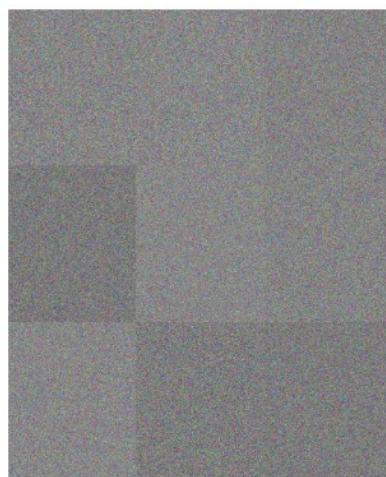




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<https://biferale.web.roma2.infn.it/>



ERICE – MACHINE LEARNING FOR COMPLEXITY 2024 APRIL

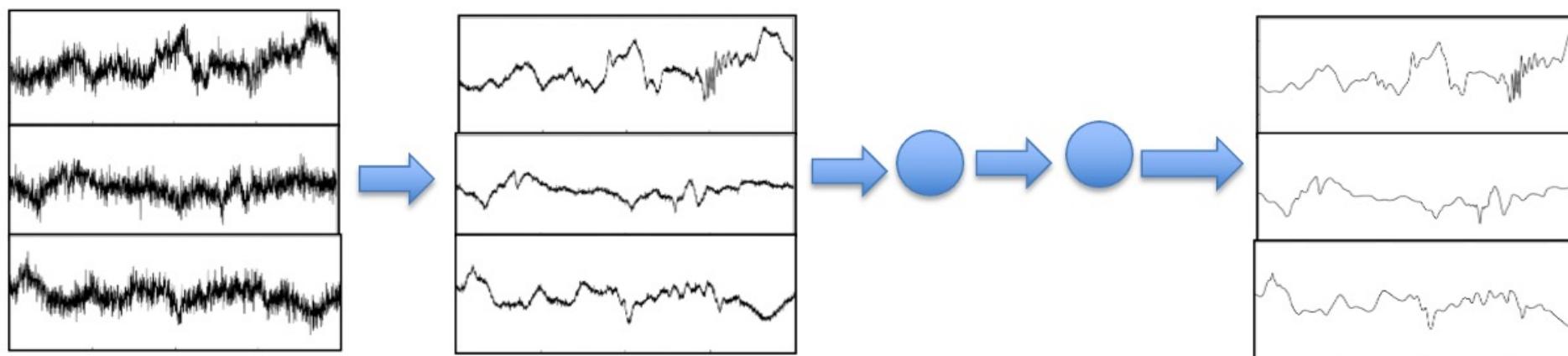
Data driven tools for Eulerian and Lagrangian Turbulence

CREDITS: M. CENCINI, C. CALASCIBETTA, L. PIRO, R. HEINONEN, T. LI, F. BONACCORSO, M. BUZZICOTTI, M. SCARPOLINI



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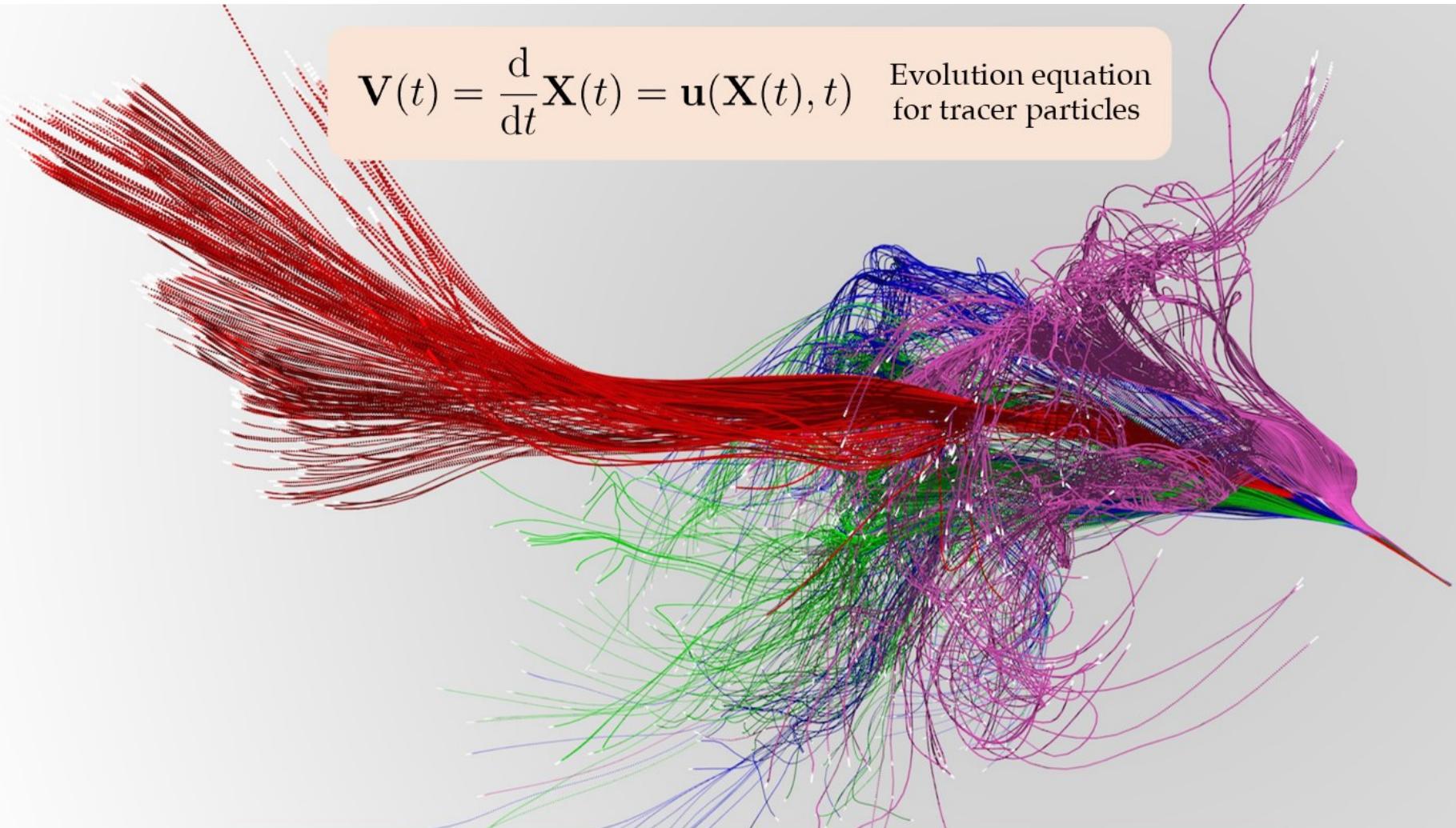




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AQTIVATE





$$\begin{cases} \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\nabla p + \frac{1}{Re} \Delta \mathbf{u} + \mathbf{F} \\ \nabla \cdot \mathbf{u} = 0 \end{cases}$$

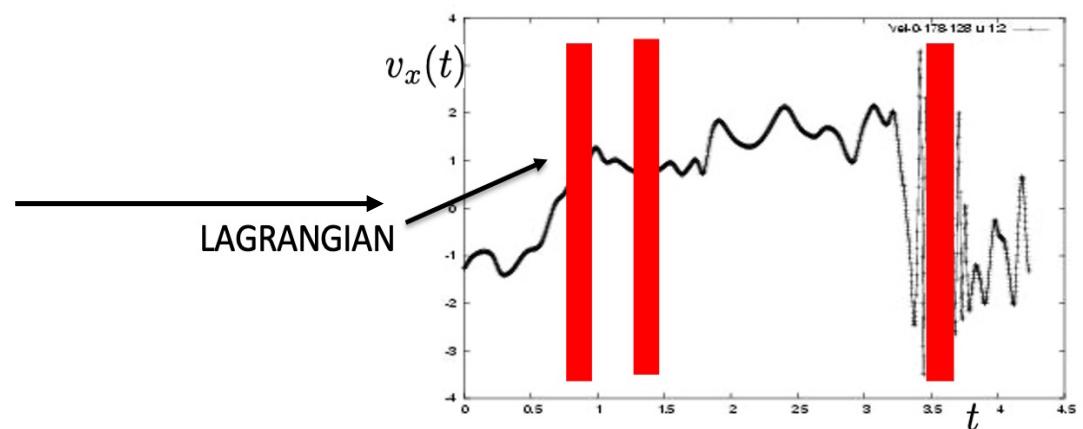
Navier-Stokes
Eq.s

STOCHASTIC MODELS FOR LAGRANGIAN TURBULENCE: WHY?

