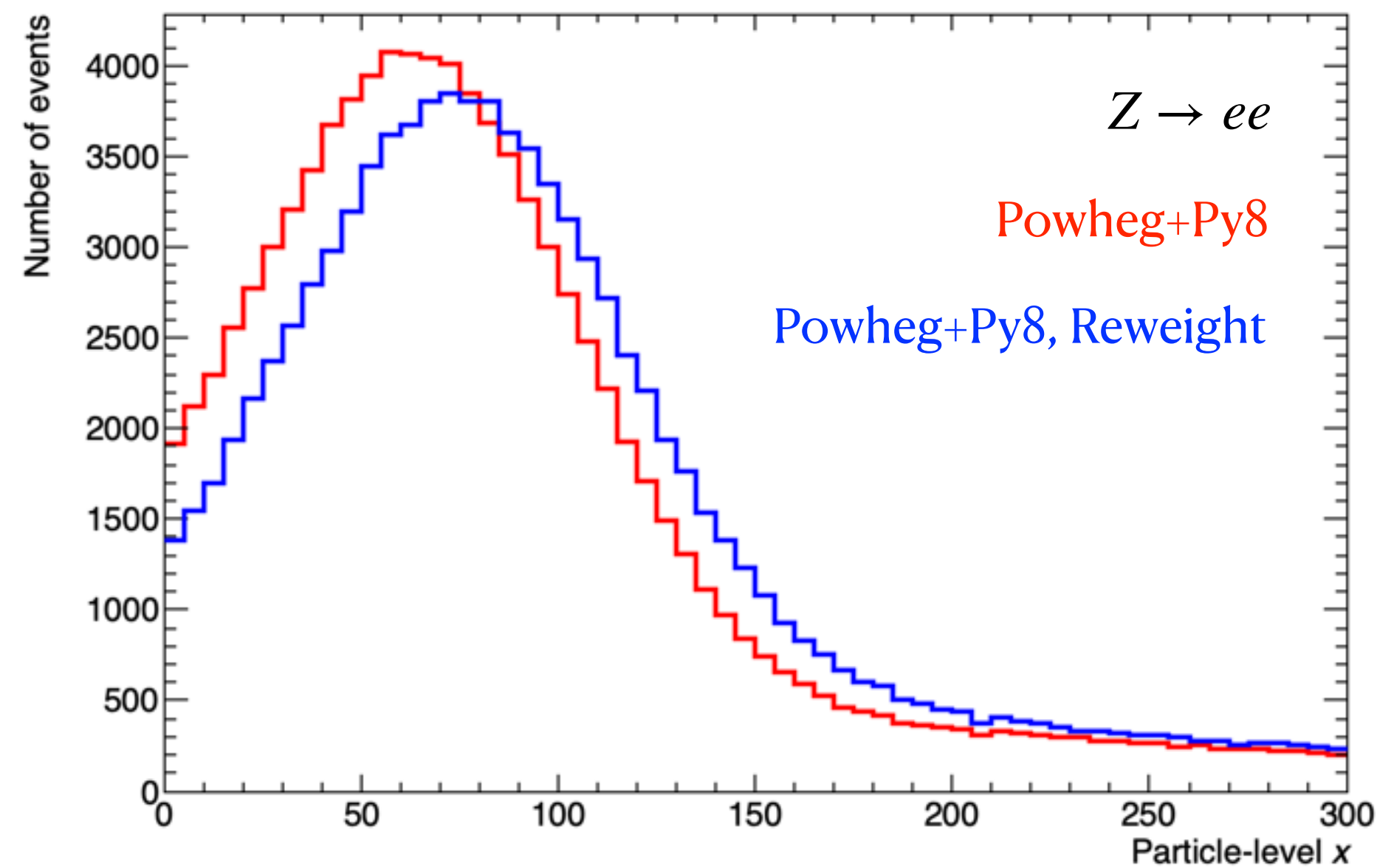
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The Omnifold method

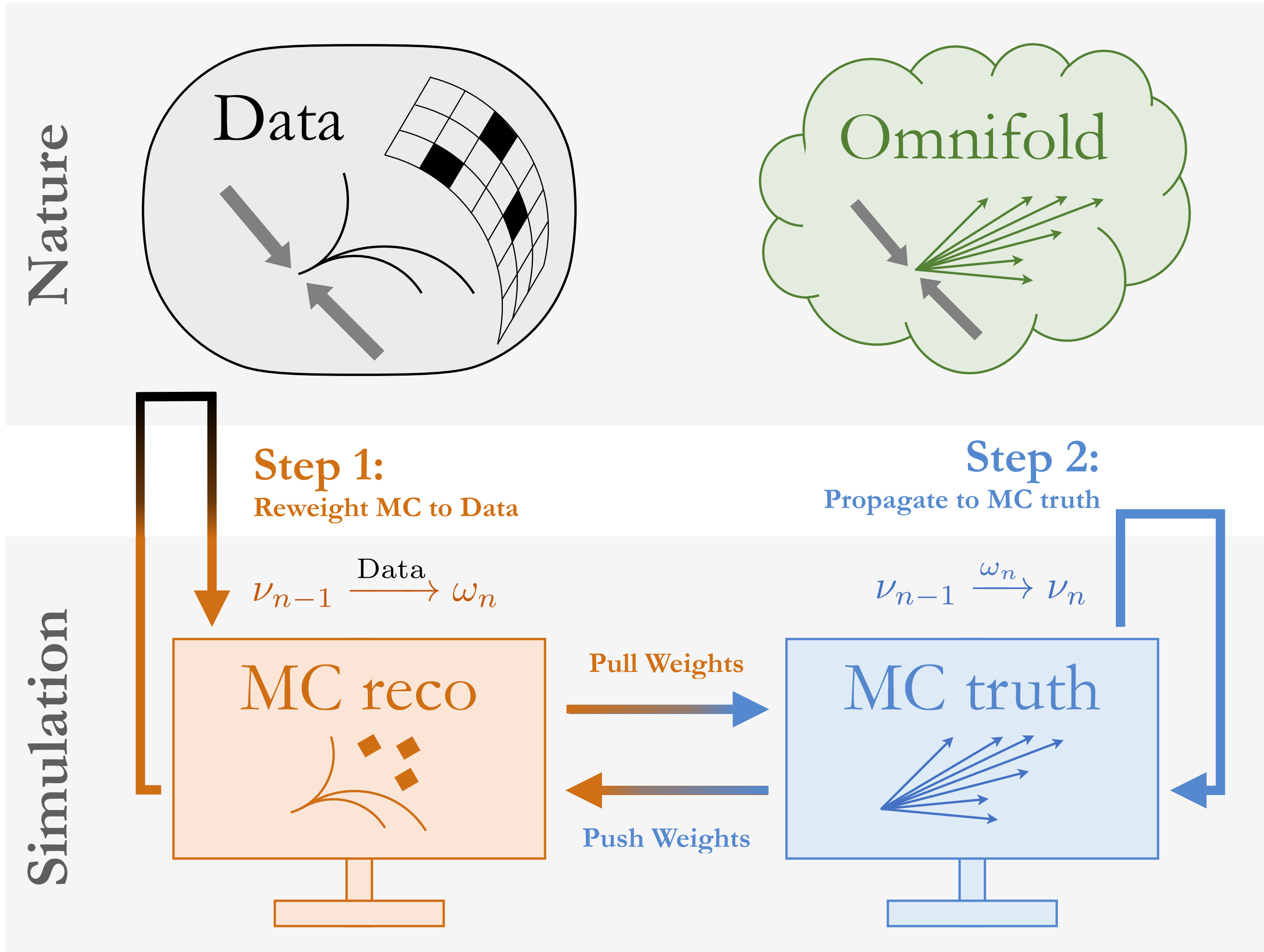
- This method interactively reweights distributions:
 - Match data, then update prior (particle-level distribution)
- Stable solution found after a few iterations (typically 2-5)
- Identical to Iterative Bayesian Unfolding when binned input is used