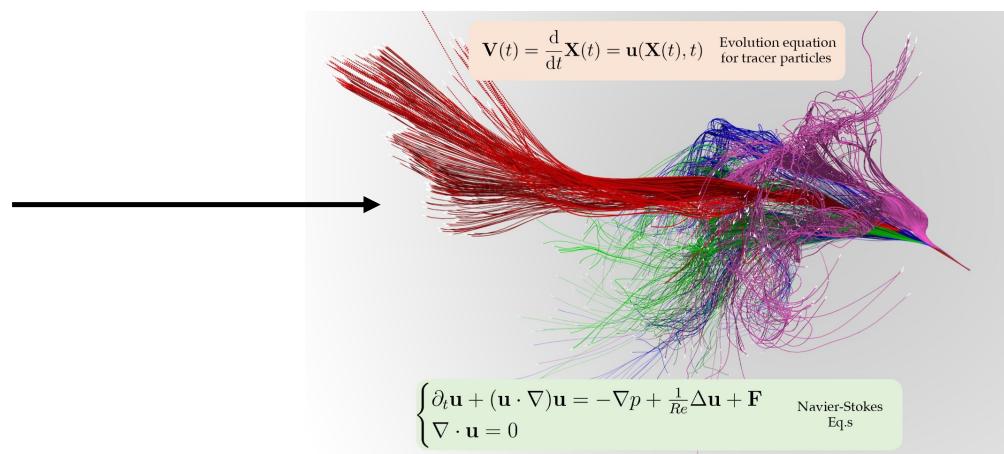
T. Li, LB, F. Bonaccorso, M. Scarpolini, M. Buzzicotti.
Synthetic Lagrangian Turbulence by Generative Diffusion Models.
arXiv:2307.08529 (2023) – Nature Machine Intelligence APRIL 2024

GENERATION OF LARGE SYNTHETIC DATA-BASE FOR
(I) RANKING OF PHYSICS FEATURES
(II) TESTING DOWNSTREAM APPLICATIONS/MODELS

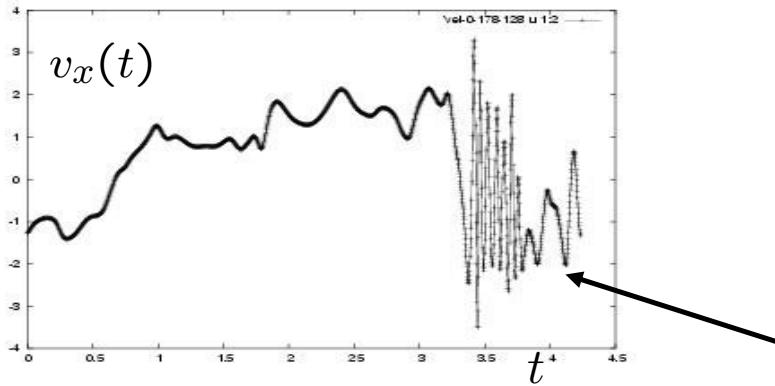
DATA ASSIMILATION/INPAINTING FROM MISSING FIELD/EXPERIMENTAL OBSERVATION



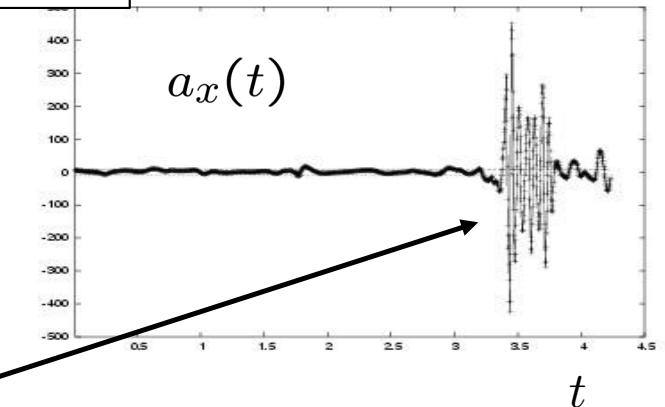
CLASSIFICATION/INFERRAL OF MISSING/INTERNAL PROPERTIES:
(I) INERTIA
(II) SHAPE
(III) ACTIVE DEGREES OF FREEDOM
(IV)



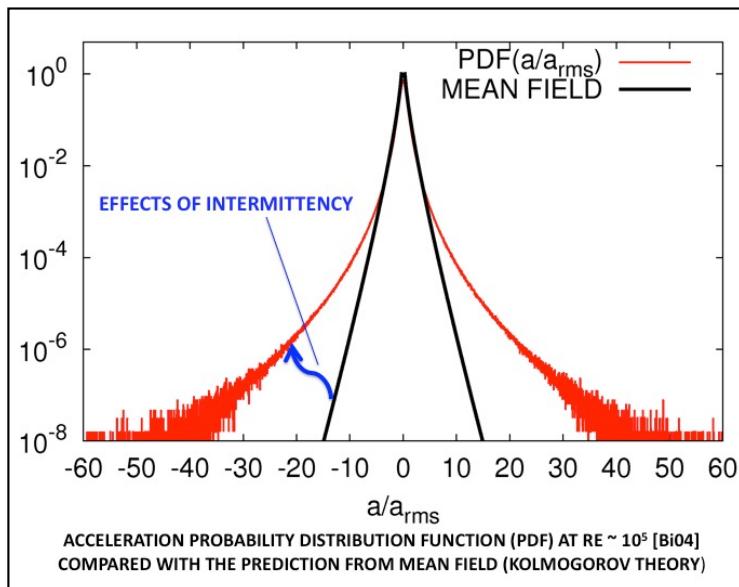
$$\begin{cases} \mathbf{a} = \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\nabla p + \nu \Delta \mathbf{u} + \mathbf{f} \\ \nabla \cdot \mathbf{u} = 0 \end{cases}$$



EXTREME EVENTS



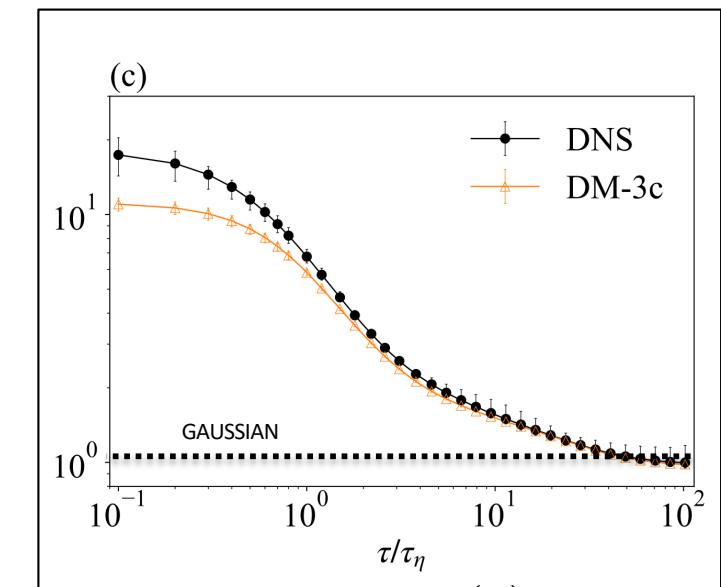
$$S_i^{(p)}(\tau) = \langle [v_i(t + \tau) - v_i(t)]^p \rangle$$



La Porta, G.A. Voth, A.M. Crawford, J. Alexander et al. Fluid particle accelerations in fully developed turbulence. *Nature*, 409(6823), 1017 (2001)

N. Mordant, P. Metz, O. Michel and J.F. Pinton. Measurement of Lagrangian velocity in fully developed turbulence. *Phys. Rev. Lett.* 87(21), 214501 (2001)

F. Toschi and E. Bodenschatz. Lagrangian Properties of Particles in Turbulence. *Annu. Rev. Fluid Mech.* 41, 375 (2009)



$$F(\tau) = \frac{S^{(4)}(\tau)}{[S^{(2)}(\tau)]^2}$$

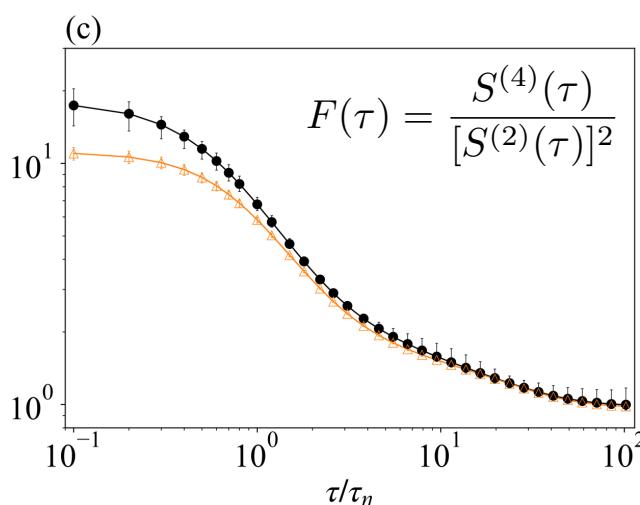
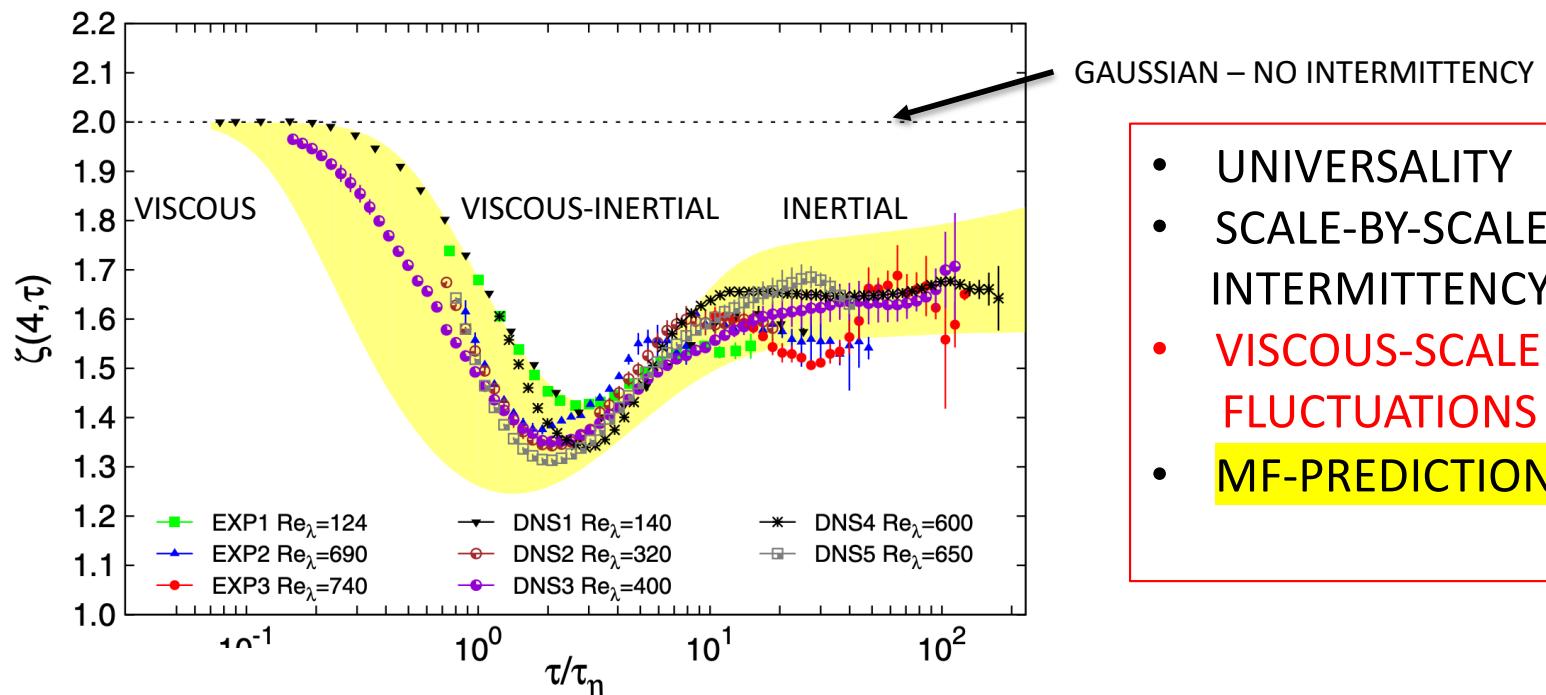
$$S_i^{(p)}(\tau) = \langle [v_i(t + \tau) - v_i(t)]^p \rangle$$

$$\zeta(4, \tau) = \frac{d \log S^{(4)}(\tau)}{d \log S^{(2)}(\tau)}$$

Universal Intermittent Properties of Particle Trajectories in Highly Turbulent Flows