The Omnifold method

Detector-level

Particle-level



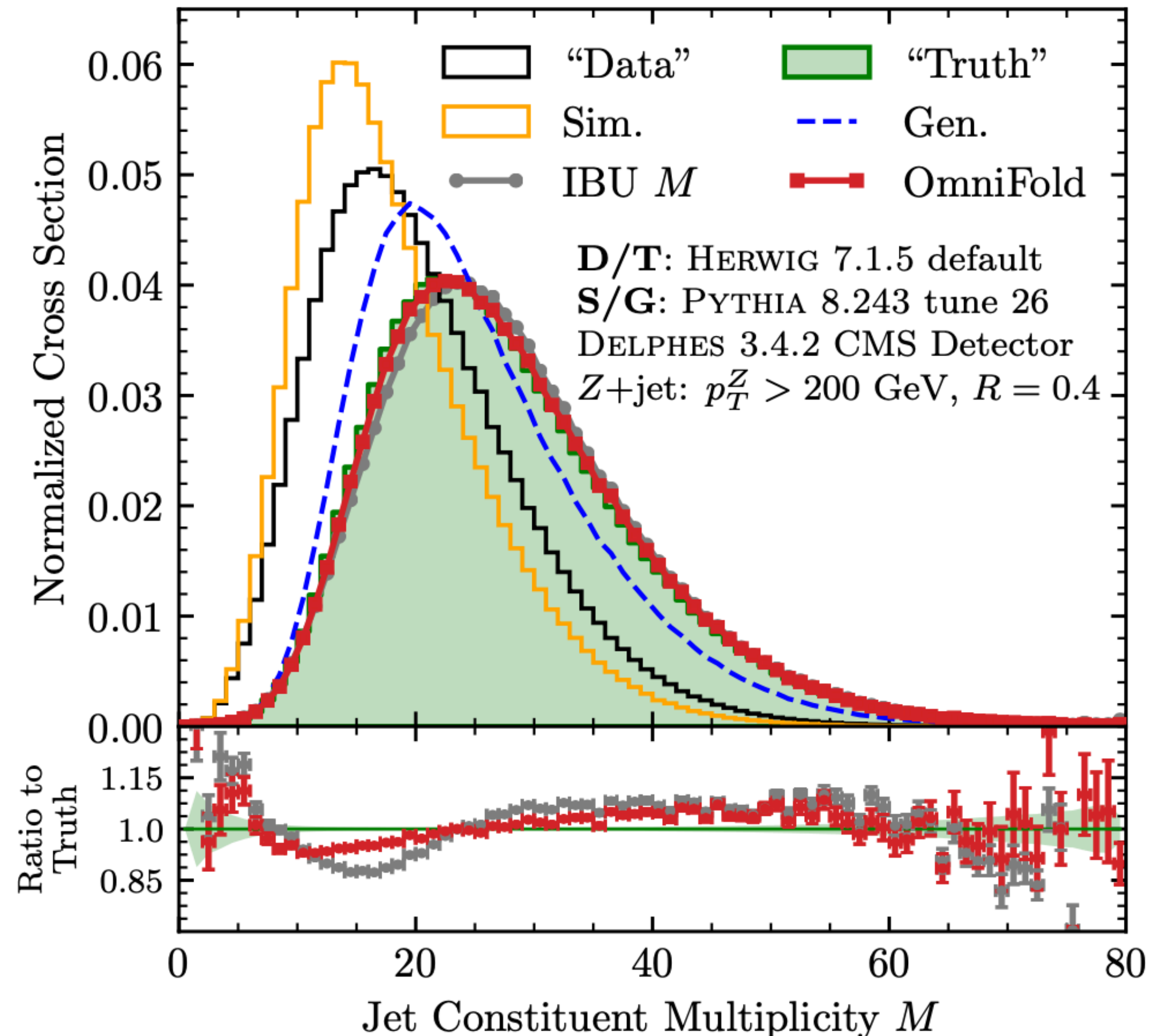
Adjust MC reco to match data
 $\rightarrow \omega_{\text{NN}}(\vec{x}_{\text{reco}})$
Propagate to particle-level
Adjust particle-level to match
this change $\rightarrow \nu_{\text{NN}}(\vec{x})$
Propagate to reco level
Repeat

The Omnifold method

- Method announced 2020 with proof-of-principle results based on simulation

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- The output is a weighing function that applies to simulated events (e.g. Powheg+Pythia)
- The function takes only particle-level quantities as input (no need for detector simulation)
- Weighing MC events makes them ‘become unfolded data’

Output of unbinned measurements

Publishing unbinned differential cross section results

Miguel Arratia^{1,2}, Anja Butter³, Mario Campanelli⁴, Vincent Croft⁵, Dag Gillberg⁶, Aishik Ghosh^{7,8},
Kristin Lohwasser⁹, Bogdan Malaescu¹⁰, Vinicius Mikuni¹¹, Benjamin Nachman^{8,12}

- The measured data needs to be made public
- In principle, one could publish just the reweighing functions
 - however, requires that MC events are generated **exactly** in the same way as analysis
- Safer to provide MC events, with the associated weights
- Each event needs to contain
 - All features used in measurement \vec{x}
 - Nominal weight that adjust it (to become unfolded data) ν
 - A long list of additional weights corresponding to uncertainties
 - Data statistical uncertainty (we propose ~ 50)
 - MC statistics uncertainty (we propose ~ 25)
 - Systematic uncertainties ($\mathcal{O}(100)$)
- Alternative MC sample with all variables and MC stat weights

Statistical uncertainties
evaluated using bootstrapping

Systematic uncertainties evaluated
using established methods
(perturbation of input sample)

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- **Plan:** produce large n-tuple (several GB) with all weights and variables
 - Need to make it **public** on some site. Zendo is an option.
 - Should keep link from HepData (best if HepData would have capability)
 - Also need to keep providing associated Rivet routine
- Further need to provide **user guide**
 - Idea is to provide a Python notebook that shows how to produce results
 - E.g. how to loop over events to create histograms with all associated uncertainties
→ unfolded measurements
 - Basic stat. guidelines, e.g. choice of binning (not too narrow, can get empty bins)
 - Caveats and validity: need to be clear with which observables and applications have been validated

Flavours of Omnifold

- UNIFOLD
 - Measure only one variable at the time.
 - Unbinned version of Iterative Bayesian Unfolding
- MULTIFOLD
 - Measure a fixed set of variables simultaneously and unbinned
 - E.g. $p_T^{\ell 1}, p_T^{\ell 2}, \eta^{\ell 2}, \eta^{\ell 1}, p_T^{j 1}, p_T^{j 2}$
 - Note that you can construct measurements of other observables afterwards.
E.g. $\Delta\eta_{\ell\ell} = \eta^{\ell 1} - \eta^{\ell 2}$
- (Full) OMNIFOLD
 - Measure a variable-length set of variables (simultaneously and unbinned)
 - For example, the momenta (p_T, η, ϕ) of all charged particles in an event
(One event might have 50 charged particles, another 150)

Full Omnifold

- Procedure is the same, i.e. reweight by $f(\vec{x}) / (1 - f(\vec{x}))$, just the length of \vec{x} varies from event to event
- Possible with particle flow networks

Energy Flow Networks: Deep Sets for Particle Jets

Patrick T. Komiske, Eric M. Metodiev, Jesse Thaler

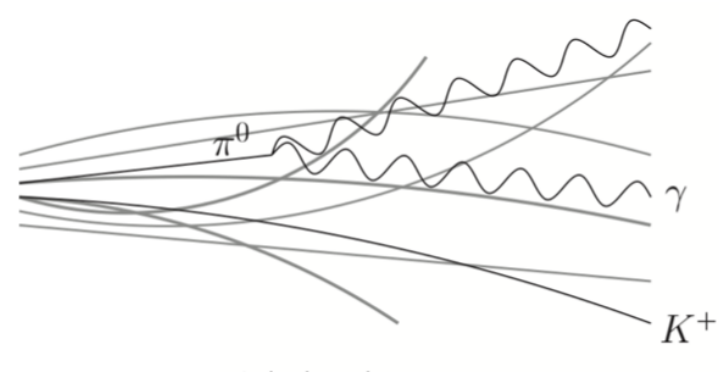
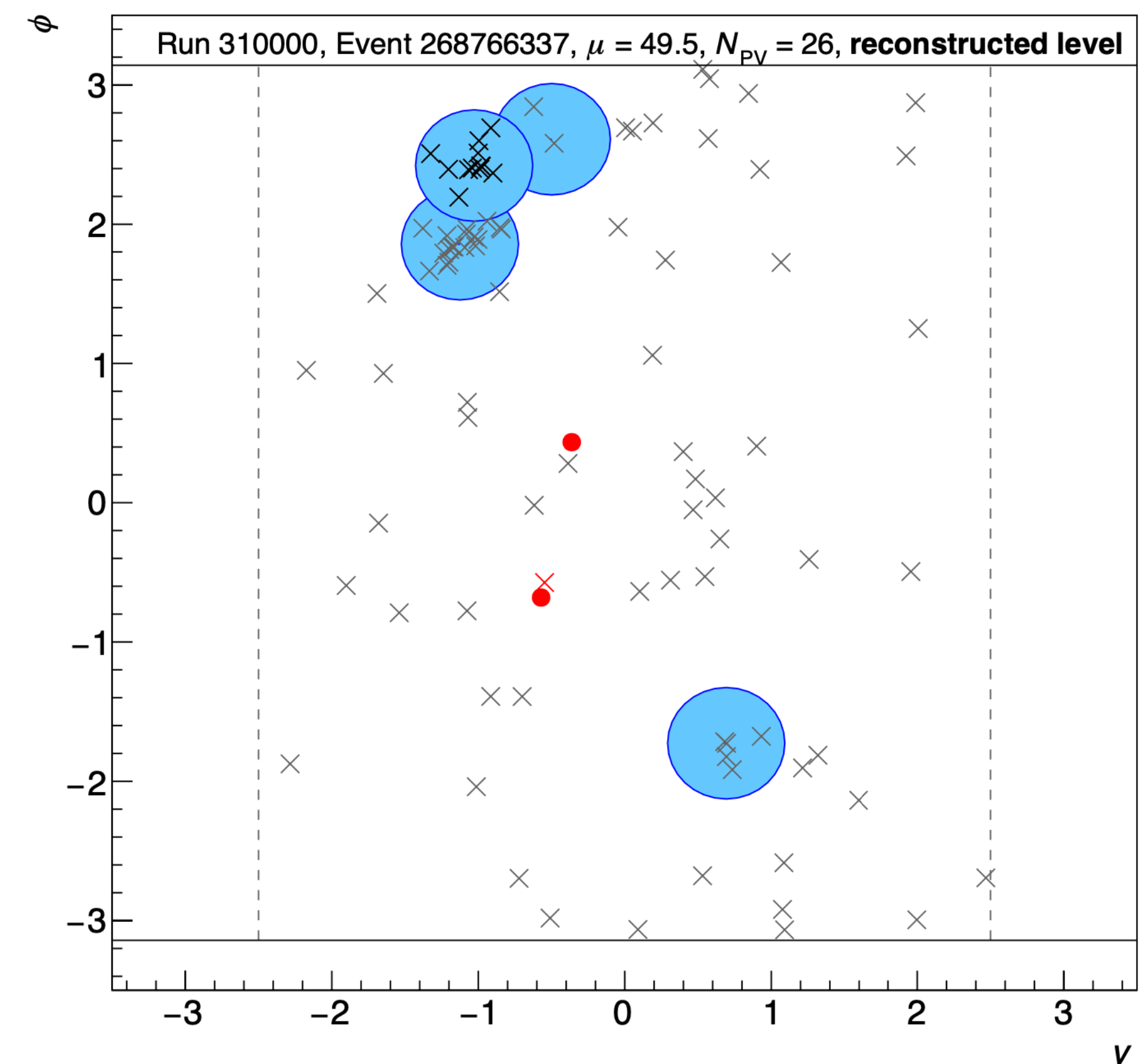
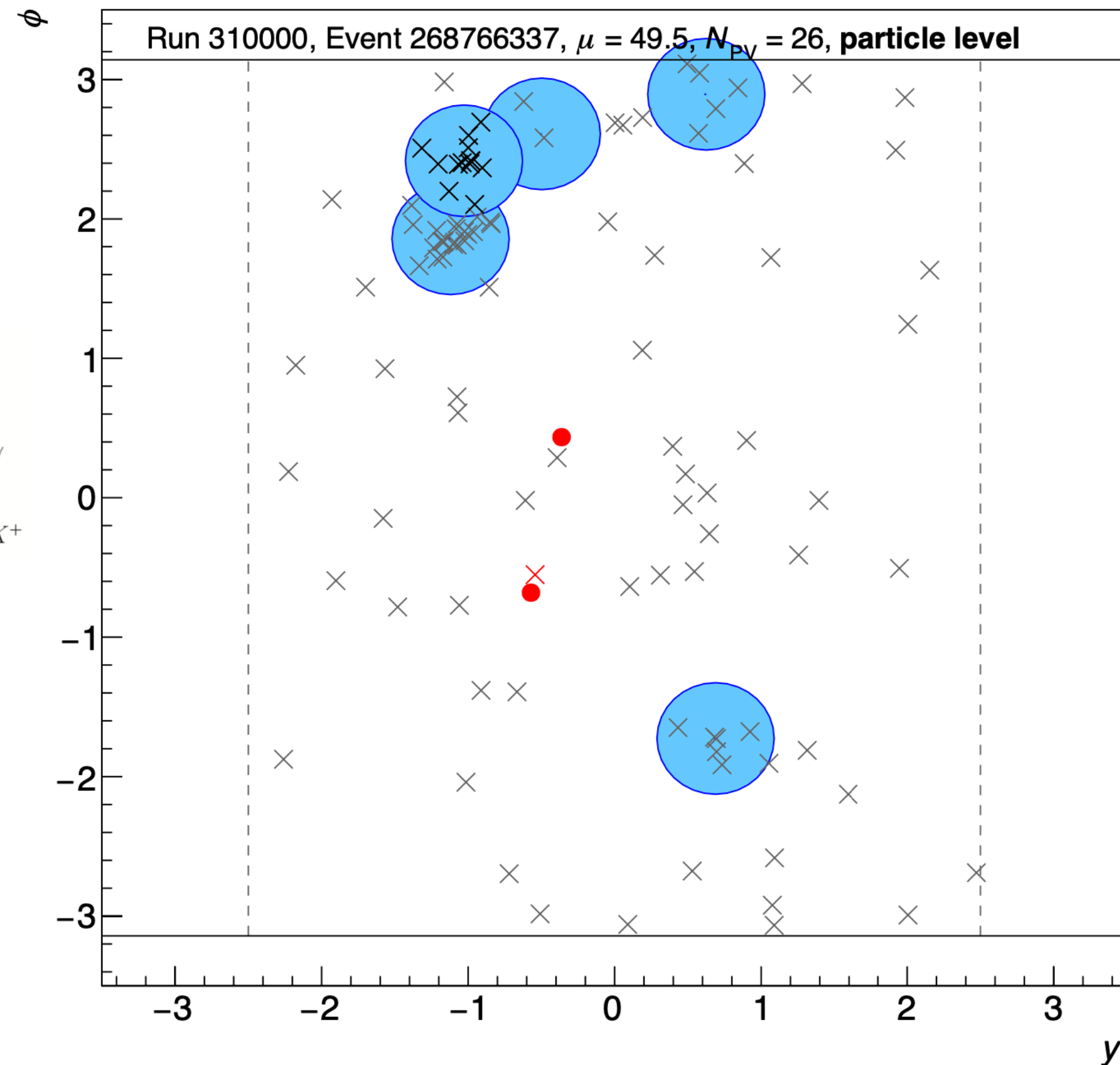
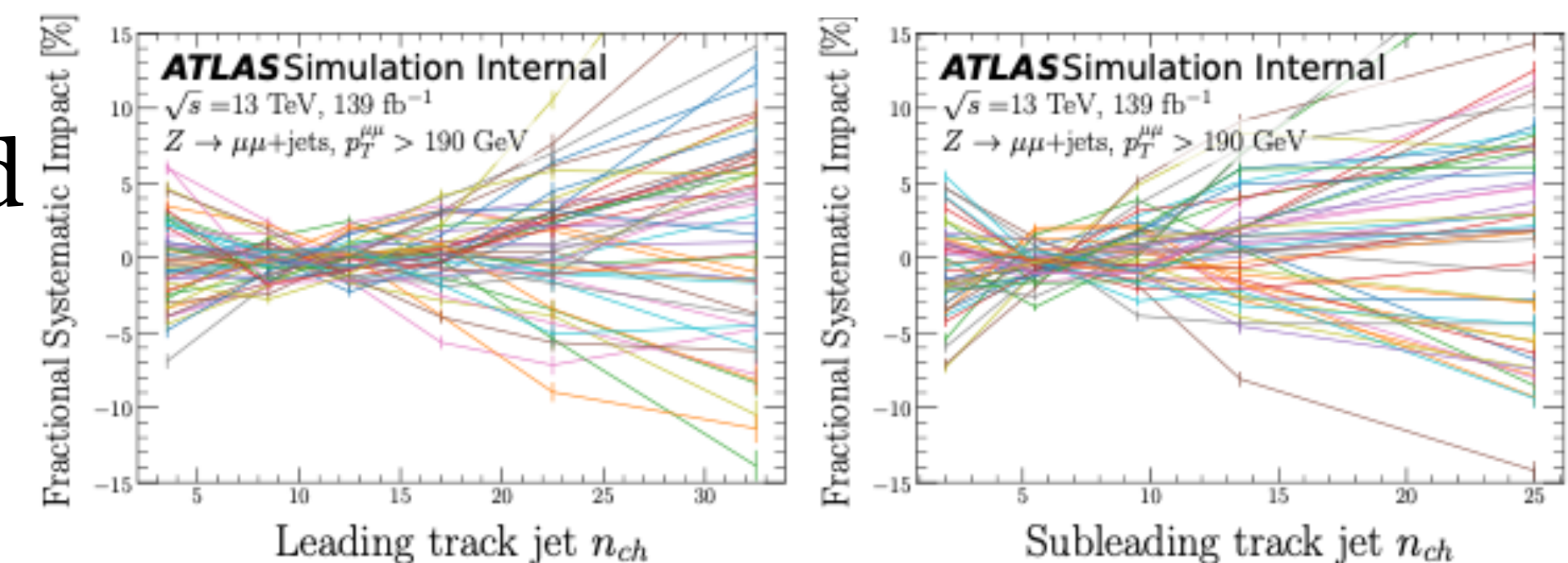
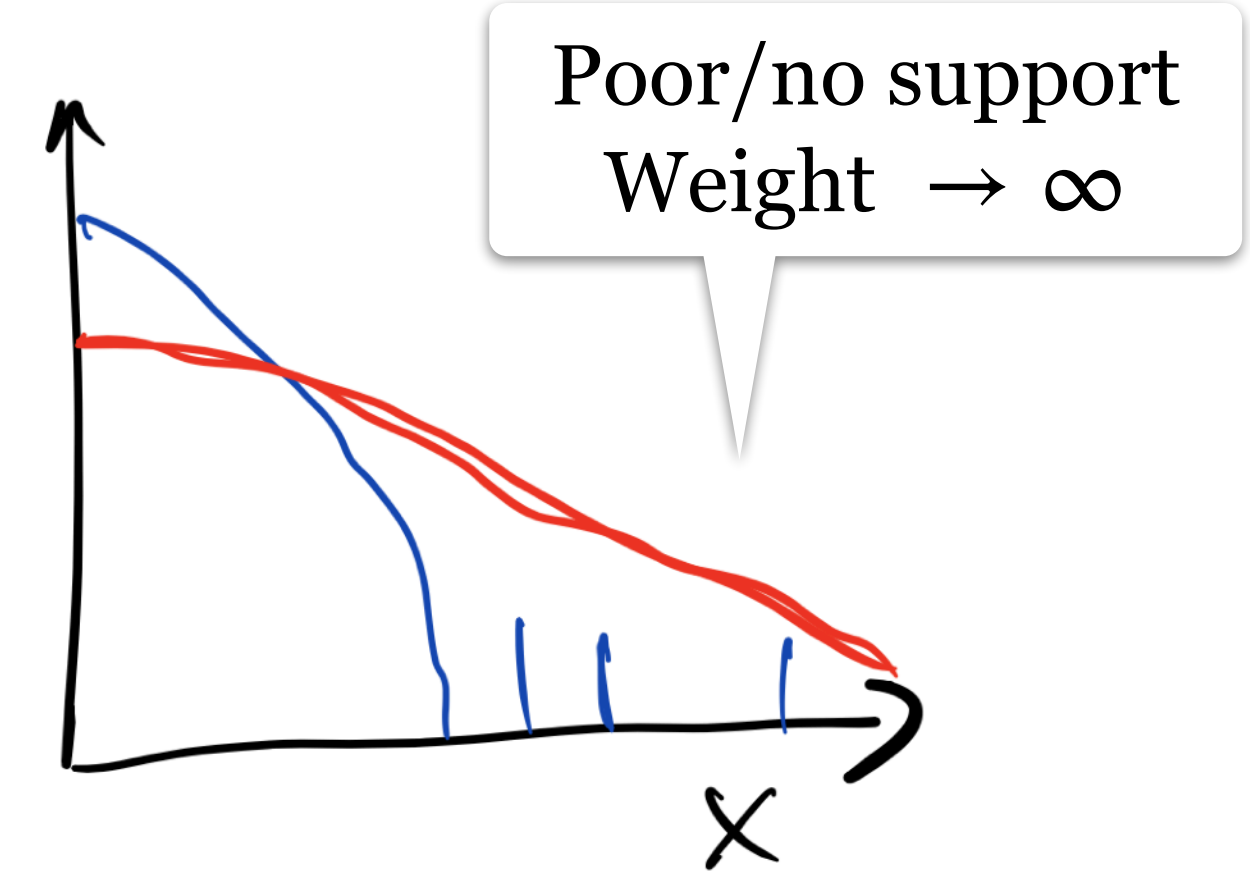