A. Arnéodo,¹ R. Benzi,² J. Berg,³ L. Biferale,^{4,*} E. Bodenschatz,⁵ A. Busse,⁶ E. Calzavarini,⁷ B. Castaing,¹ M. Cencini,^{8,*} L. Chevillard,¹ R. T. Fisher,⁹ R. Grauer,¹⁰ H. Homann,¹⁰ D. Lamb,⁹ A. S. Lanotte,^{11,*} E. Lévêque,¹ B. Lüthi,¹² J. Mann,³ N. Mordant,¹³ W.-C. Müller,⁶ S. Ott,³ N. T. Ouellette,¹⁴ J.-F. Pinton,¹ S. B. Pope,¹⁵ S. G. Roux,¹ F. Toschi,^{16,17,*} H. Xu,⁵ and P. K. Yeung¹⁸

(International Collaboration for Turbulence Research)



- M. Borgas "The multifractal Lagrangian nature of turbulence", PTRSA 342, 379 (1993)
 G. K. Batchelor. "Pressure fluctuations in isotropic turbulence" Proc. Camb. Philos. Soc. 47, 359 (1951)
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Zamansky, R. **Acceleration scaling and stochastic dynamics** of a fluid particle in turbulence. Physical Review Fluids 7, 084608 (2022).

Lubcke, J., Friedrich, J., Grauer, R. **Stochastic interpolation** of sparsely sampled time series by a superstatistical random process and its synthesis in Fourier and wavelet space. J. Phys. Complex. 4 015005 (2023)

Diffusion Models

Training set: a set of images $\vec{a}^\mu \in \mathbb{R}^N$ $\mu = 1, \dots, P$
N is the dimension of the data, P their number

Langevin equation for an Ornstein-Uhlenbeck process

$$\frac{d\vec{x}}{dt} = -\vec{x} + \vec{\eta}(t) \quad \langle \eta_i(t)\eta_j(t') \rangle = 2T\delta_{ij}\delta(t-t')$$

$\vec{x}^\mu(t=0) = \vec{a}^\mu$ It transforms the data in iid Gaussian $\mathcal{N}(0, 1)$ at $t \gg 1$

$$P_t(\vec{x}) = \int d\vec{a} P_0(\vec{a}) \frac{1}{\sqrt{2\pi\Delta_t}^N} \exp\left(-\frac{1}{2} \frac{(\vec{x} - \vec{a}e^{-t})^2}{\Delta_t}\right) = \int d\vec{a} P_t(\vec{a}, \vec{x})$$
$$\Delta_t = T(1 - e^{-2t})$$

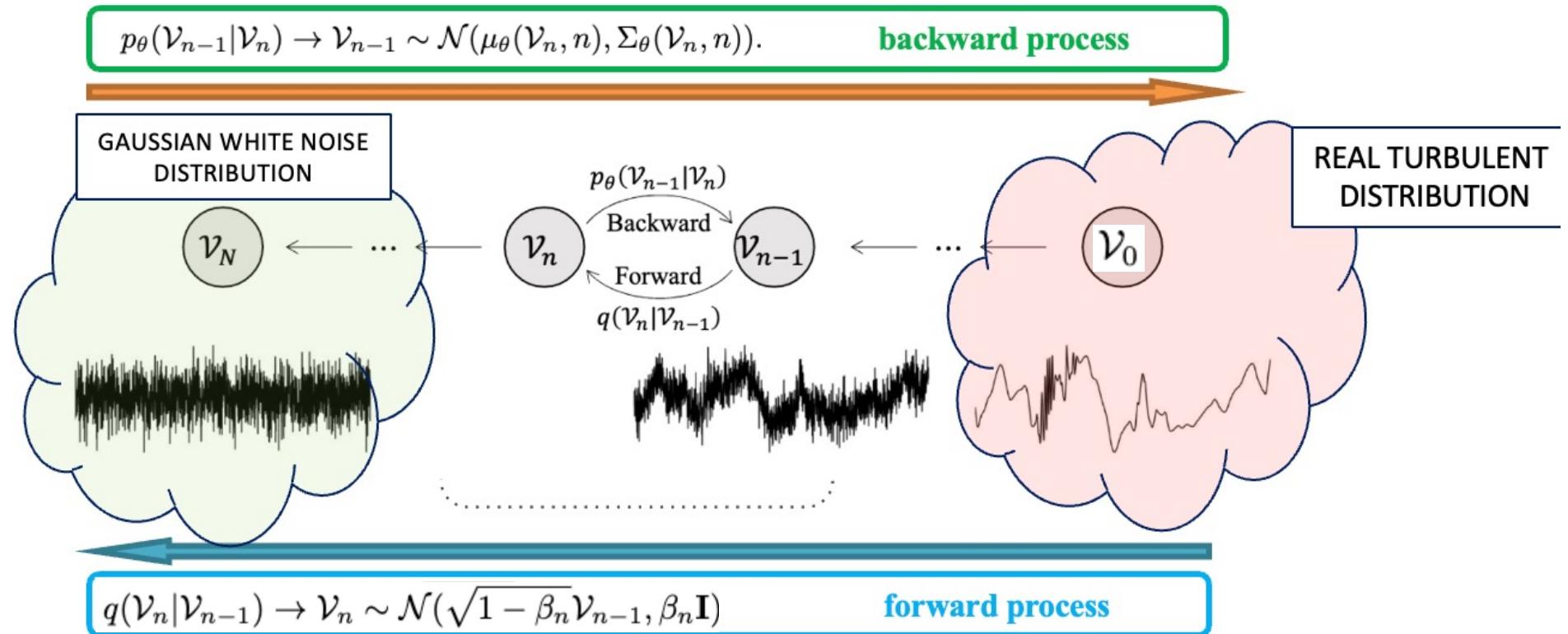


Score function provides the force field to go back in time

$$\mathcal{F}_i(\vec{x}, t) = \frac{\partial \log P_t(\vec{x})}{\partial x_i} \quad -\frac{dy_i}{dt} = y_i + 2T\mathcal{F}_i(y, t) + \eta_i(t)$$

Diffusion Models

‘Synthetica Lagrangian Turbulence: all you need is Diffusion Models’ T. Li, L.B, F. Bonaccorso, M. Scarpolini and M. Buzzicotti (arXiv:2307.08529 2023, submitted Nature Machine Intelligence)

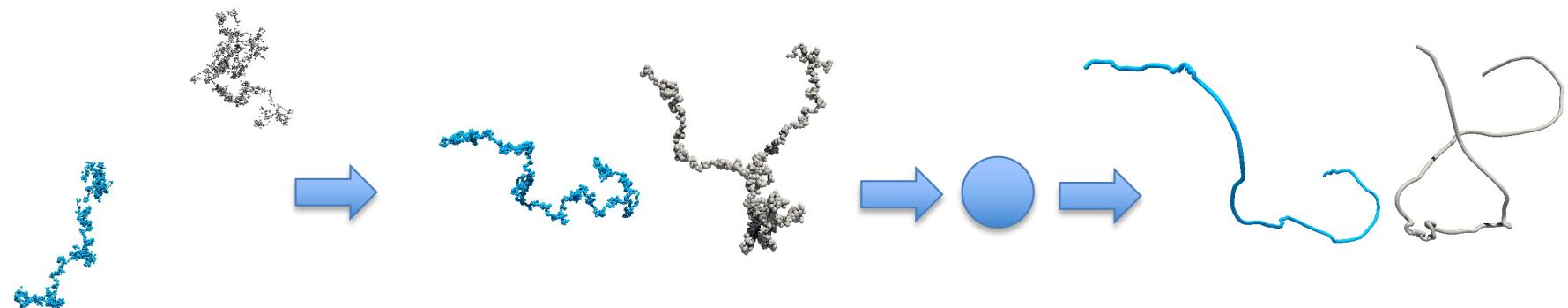
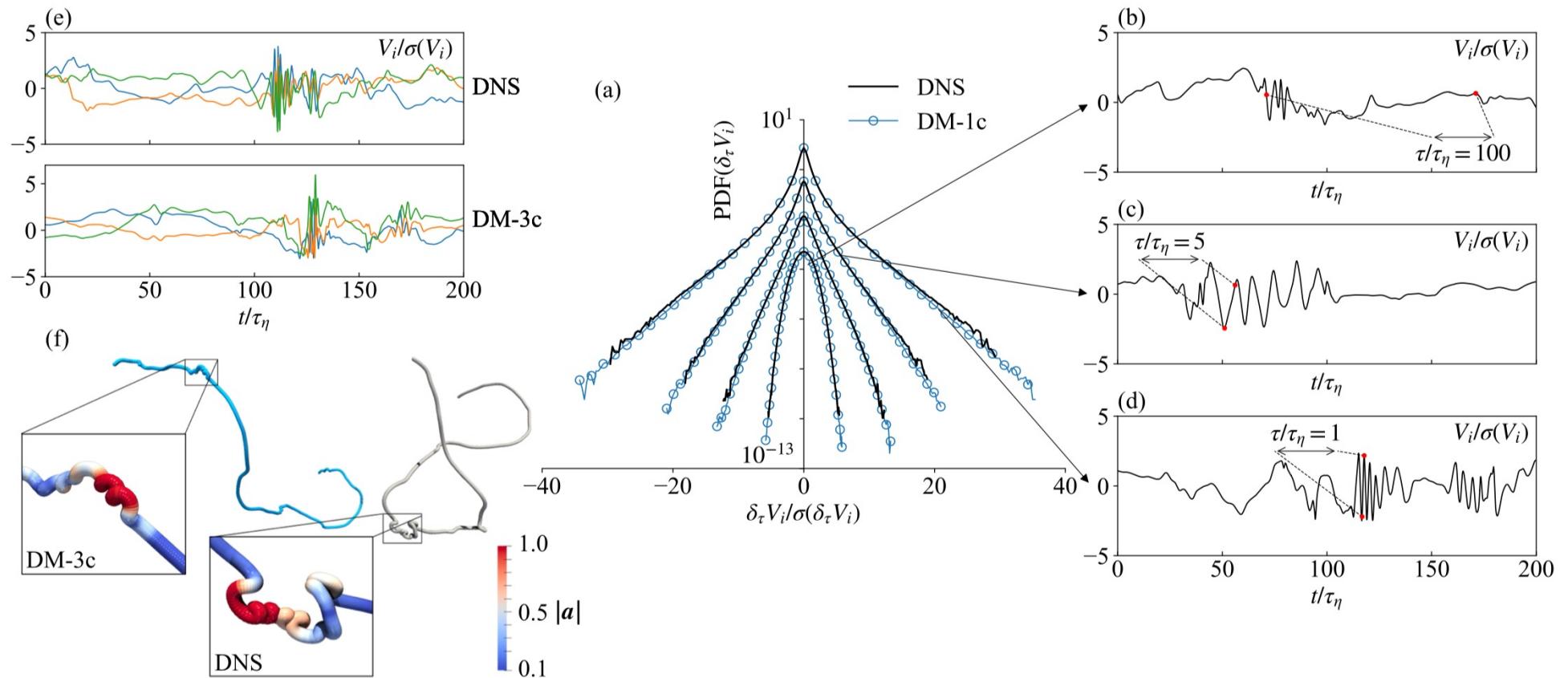


[Sohl-Dickstein et al., Deep Unsupervised Learning using Nonequilibrium Thermodynamics, ICML 2015](#)

[Ho et al., Denoising Diffusion Probabilistic Models, NeurIPS 2020](#)

[Song et al., Score-Based Generative Modeling through Stochastic Differential Equations, ICLR 2021](#)

$$\delta_\tau V_i(t) = V_i(t + \tau) - V_i(t),$$

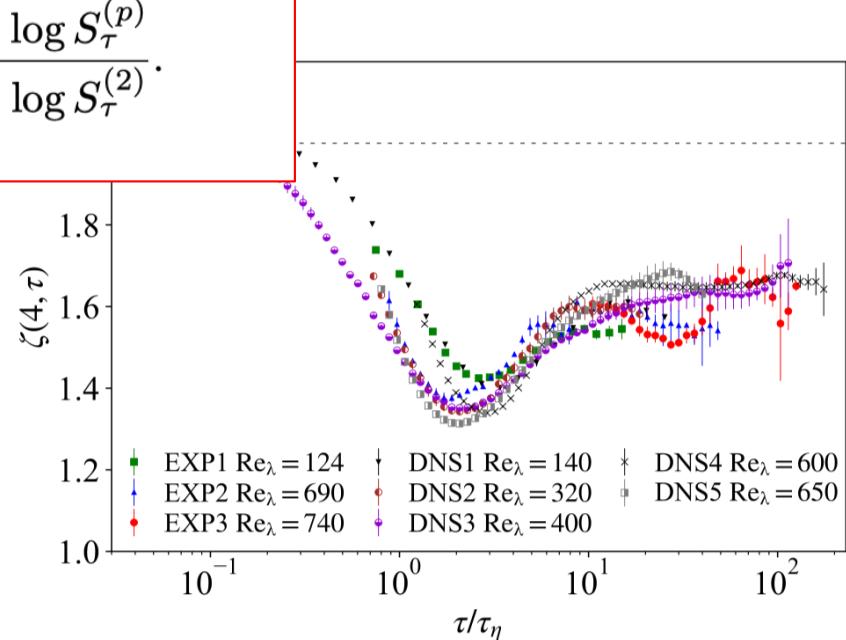
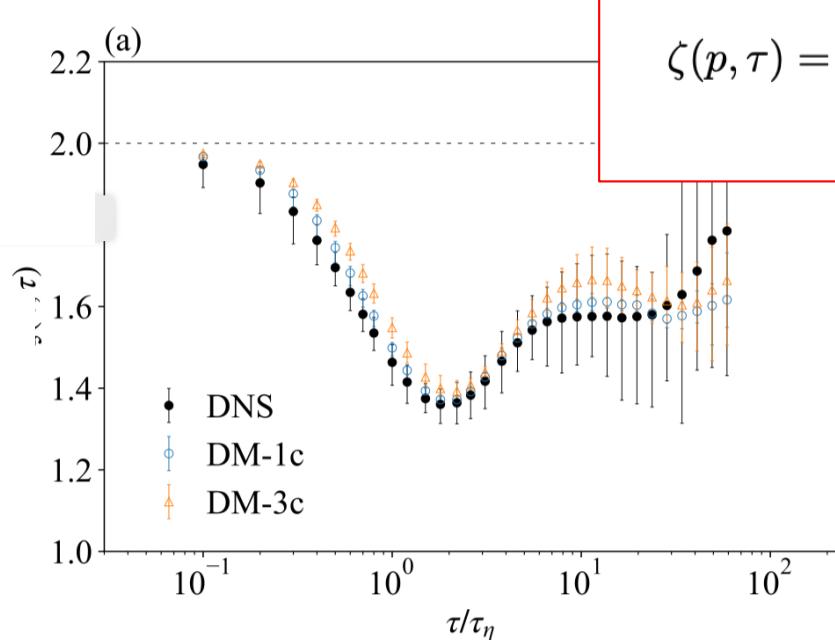
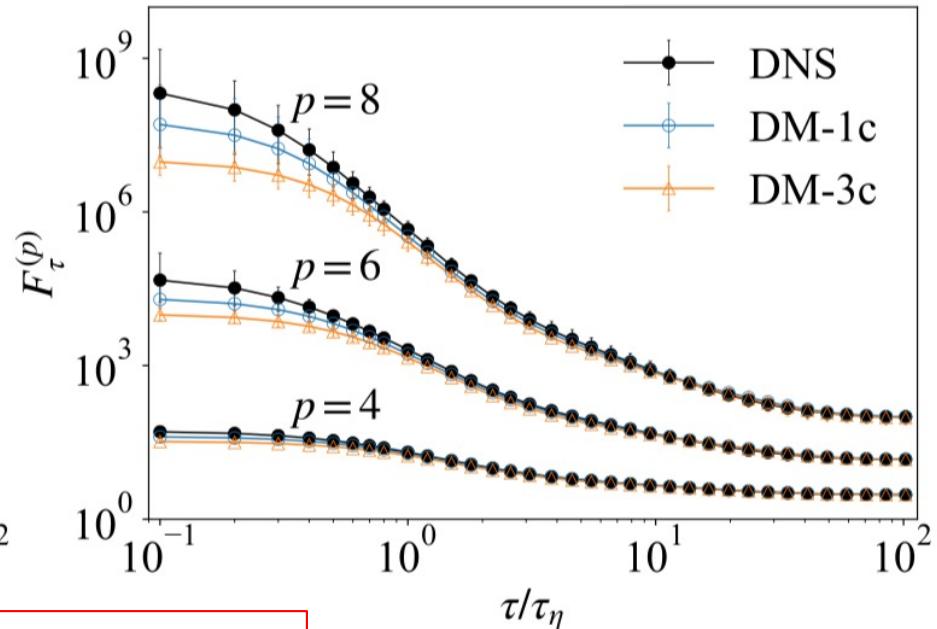
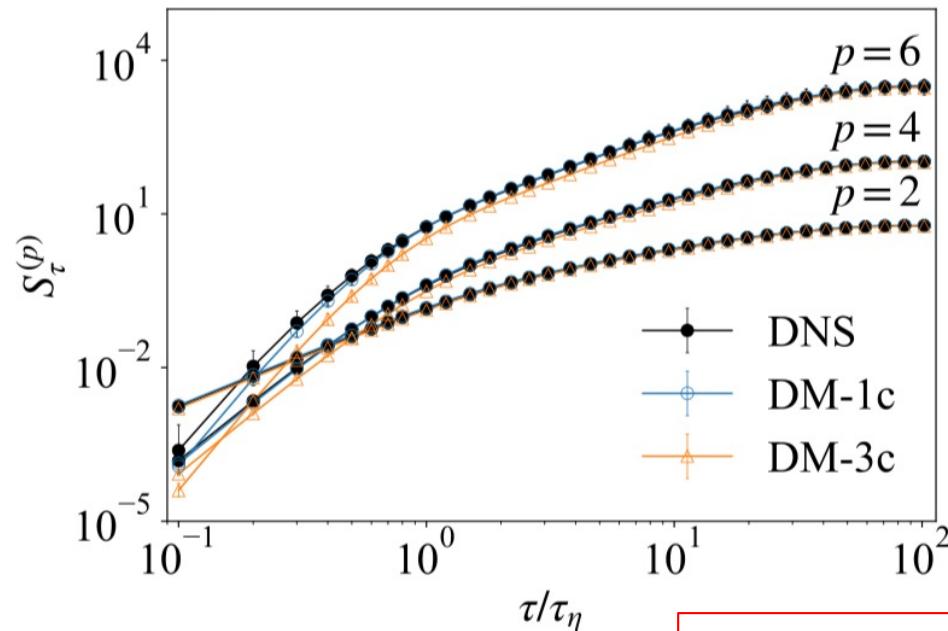