Illustration of
All changed particles
Produced in high pT
 $Z \rightarrow \mu\mu$ events



Shortcomings and challenges

- Wrap-around effect
 - Network gets confused by discontinuity in ϕ . It assumes smooth functions. Solved by letting network used $\sin(\phi)$ and $\cos(\phi)$.
- Insufficient support across full phase space
 - If we have reigns of phase space with too few initial MC events, the reweight will be too large (purity $f(\vec{x})$ too low, therefore $w(\vec{x}) = f / (1 - f)$ unstable
- Instabilities of the network
 - Networks (Keras Tensorflow) initialized with random seed. Quickly finds solution. But different dep. on seed \rightarrow per-event instabilities
 - Hyperparameter optimization, and ensembling

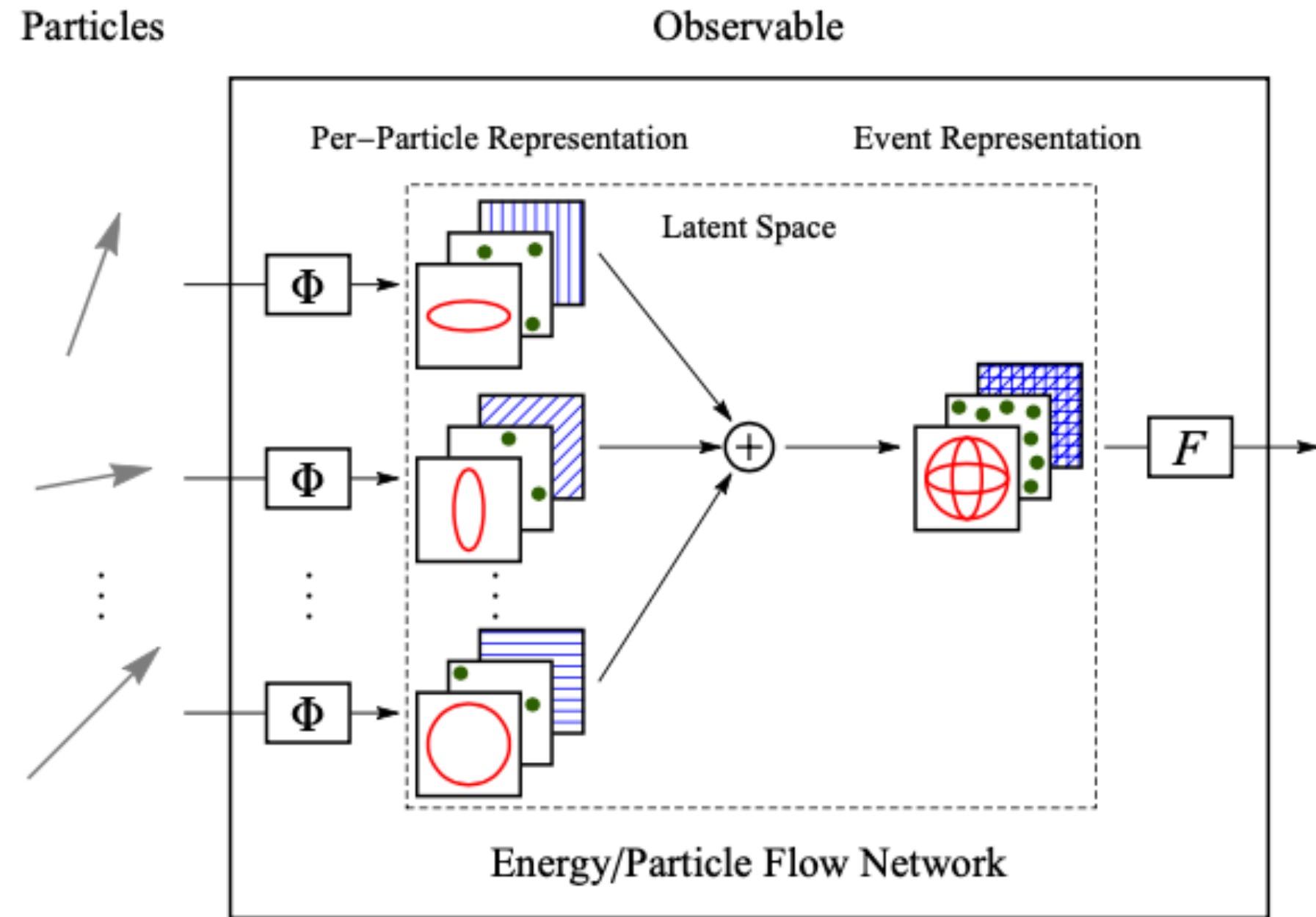


Summary

- Rapid development in machine learning opens up for new possibilities in particle physics
- One such development presented here: simultaneous unfolding of many variables at once
- This means output of measurement will be a large set of events rather than a binned spectrum as we have now
 - Significant more information provided
 - Clear applications to e.g. MC tuning, searches for BSM effects, anomaly detection
- A lot of potential and rapid development
- Challenges and details around validation and guidelines still being worked out
- Exciting times ahead

Backup

Particle flow networks



$$\mathcal{O}(\{p_1, \dots, p_M\}) = F \left(\sum_{i=1}^M \Phi(p_i) \right)$$

Symbol	Name	Short Description
PFN-ID	Particle Flow Network w. ID	PFN with full particle ID
PFN-Ex	Particle Flow Network w. PF ID	PFN with realistic particle ID
PFN-Ch	Particle Flow Network w. charge	PFN with charge information
PFN	Particle Flow Network	Using three-momentum information
EFN	Energy Flow Network	Using IRC-safe information
RNN-ID	Recurrent Neural Network w. ID	RNN with full particle ID
RNN	Recurrent Neural Network	Using three-momentum information
EFP	Energy Flow Polynomials	A linear basis for IRC-safe information
DNN	Dense Neural Network	Trained on an N -subjettiness basis
CNN	Convolutional Neural Network	Trained on 33×33 grayscale jet images
M	Constituent Multiplicity	Number of particles in the jet
n_{SD}	Soft Drop Multiplicity	Probes number of perturbative emissions
m	Jet Mass	Mass of the jet