LAGRANGIAN STRUCTURE FUNCTIONS

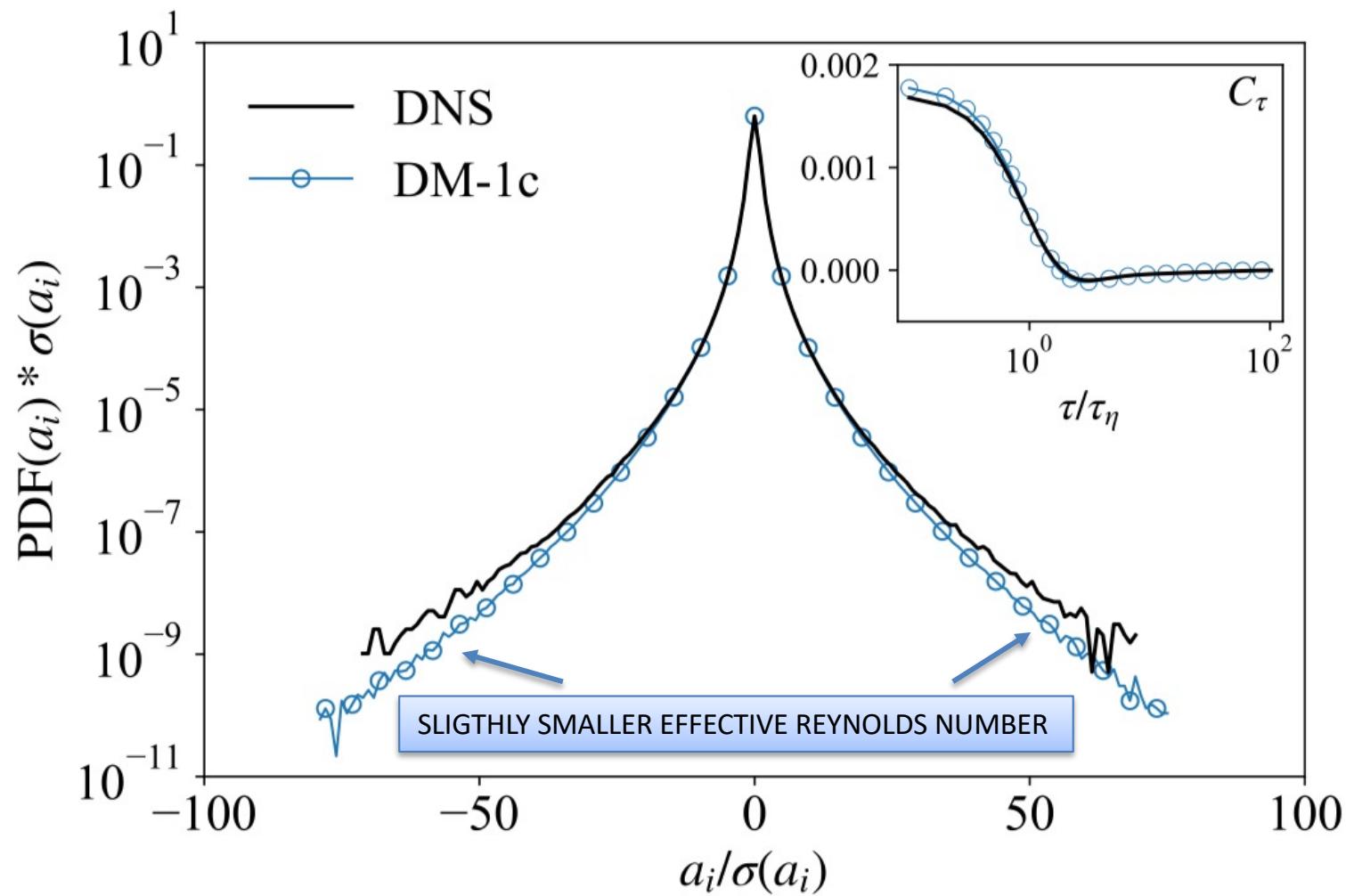
GENERALIZED FLATNESS

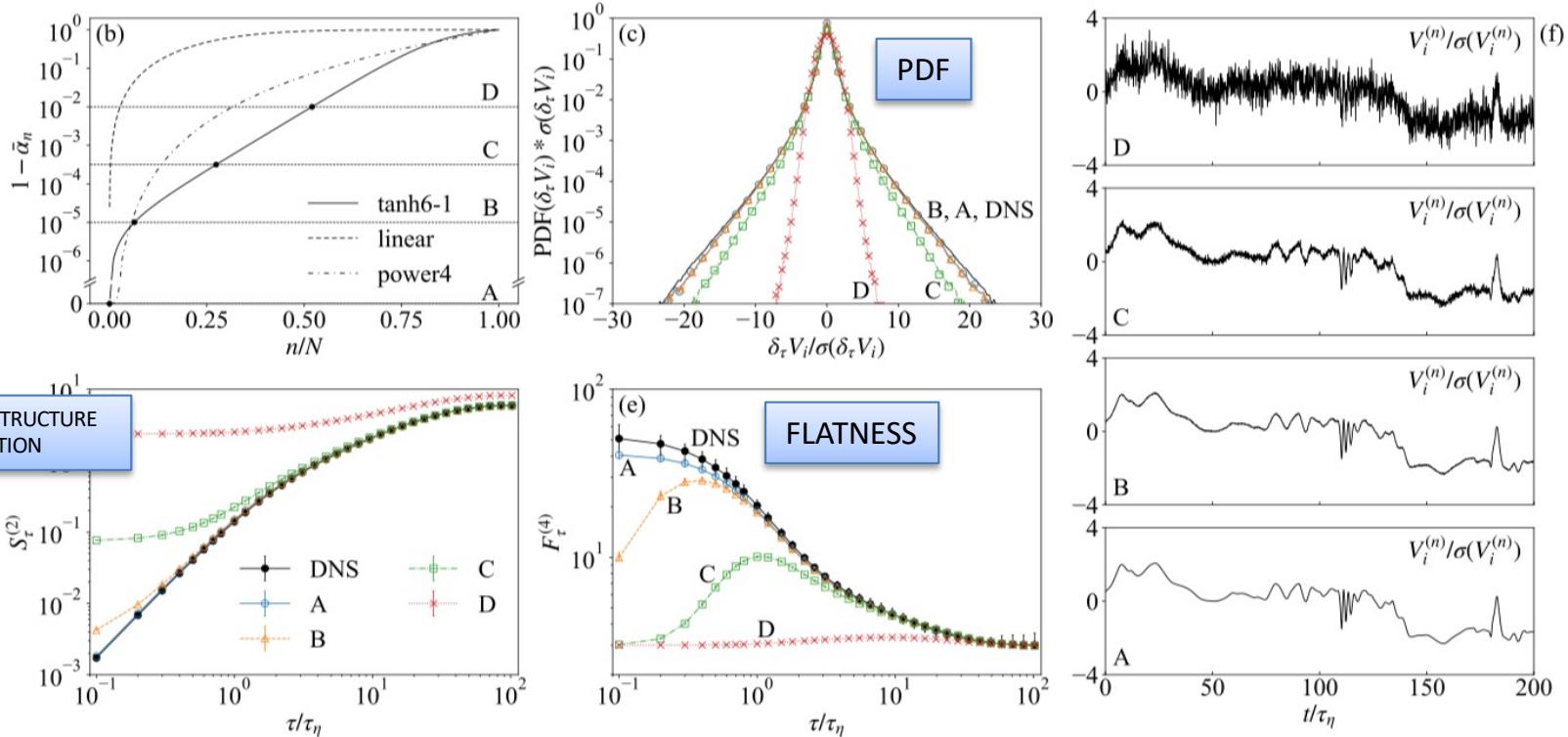
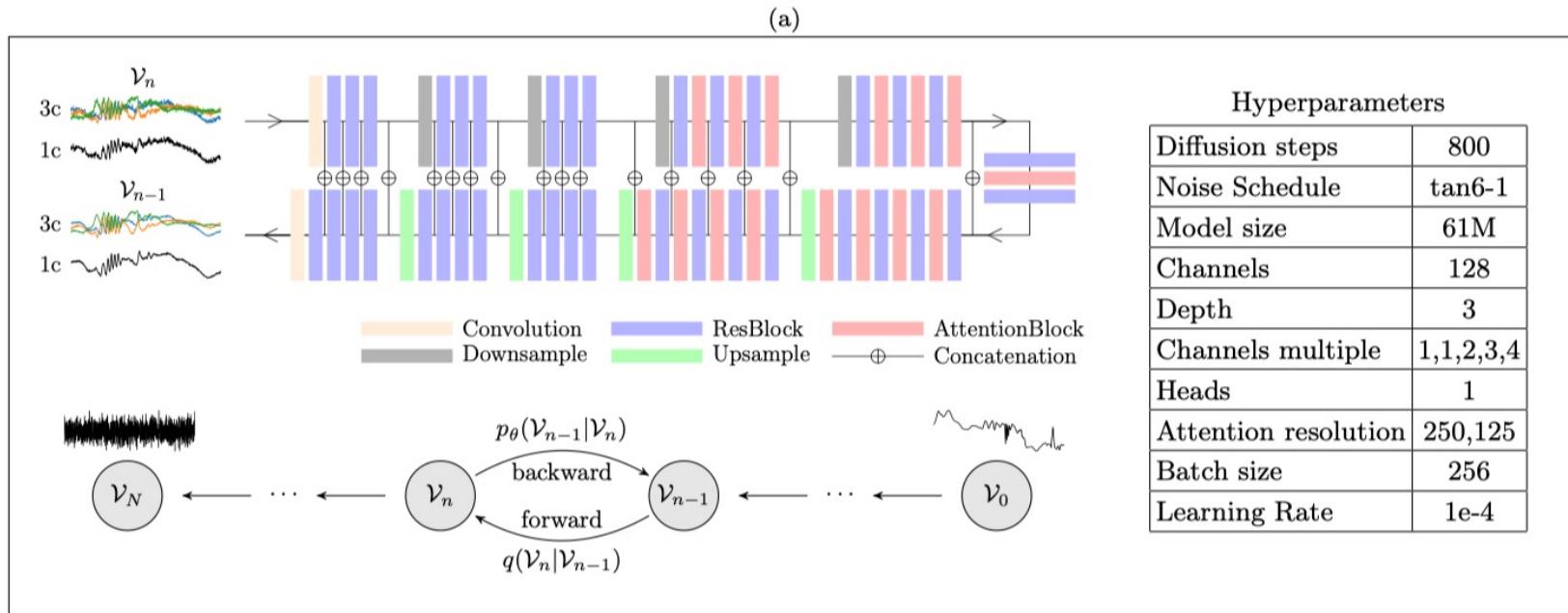
$$S_\tau^{(p)} = \langle (\delta_\tau V_i)^p \rangle$$

$$F_\tau^{(p)} = S_\tau^{(p)} / [S_\tau^{(2)}]^{p/2}.$$



ACCELERATION PDF

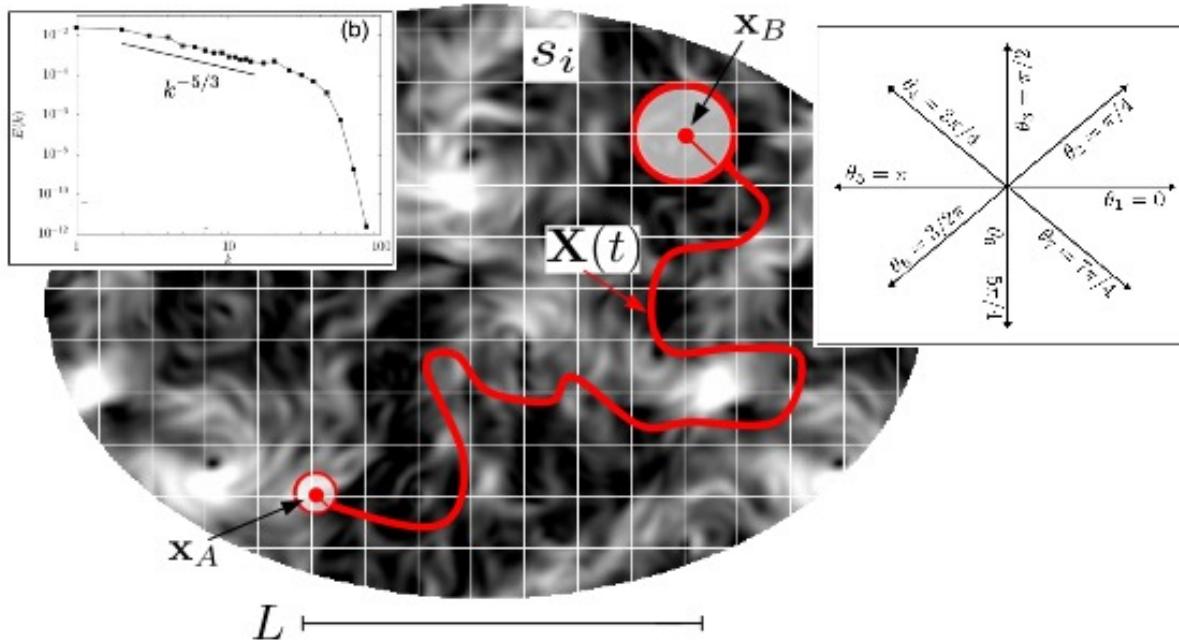




Zermelo's problem: Optimal point-to-point navigation in 2D turbulent flows using Reinforcement Learning

L. Biferale,¹ F. Bonacorso,^{1,2} M. Buzzicotti,¹ P. Clark Di Leoni,^{1,3} and K. Gustavsson⁴

Chaos: An Interdisciplinary Journal of Nonlinear Science
29.10 (2019): 103138.
arXiv preprint:1907.08591



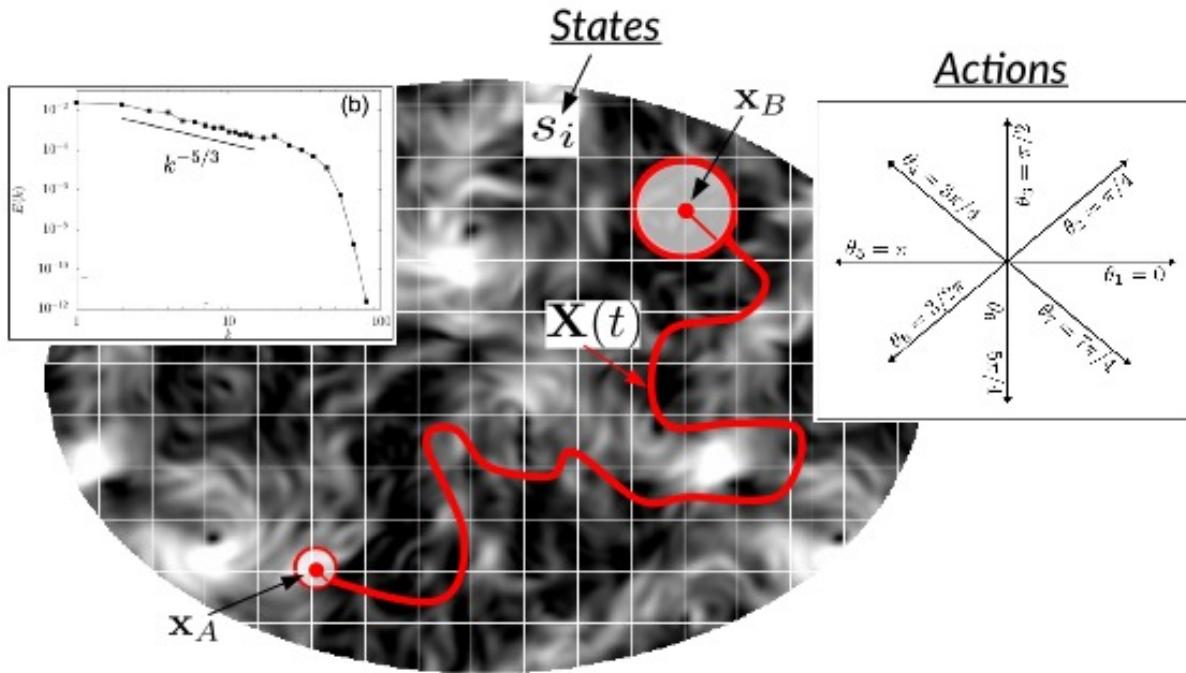
$V_s \rightarrow$ Navigation speed is small compared to the velocity of the underling flow!

E. Zermelo, "Über das naviagationsproblem bei ruhender oder veränderlicher windverteilung," ZAMM-Journal of Applied Mathematics and Mechanics/Zeitschrift für Angewandte Mathematik und Mechanik **11**, 114–124 (1931).
A. E. Bryson and Y. Ho, *Applied optimal control: optimization, estimation and control* (New York: Routledge, 1975).

$$\mathbf{n}(\mathbf{X}_t) = (\cos[\theta_t], \sin[\theta_t]),$$

$$\begin{cases} \dot{\mathbf{X}}_t = \mathbf{u}(\mathbf{X}_t) + \mathbf{U}^{ctrl}(\mathbf{X}_t) \\ \mathbf{U}^{ctrl}(\mathbf{X}_t) = V_s \mathbf{n}(\mathbf{X}_t) \end{cases}$$

Reinforcement Learning; Policy Gradient Methods



Reward

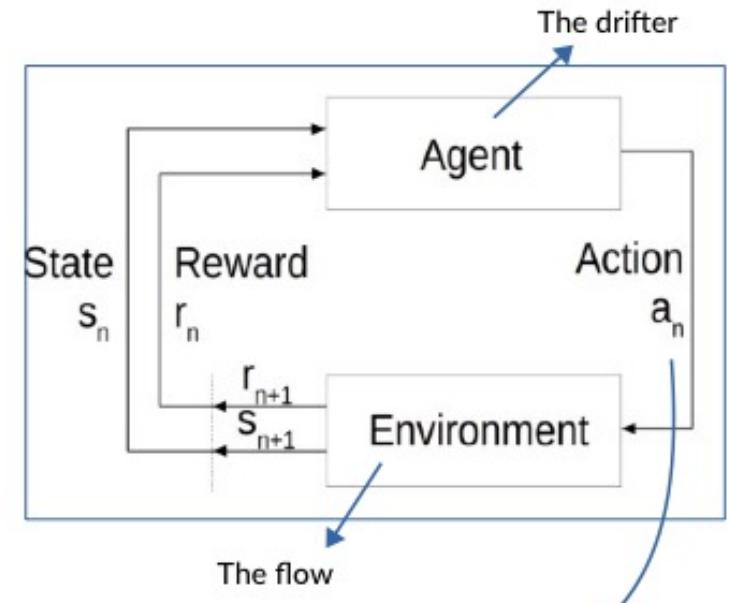
$$r_t = -\Delta t$$

$$r_{tot} = -T_{A \rightarrow B}$$

Actor-Critic algorithm

$$\begin{cases} \mathbf{q}_{t+\Delta t} = \mathbf{q}_t + \alpha_t \beta_t \nabla_{\mathbf{q}} \ln(\pi(a_t | s_t, \mathbf{q}_t)) \\ \mathbf{w}_{t+\Delta t} = \mathbf{w}_t + \alpha'_t \beta_t \nabla_{\mathbf{w}} \hat{v}(s_t, \mathbf{w}_t) \end{cases}$$

$$\beta_t = [\hat{r}_{t+\Delta t} - \hat{v}(s_t, \mathbf{w}_t)] \rightarrow \text{baseline}$$