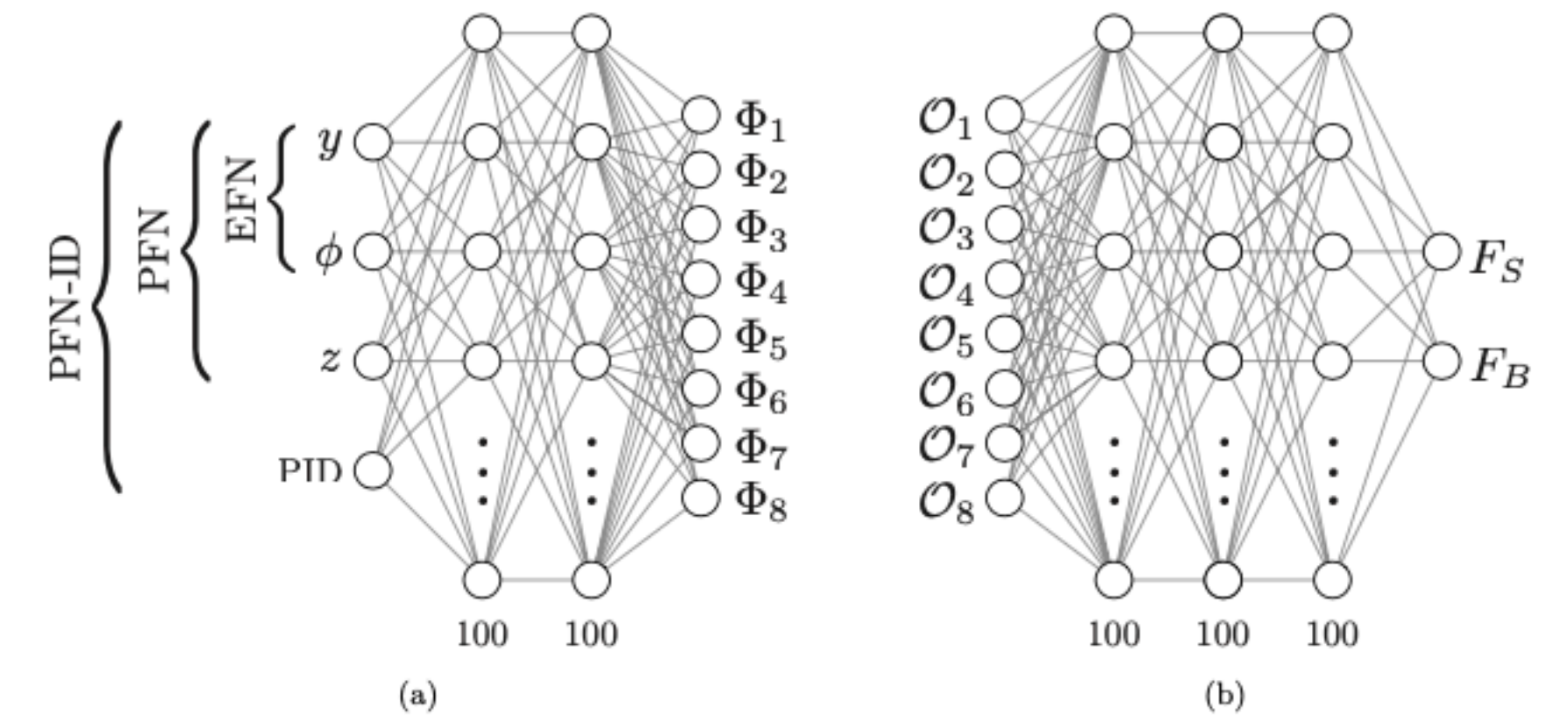
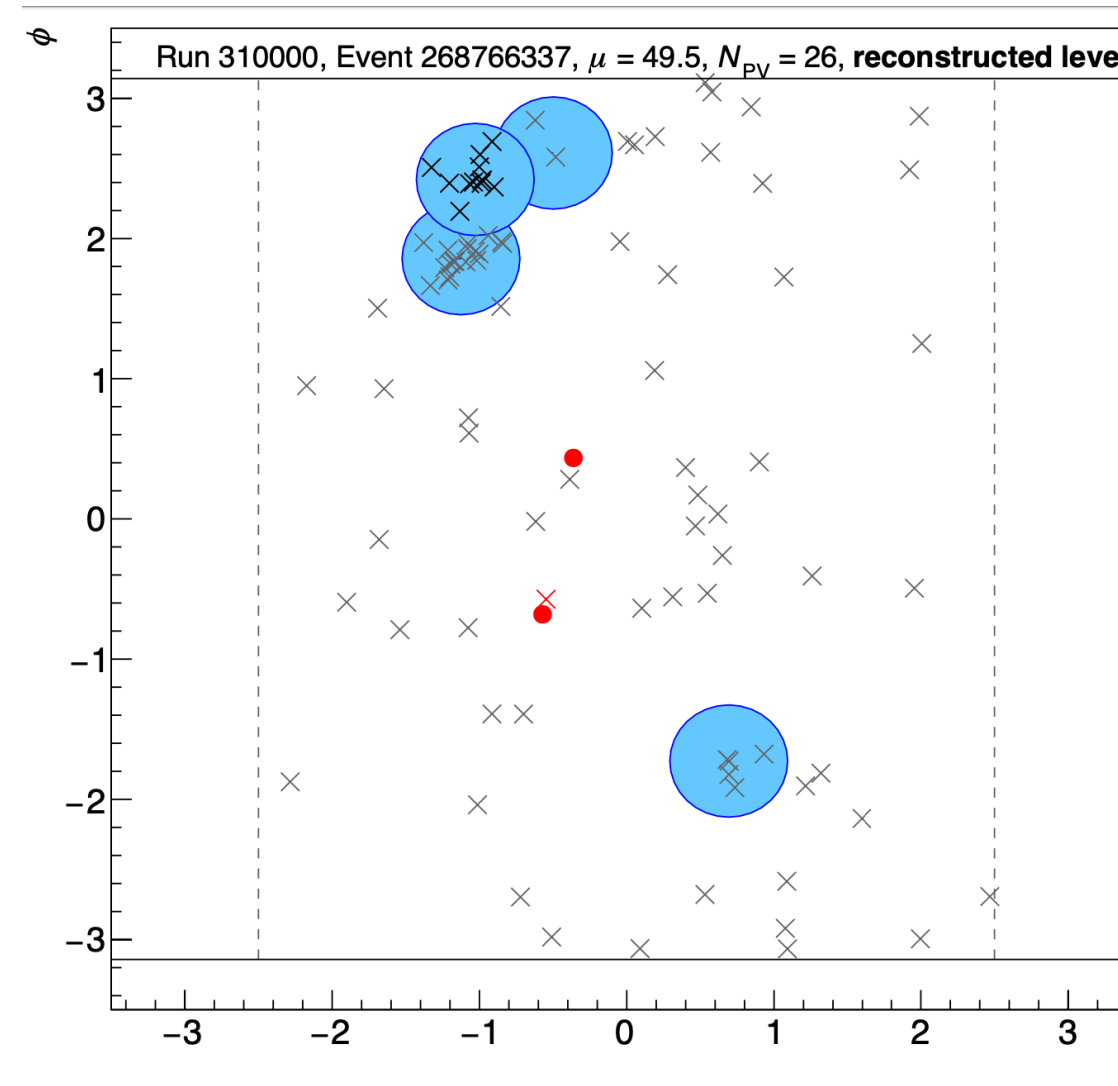
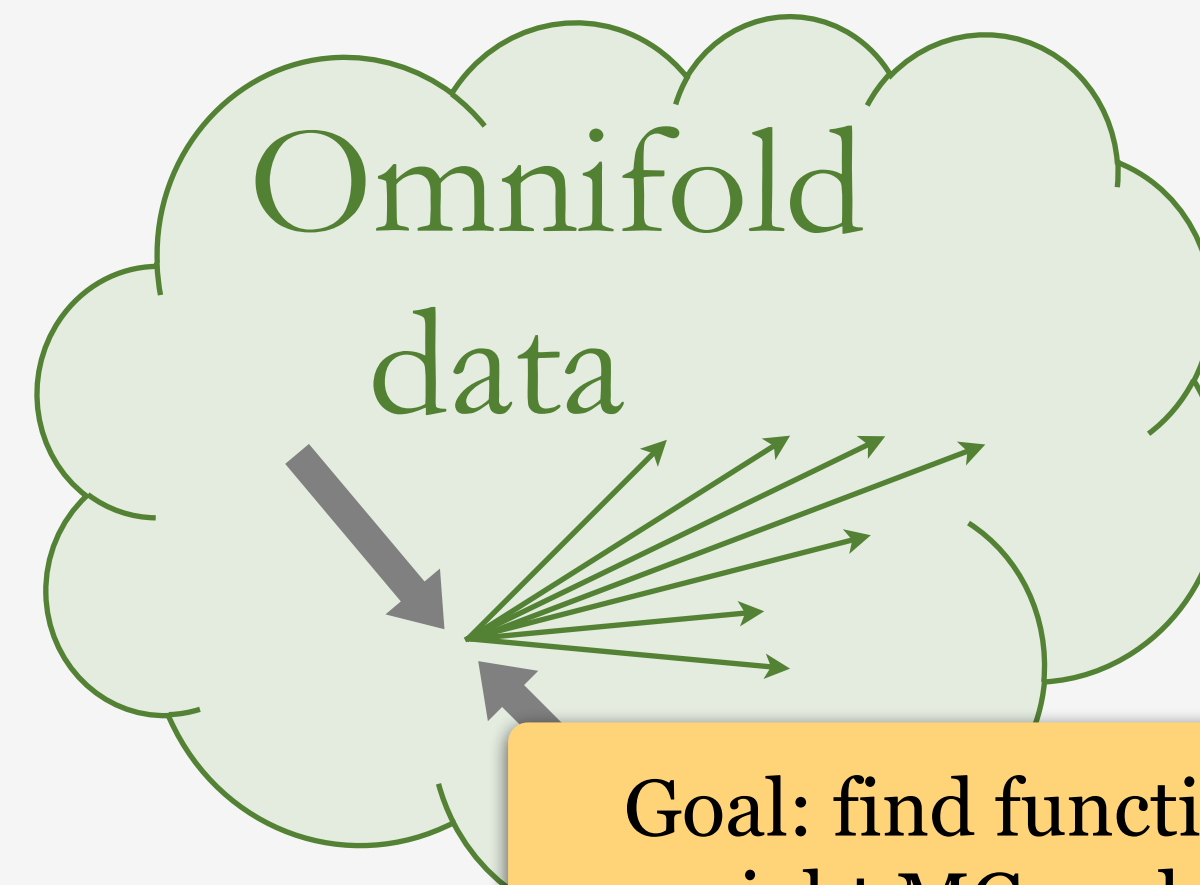
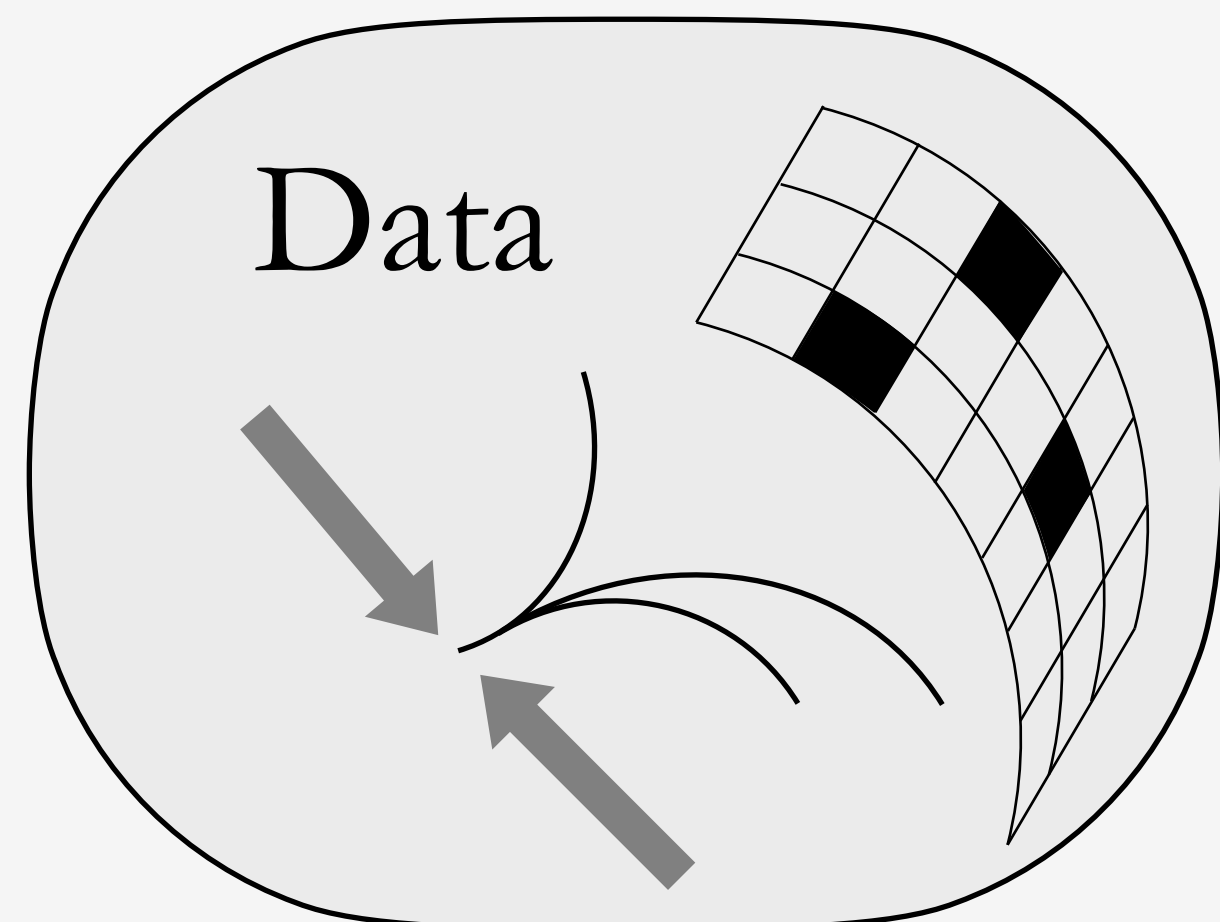