Parameterized policy:

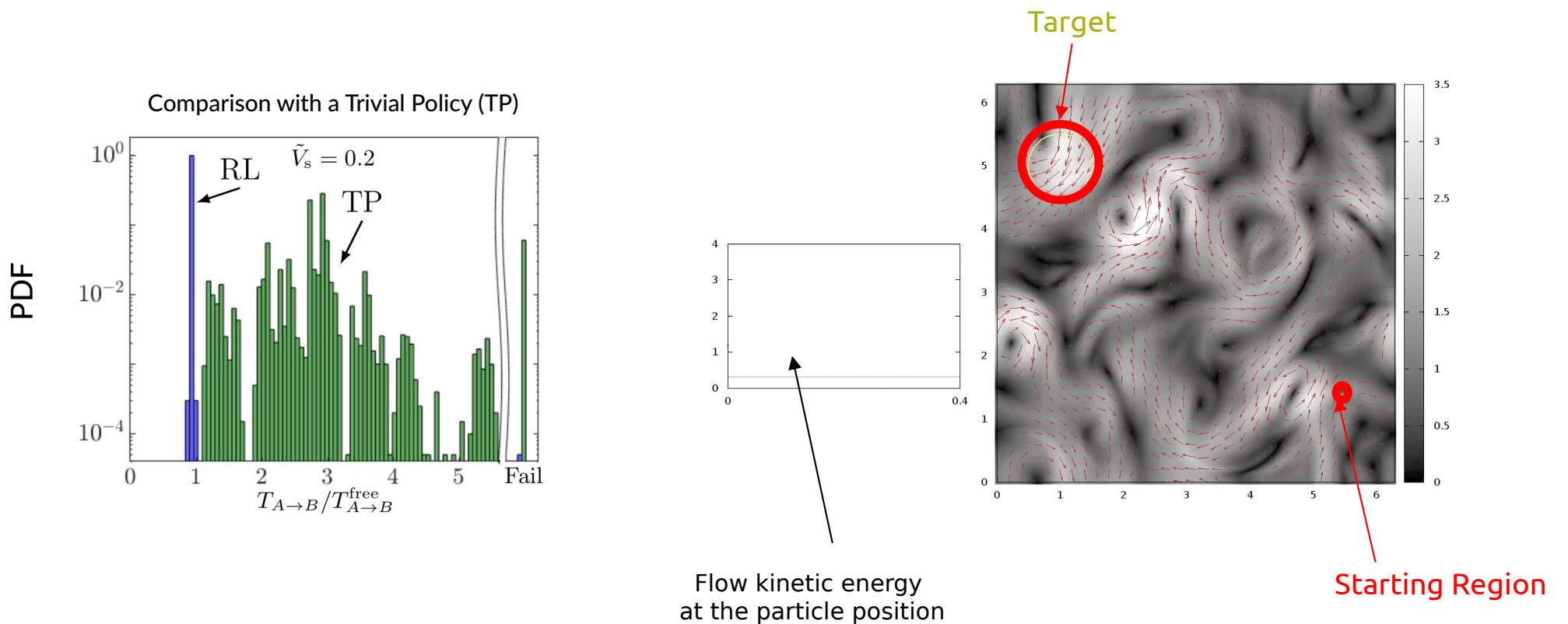
$$\pi(a_j | s_i, \mathbf{q}) = \frac{\exp h(s_i, a_j, \mathbf{q})}{\sum_{k=1}^{N_a} \exp h(s_i, a_k, \mathbf{q})}$$

Parameterized state value function:

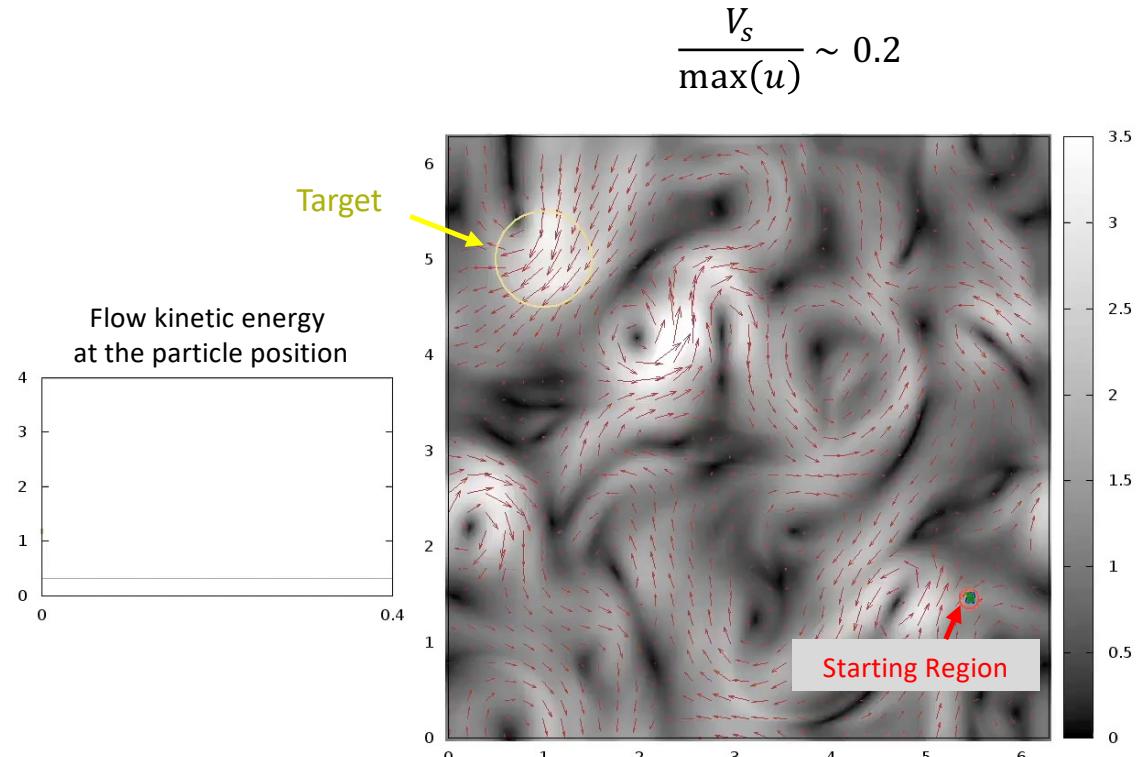
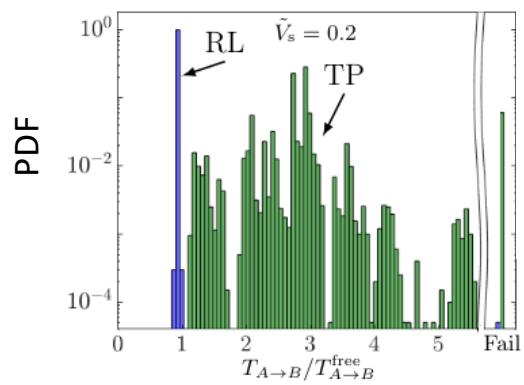
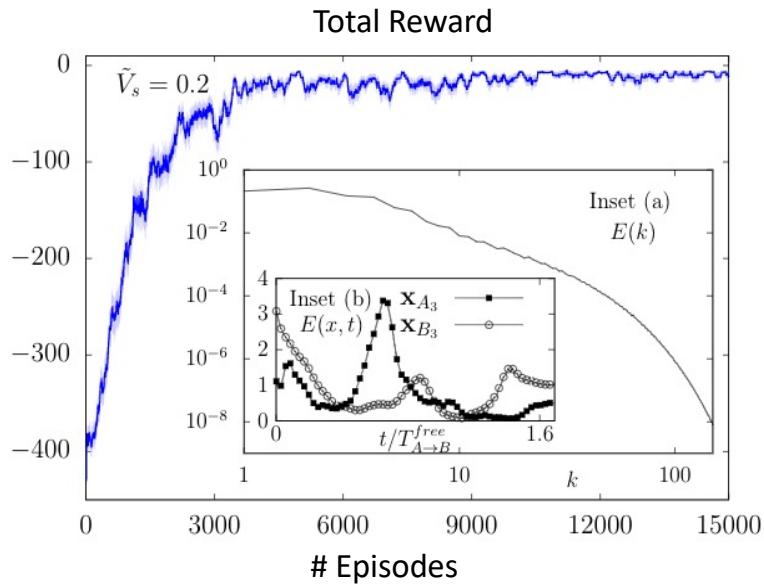
$$\hat{v}(s_i, \mathbf{w}) = \sum_{j=1}^{N_s} w_j \delta_{j,i}$$

TIME-DEPENDENT 2D TURBULENT FLOWS

REINFORCEMENT LEARNING (BLUE) VS TRIVIAL POLICY (GREEN) $\tilde{V}_s = 0.2$



Time-Dependent 2D Turbulent Flow



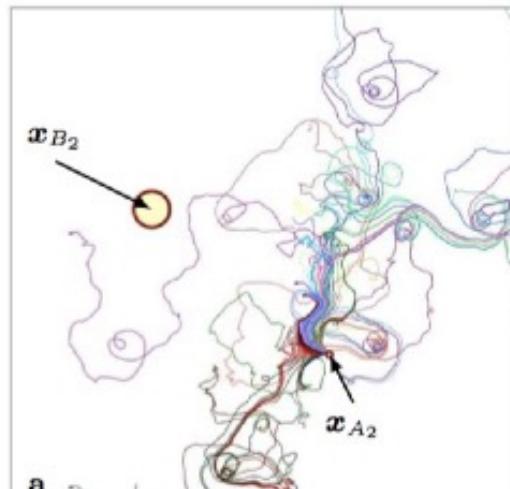
Reinforcement Learning (blue)
vs
Trivial Policy (green)

COMPARISON RL VS OPTIMAL NAVIGATION

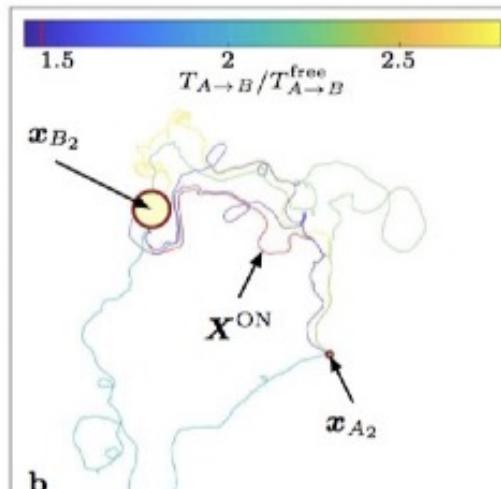
A. E. Bryson and Y. Ho, Applied optimal control: optimization, estimation and control (New York: Routledge, 1975).