Figure 4: The particular dense networks used here to parametrize (a) the per-particle

Detector-level

Particle-level

Nature



Goal: find function to reweight MC such that it becomes unfolded data!

Step 1:
Reweight MC to Data

Step 2:
Propagate to MC truth

Simulation

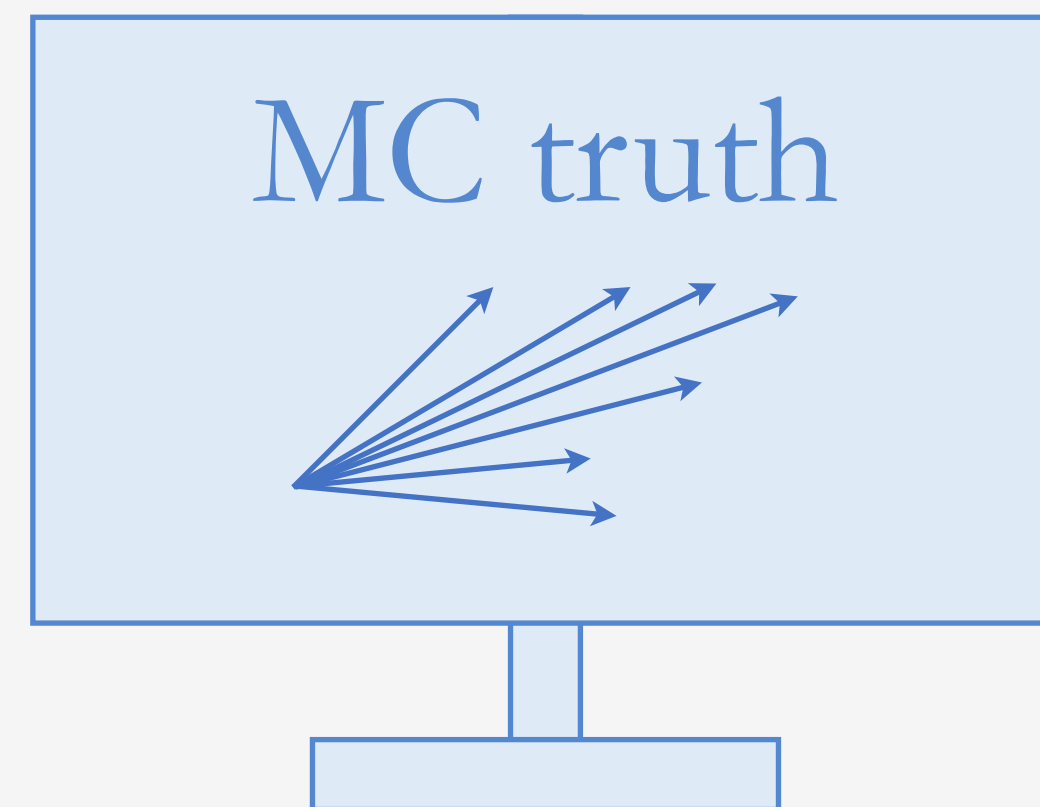
$$\nu_{n-1} \xrightarrow{\text{Data}} \omega_n$$

$$\nu_{n-1} \xrightarrow{\omega_n} \nu_n$$



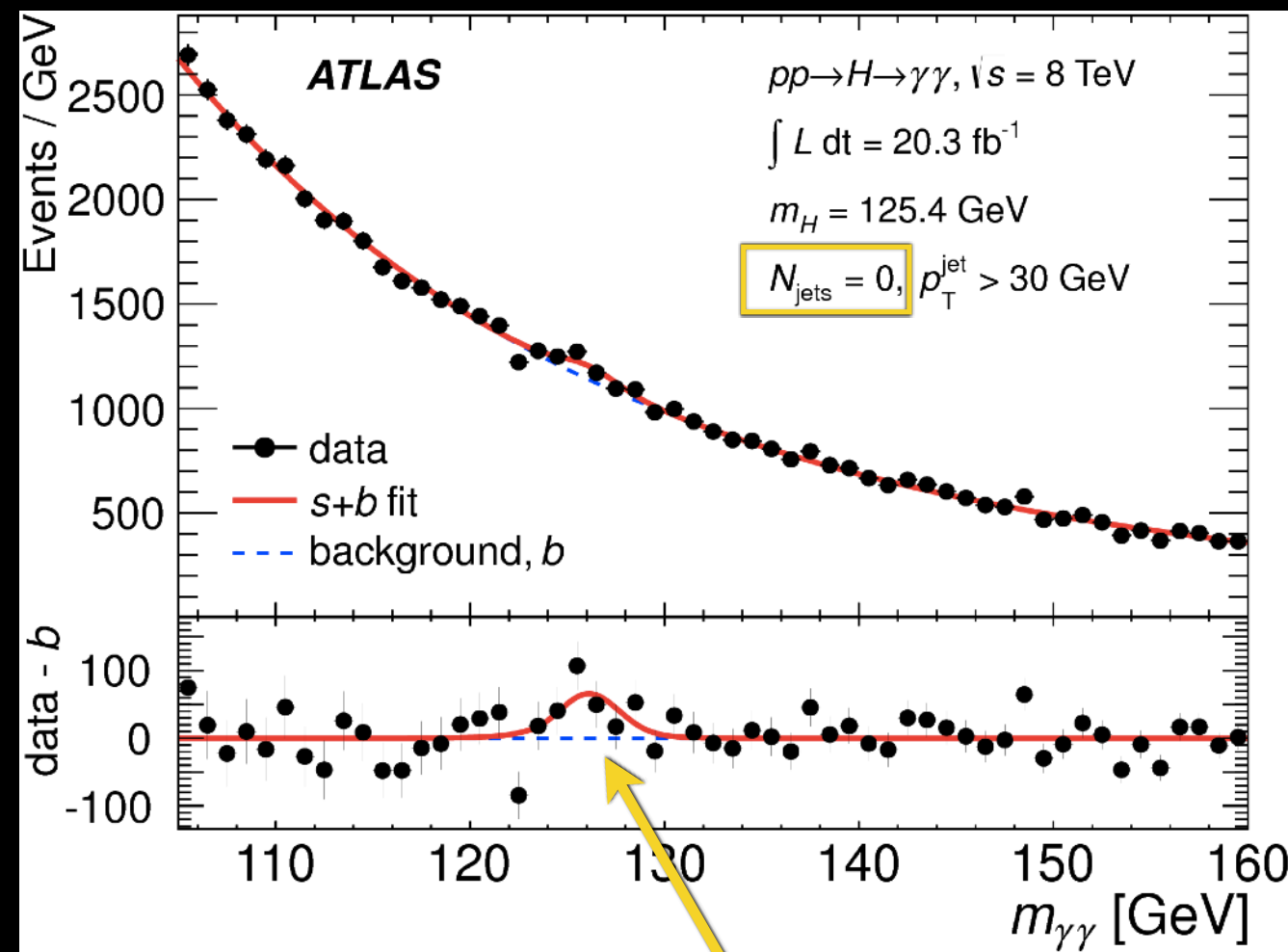
Pull Weights

Push Weights

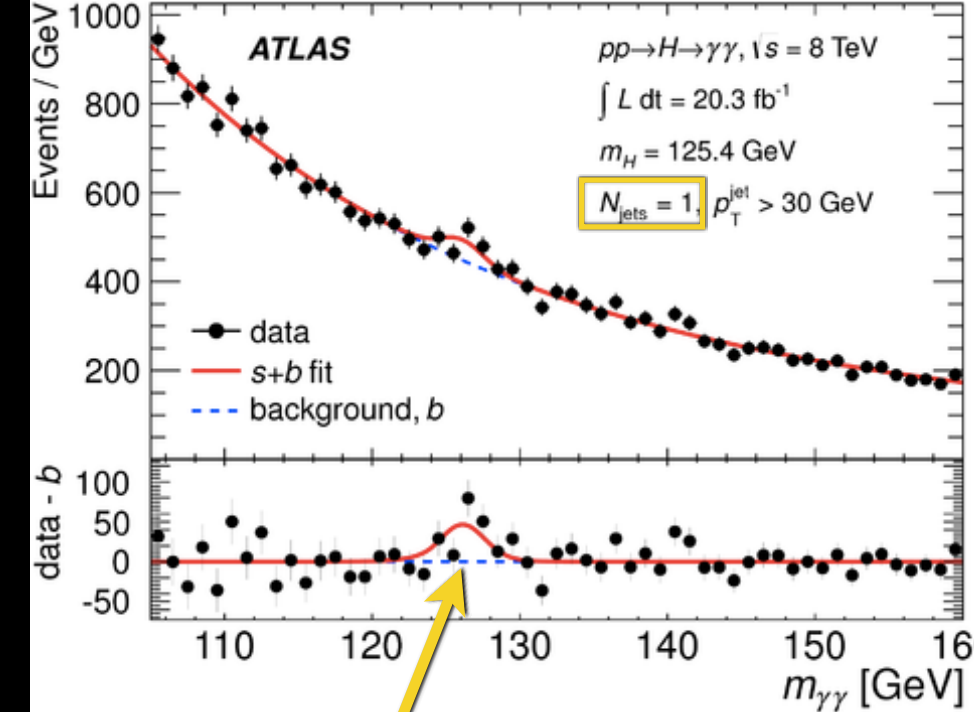


Measuring Higgs boson distributions

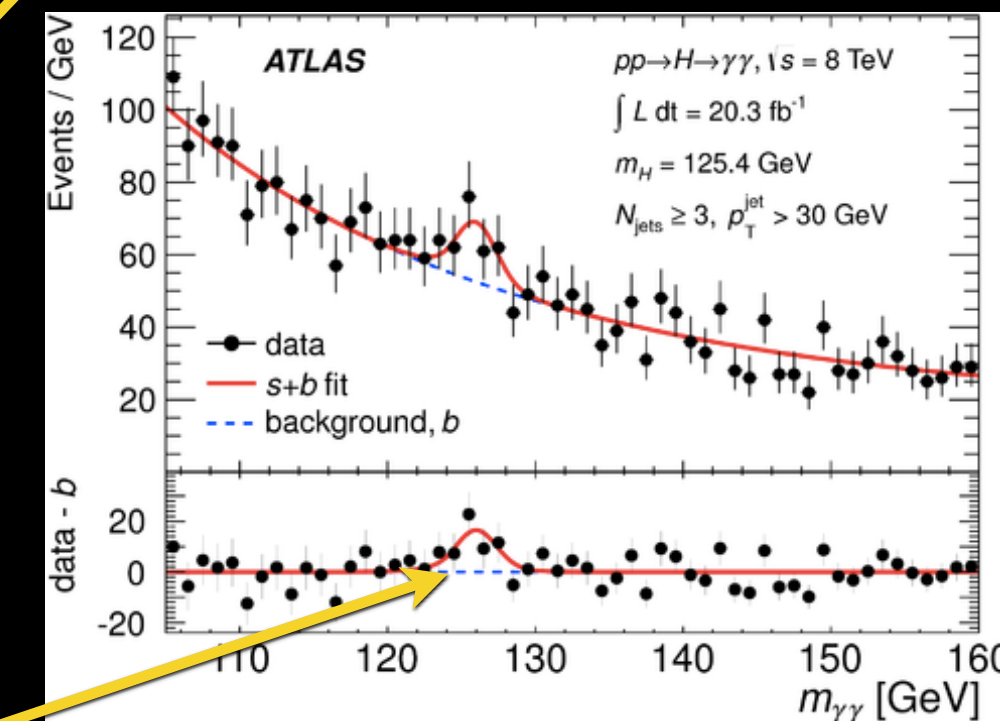
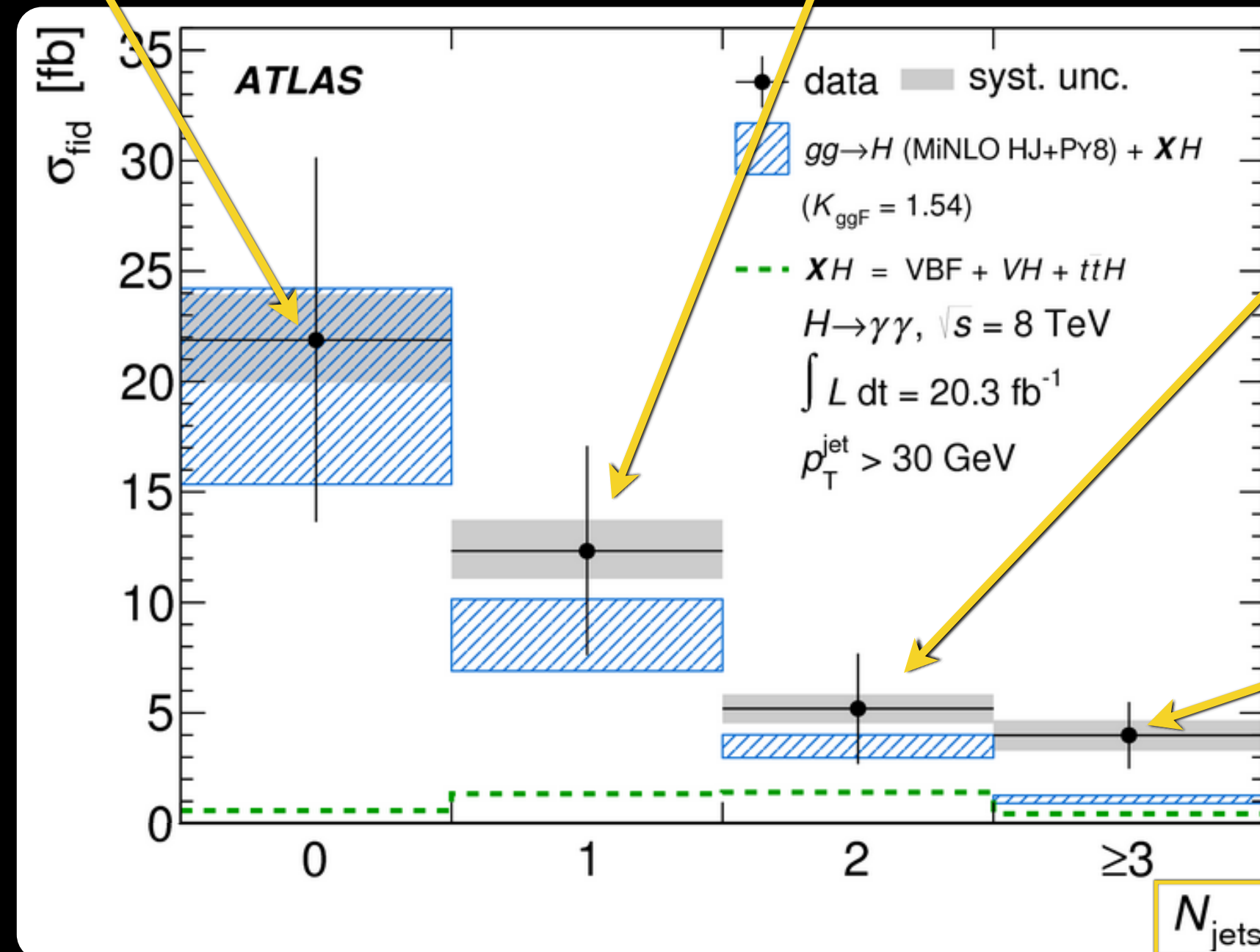
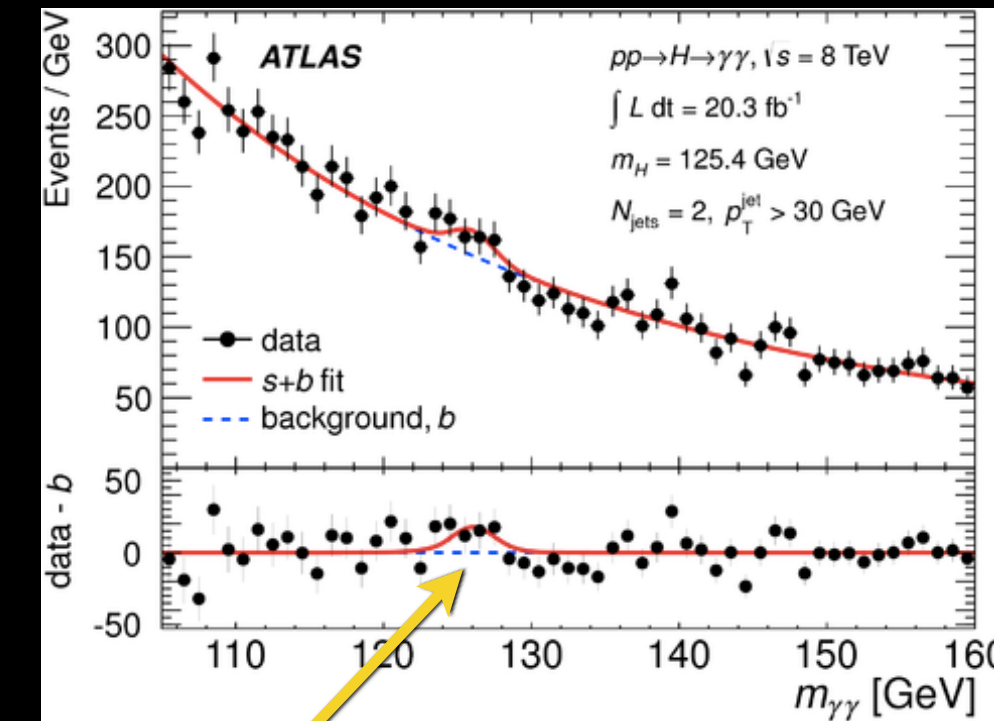
All events with no jets