Time independent flow

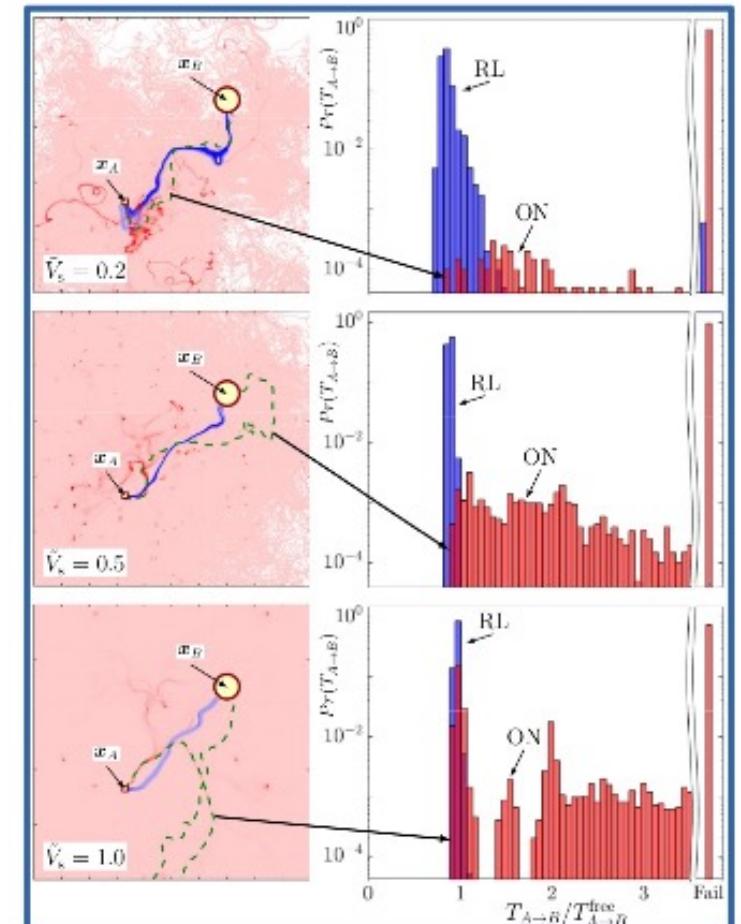
$$\begin{cases} \dot{\mathbf{X}}_t = \mathbf{u}(\mathbf{X}_t) + \mathbf{U}^{ctrl}(\mathbf{X}_t) & \mathbf{n}(\mathbf{X}_t) = (\cos[\theta_t], \sin[\theta_t]), \\ \mathbf{U}^{ctrl}(\mathbf{X}_t) = V_s \mathbf{n}(\mathbf{X}_t) & A_{ij} = \partial_i u_j \\ \dot{\theta}_t = A_{21} \sin^2 \theta_t - A_{12} \cos^2 \theta_t + (A_{11} - A_{22}) \cos \theta_t \sin \theta_t, \end{cases}$$

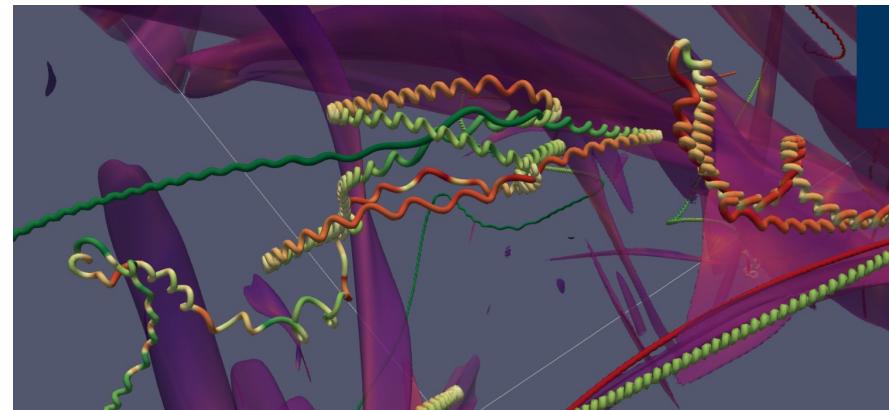
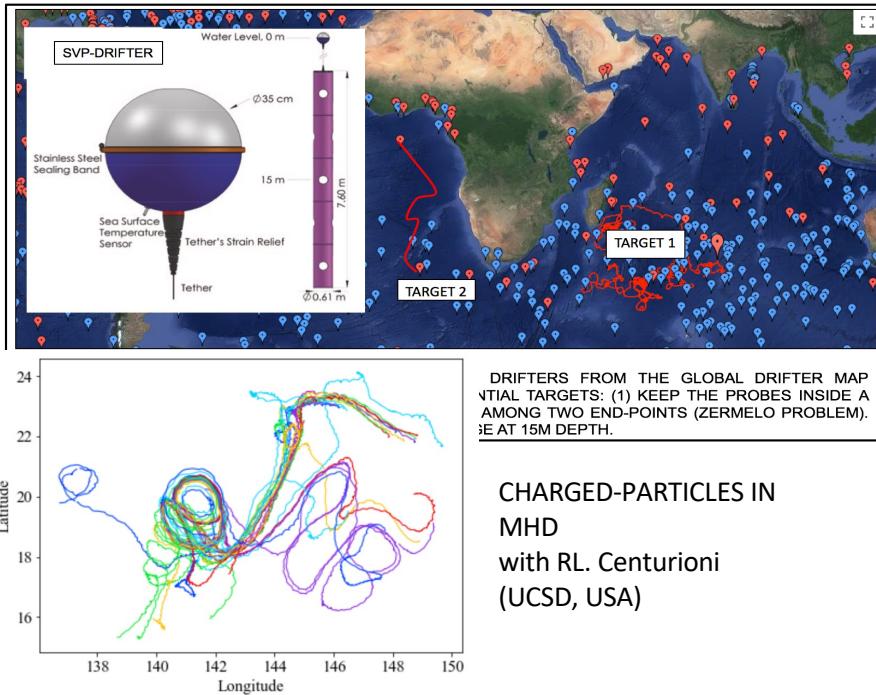


1000 trials (all failures)



100k trials (10 successes)





-WHAT-IF QUESTIONS: EXPLICABILITY OF THE GENERATED DATA, FEATURES RANKINGS, PHYSICS DISCOVERY

Wavelet Score-Based Generative Modeling

<p>Florentin Guth Computer Science Department, ENS, CNRS, PSL University</p> <p>Valentin De Bortoli Computer Science Department, ENS, CNRS, PSL University</p>	<p>Simon Coste Computer Science Department, ENS, CNRS, PSL University</p> <p>Stéphane Mallat Collège de France, Paris, France Flatiron Institute, New York, USA</p>
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[arxive 2208.05003](https://arxiv.org/abs/2208.05003)

WE HAVE NEW TOOLS IN THE BOX!

OPEN ISSUES:

0. EXPLENABILITY. VERY FAR, AT THE MOMENT. COMPUTO ERGO SUM?
1. PROOF-OF-CONCEPTS STAGE. VERY FEW NEW DISCOVERIES/FAR FROM FRONTIER RESEARCH
2. GENERALIZABILITY/ROBUSTNESS. CHANGE ANYTHING, CHANGES EVERYTHING?
3. SCALABILITY. VS NETWORK ARCHITECTURE AND VS CONTROL PHYSICAL PARAMETERS
4. UNCERTAINTY QUANTIFICATION/TRUSTABILITY

WHAT WE MISS:

1. COMMUNITY EFFORT TO:
 - (A) DEPLOY AND MAINTAIN HIGH QUALITY AND HIGH QUANTITY DATA (OPEN)
 - (B) IDENTIFY BENCHMARKS, VALIDATION STEPS, BASELINES
 - (C) IDENTIFY GRAND CHALLENGES



Guide for users

TURB-ROT. A LARGE DATABASE OF 3D AND 2D SNAPSHOTTS FROM TURBULENT ROTATING FLOWS

A PREPRINT

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P. Clark Di Losi
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Johns Hopkins University, Baltimore, USA.
pato@jhu.edu

Search for datasets

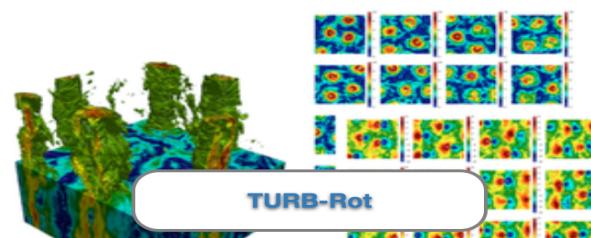


1

Datasets

TURB-Rot

A large database of 3d and 2d snapshots from turbulent rotating



2

Organizations

web_admin

web_admin group

1

member

THANK YOU !

If you are interested to /working in AI
applications to fluid dynamics
participate to the questionnaire-->

The idea is to survey some information on the subject from
the community and present / discuss the results in a
JFM Perspective paper

with L. Biferale & M. Buzzicotti

LINK TO THE QUESTIONNAIRE

<https://forms.gle/j1ubGQQ8V2S9UwjP8>



QR CODE TO REACH THE QUESTIONNAIRE