All events with one jet



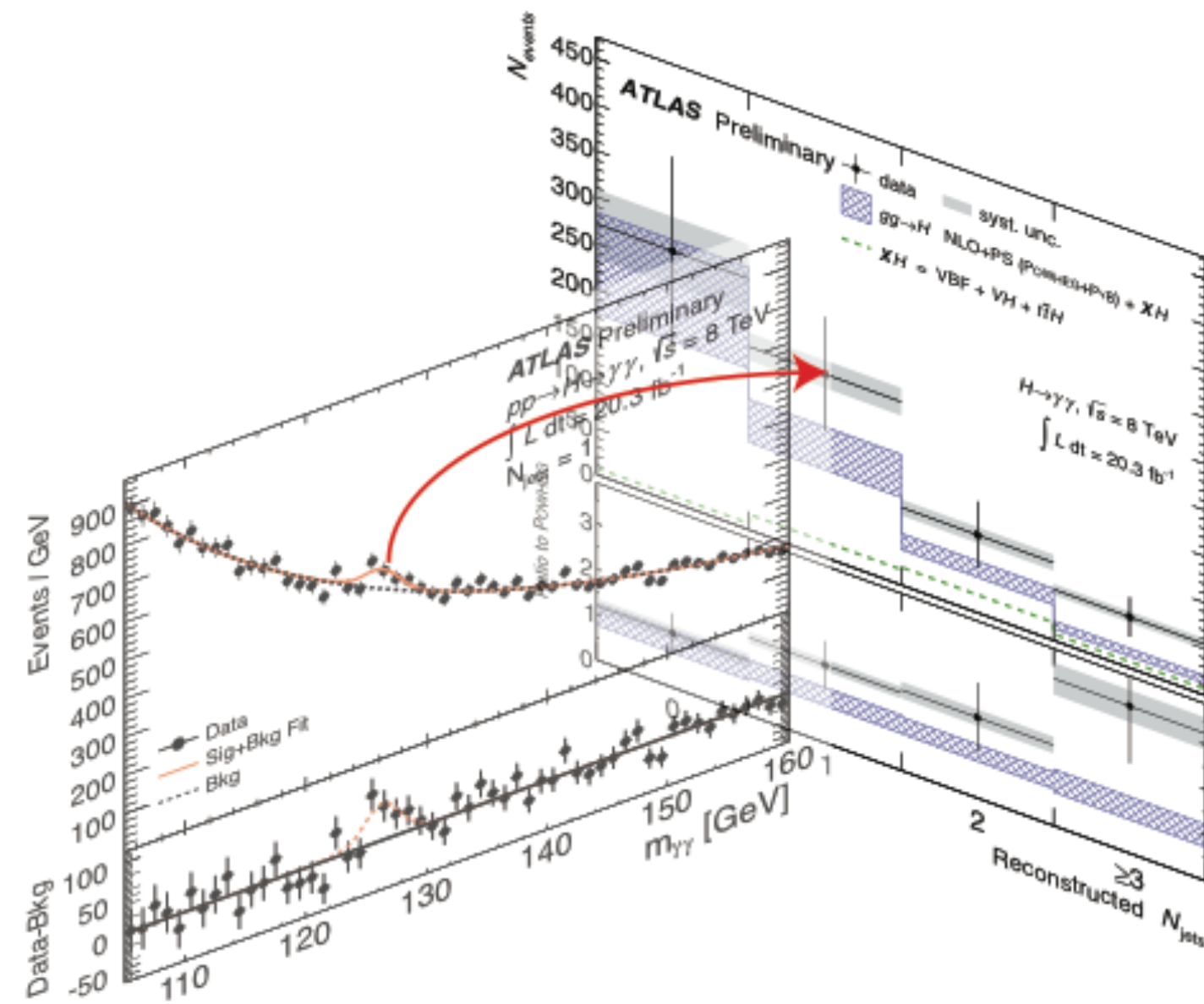
All events with two jets ...



All events with 3 or more jets

Differential cross section measurement overview

1. Signal extraction



- Spit dataset into bins of variable of interest (here 4 N_{jets} bins)
- For each bin, extract s from a $s+b$ fit to the $m_{\gamma\gamma}$ spectra
- Large statistical uncertainty due to small s/b

2. Unfold to particle level and divide by integrated luminosity and bin-width

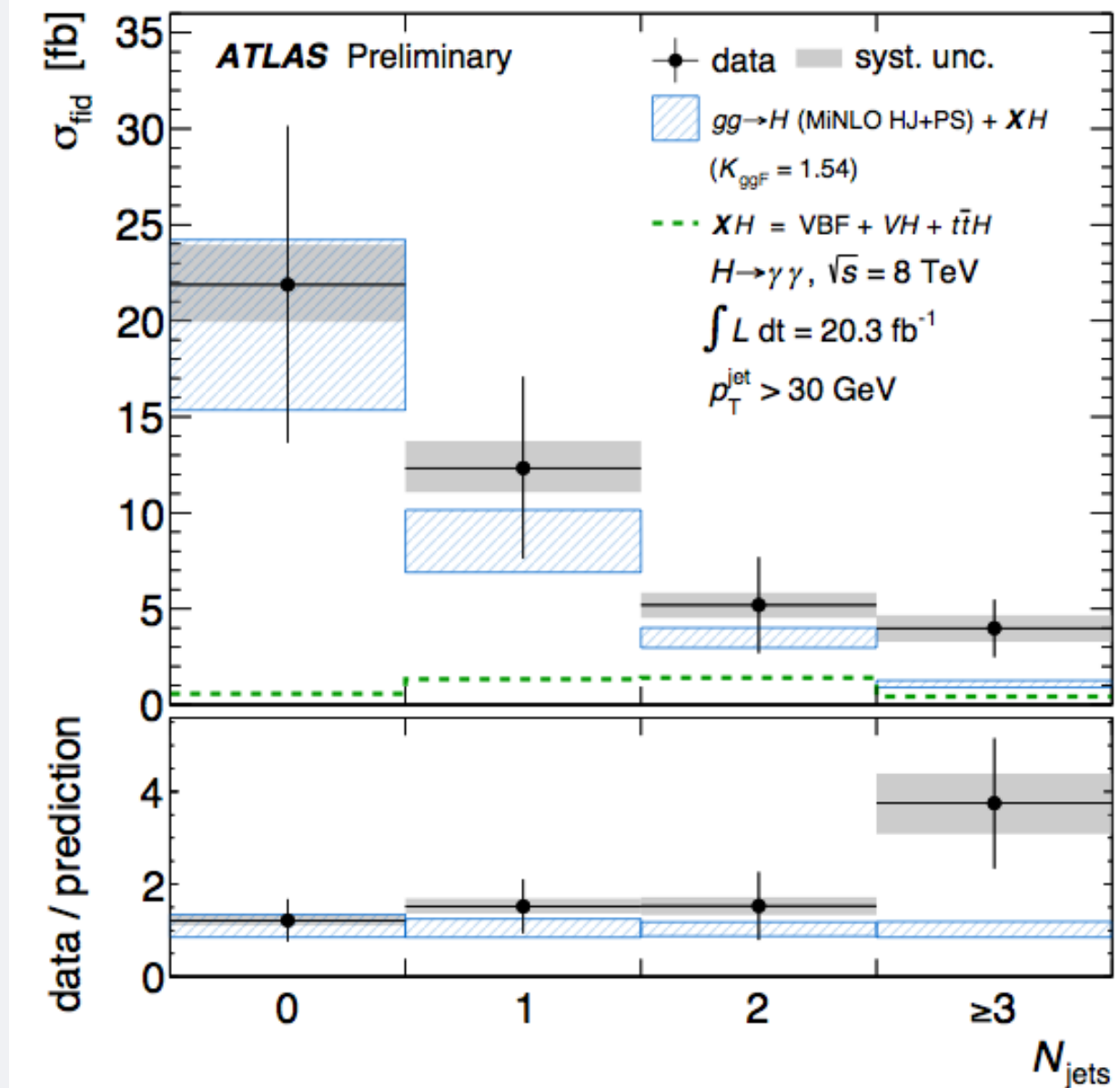
$$\sigma_{\text{fid}} = \frac{n_{\text{sig},i}}{c_i \mathcal{L}_{\text{int}}}$$

correction factor for detector effects

20.3 fb⁻¹ (±2.8%)

- correction for detector effects with bin-by-bin unfolding
- convert to (“differential”) cross section by dividing by int. lumi (and bin-width)

3. Plot and compare with theory



- compare to **particle level** prediction - i.e. no need for detector simulation
- Can also compare with analytical calculations (parton level) but then need small parton→particle level (NP) correction

Likelihood fit for EW Z_{jj} signal extraction

$$\ln \mathcal{L} = - \sum_{r,i} \nu_{ri}(\theta) + \sum_{r,i} N_{ri}^{\text{data}} \ln \nu_{ri}(\theta) - \sum_s \frac{\theta_s^2}{2},$$

$$\nu_{ri} = \mu_i \nu_{ri}^{\text{EW,MC}} + \nu_{ri}^{\text{strong}} + \nu_{ri}^{\text{other,MC}},$$

$$\begin{aligned} \nu_{\text{CRa},i}^{\text{strong}} &= b_{\text{L},i} \nu_{\text{CRa},i}^{\text{strong,MC}}, & \nu_{\text{CRb},i}^{\text{strong}} &= b_{\text{H},i} \nu_{\text{CRb},i}^{\text{strong,MC}}, \\ \nu_{\text{SR},i}^{\text{strong}} &= b_{\text{L},i} f(x_i) \nu_{\text{SR},i}^{\text{strong,MC}}, & \nu_{\text{CRc},i}^{\text{strong}} &= b_{\text{H},i} f(x_i) \nu_{\text{CRc},i}^{\text{strong,MC}} \end{aligned}$$

20 bins, 5 POIs, 12 free parameter that constrain strong Z_{jj} (5+5+2)

Each red bin count (after fitting, in SR) is: $\hat{\nu}_i^{\text{EW}} = \hat{\mu}_i \nu_i^{\text{EW,MC}}$

